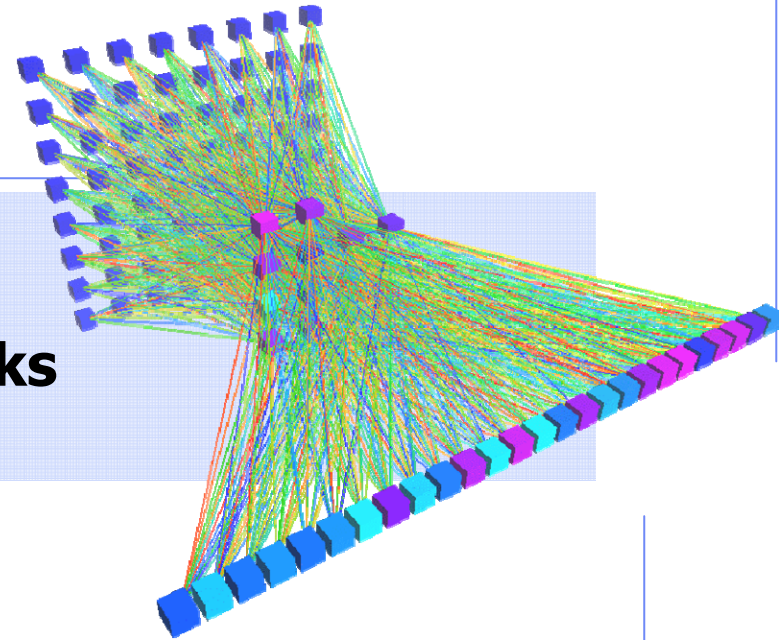


Forecasting with Artificial Neural Networks



EVIC 2005 Tutorial
Santiago de Chile, 15 December 2005

→ slides on www.neural-forecasting.com



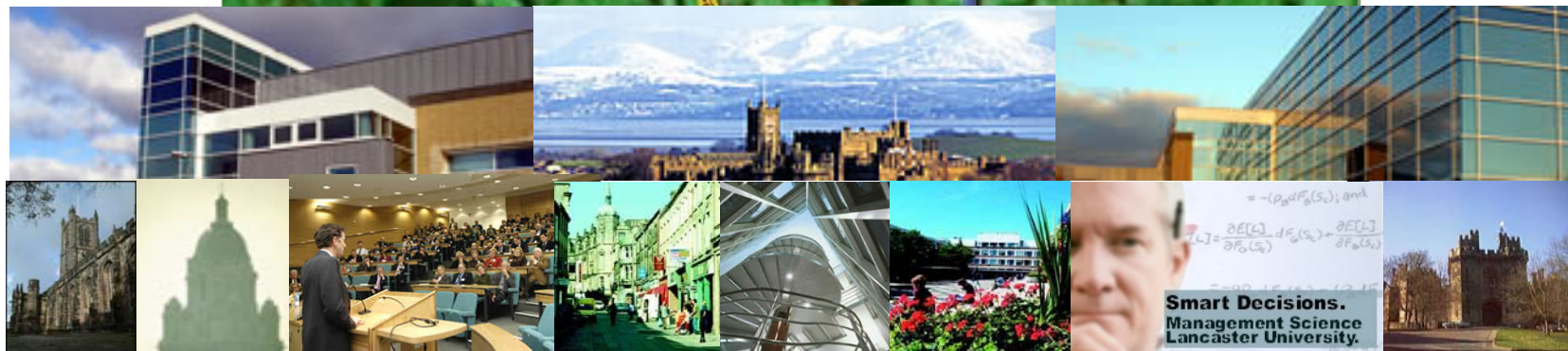
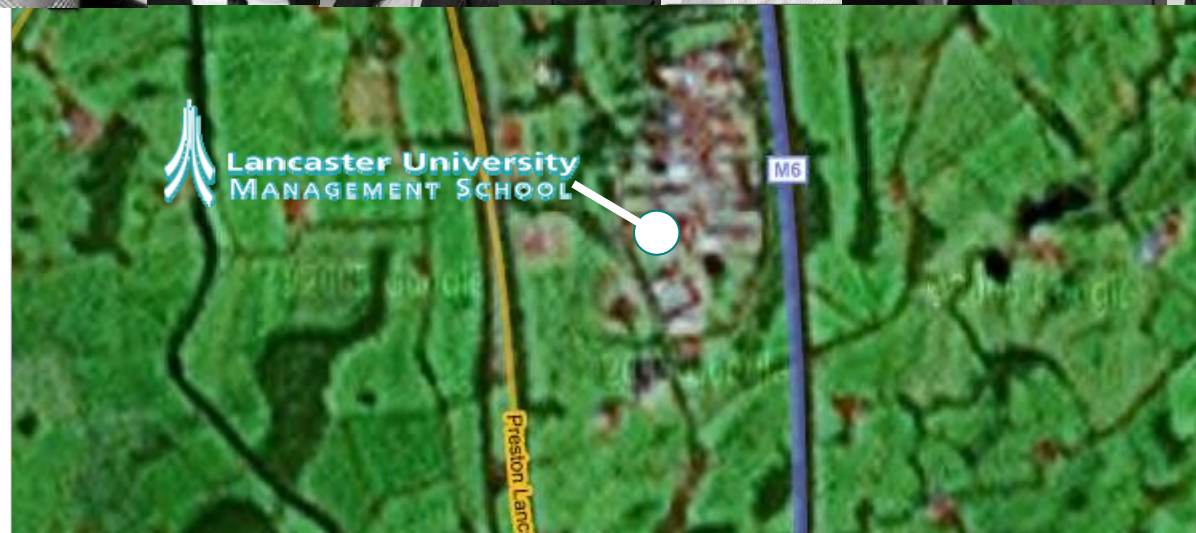
Sven F. Crone

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Department of Management Science
Lancaster University Management School
email: s.crone@neural-forecasting.com

LANCASTER
UNIVERSITY



Lancaster University Management School?



What you can expect from this session ...

- Simple back propagation algorithm [Rumelhart et al. 1982]

~~$$E_p = C(t_{pj}, o_{pj}) \quad o_{pj} = f_j(\text{net}_{pj}) \quad \Delta_p w_{ji} \propto -\frac{\partial C(t_{pj}, o_{pj})}{\partial w_{ji}}$$

$$\frac{\partial C(t_{pj}, o_{pj})}{\partial w_{ji}} = \frac{\partial C(t_{pj}, o_{pj})}{\partial \text{net}_{pj}} \frac{\partial \text{net}_{pj}}{\partial w_{ji}}$$

$$\delta_{pj} = -\frac{\partial C(t_{pj}, o_{pj})}{\partial \text{net}_{pj}}$$

$$\delta_{pj} = -\frac{\partial C(t_{pj}, o_{pj})}{\partial \text{net}_{pj}} = \frac{\partial C(t_{pj}, o_{pj})}{\partial o_{pj}} \frac{\partial o_{pj}}{\partial \text{net}_{pj}}$$

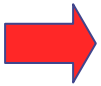
$$\frac{\partial o_{pj}}{\partial \text{net}_{pj}} = f'_j(\text{net}_{pj})$$

$$\delta_{pj} = \frac{\partial C(t_{pj}, o_{pj})}{\partial o_{pj}} f'_j(\text{net}_{pj})$$

$$\sum_k \frac{\partial C(t_{pj}, o_{pj})}{\partial \text{net}_{pk}} \frac{\partial \text{net}_{pk}}{\partial o_{pj}} = \sum_k \frac{\partial C(t_{pj}, o_{pj})}{\partial \text{net}_{pk}} \frac{\partial \sum_i w_{ki} o_{pi}}{\partial o_{pj}}$$

$$= \sum_k \frac{\partial C(t_{pj}, o_{pj})}{\partial \text{net}_{pk}} w_{kj} = -\sum_k \delta_{pk} w_{kj}$$

$$\delta_{pj} = f'_j(\text{net}_{pj}) \sum_k \delta_{pk} w_{kj}$$~~



$$\delta_{pj} = \begin{cases} \frac{\partial C(t_{pj}, o_{pj})}{\partial o_{pj}} f'_j(\text{net}_{pj}) & \text{if unit } j \text{ is in the output layer} \\ f'_j(\text{net}_{pj}) \sum_k \delta_{pk} w_{pk} & \text{if unit } j \text{ is in a hidden layer} \end{cases}$$

→ „How to ...“ on Neural Network Forecasting with limited maths!

→ **CD-Start-Up Kit for Neural Net Forecasting**

- 20+ software simulators
- datasets
- literature & faq

→ slides, data & additional info on www.neural-forecasting.com

Agenda

Forecasting with Artificial Neural Networks

1. Forecasting?
2. Neural Networks?
3. Forecasting with Neural Networks ...
4. How to write a good Neural Network forecasting paper!

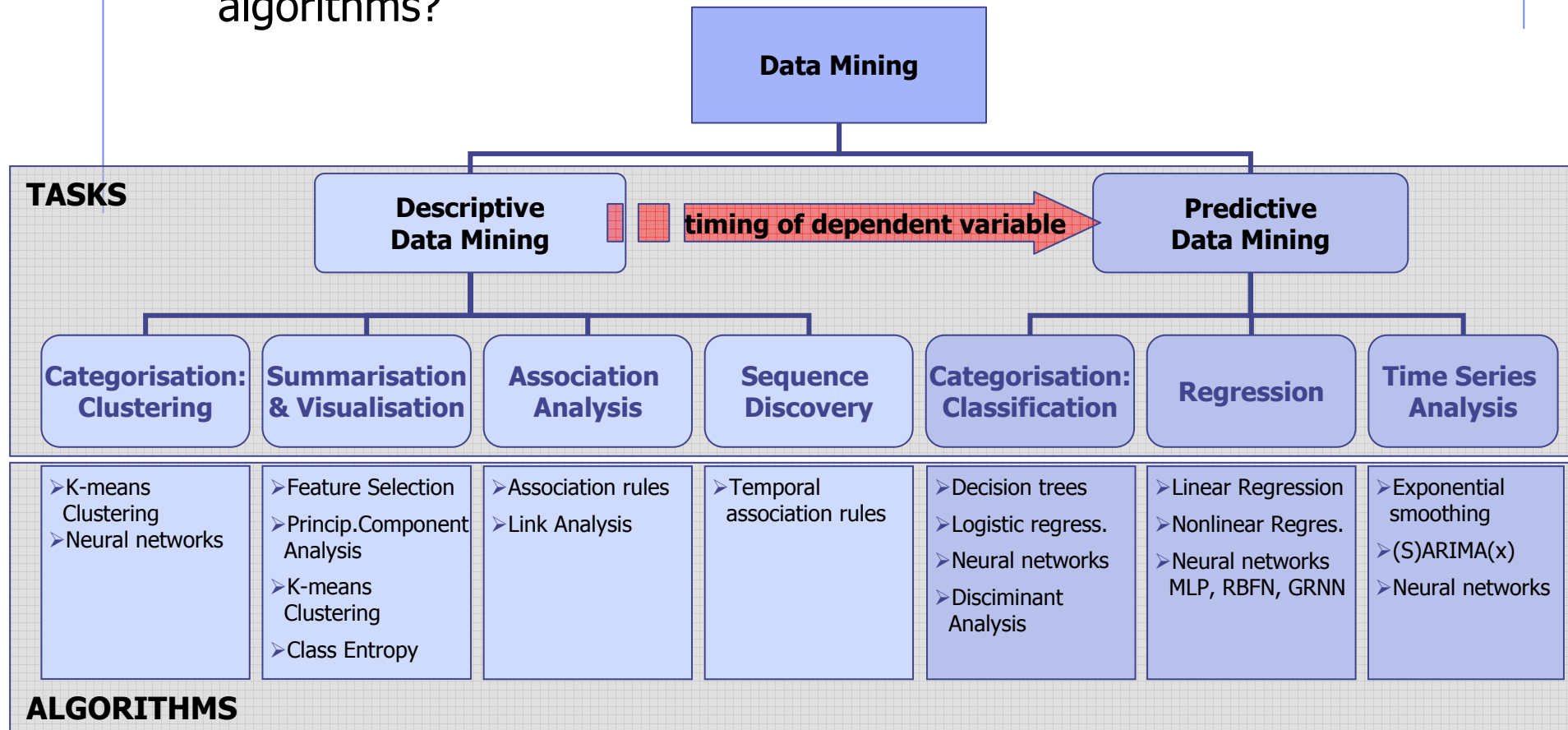
Agenda

Forecasting with Artificial Neural Networks





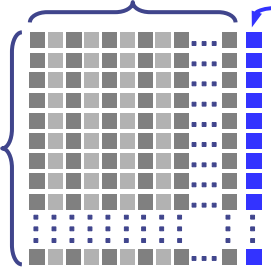


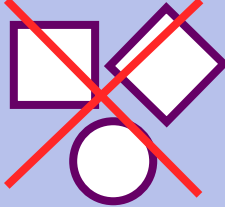
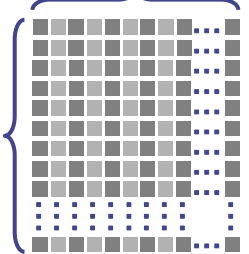
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 1. Forecasting as predictive Regression
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Forecasting or Prediction?

- Data Mining:** „ Application of data analysis algorithms & discovery algorithms that extract patterns out of the data” → algorithms?



Forecasting or Classification

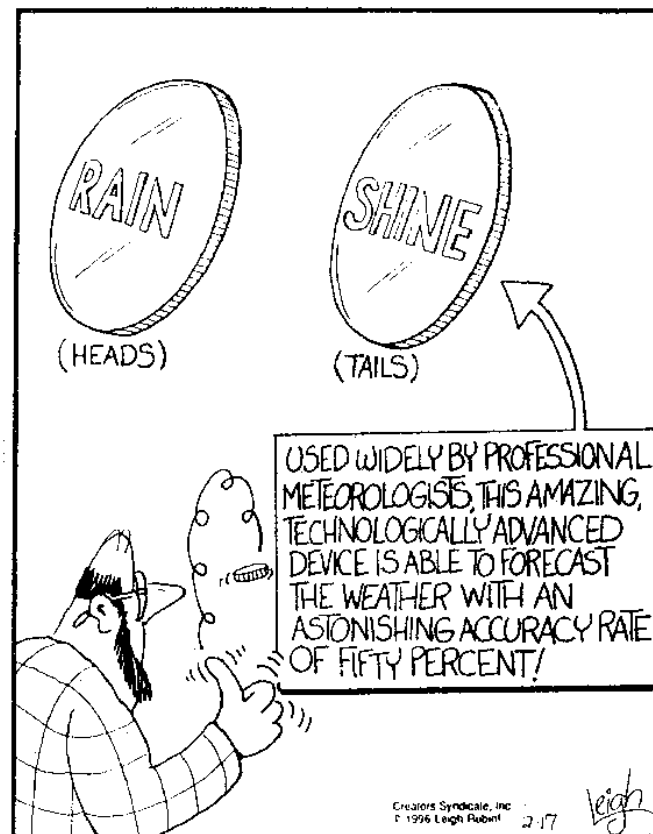
| Independent \ dependent | Metric scale  | Ordinal scale  | Nominal scale  | |
|--|---|--|--|--|
| Metric sale  | <ul style="list-style-type: none"> Regression Time Series Analysis | DOWNSCALE → Analysis of Variance | | Supervised learning Inputs Target  |
| Ordinal scale  | DOWNSCALE ↓ | DOWNSCALE → | DOWNSCALE ↓ | |
| Nominal scale  | Classification | DOWNSCALE → | Contingency Analysis | |
| NONE  | <ul style="list-style-type: none"> Principal Component Analysis | | <ul style="list-style-type: none"> Clustering | Unsupervised learning Inputs  |

- Simplification from Regression ("How much") → Classification ("Will event occur")
- FORECASTING = PREDICTIVE modelling (dependent variable is in future)
- FORECASTING = REGRESSION modelling (dependent variable is of metric scale)

Forecasting or Classification?


- What the experts say ...

RUBES by LEIGH RUBIN



International Conference on Data Mining

- You are welcome to contribute ... www.dmin-2006.com !!!


DMIN'06
THE 2006 INTERNATIONAL
CONFERENCE ON DATA MINING
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Call for Papers

The 2006 International Conference on Data Mining
Part of the 2006 World Congress in Computer Sciences
June 26-29, 2006
Las Vegas, Nevada, USA

Welcome to The 2006 International Conference on Data Mining. DMIN'06 is an international conference held simultaneously with 28 other joint conferences as part of WORLDCOMP'06, The 2006 World Congress in Computer Science, Computer Engineering, and Applied Computing. WORLDCOMP'06 is the largest annual gathering of researchers in computer science, computer engineering and applied computing. Each of the joint conferences in WORLDCOMP is a premier conference for presentation of advances in their respective fields (for the complete list of joint conferences [click here](#)). The last set of conferences (DMIN'05 and affiliated events) had research contributions from 76 countries and had attracted over 1,500 participants. It is anticipated to have over 2,000 participants for the 2006 event.

You are invited to submit a draft paper of about 5-8 pages via our [online draft paper submission system](#) (for more information see the [submission](#) information). All accepted papers will be published in the respective conference proceedings. The names of technical session/workshop organizers/chairs will appear on the cover of the proceedings/books as Associate Editors. Topics of interest include, but are not limited to (see also [topics](#)):


- Data Mining Methods & Algorithms
- Data Mining & Knowledge Discovery Process
- Data Mining Applications
- Data Mining Tools
- Data Visualisation
- Data Warehousing
- Data reduction

We welcome all contributions through theoretical research papers and industrial reports and case studies on applications in form of regular research papers of 7

Important Dates

| |
|---|
| December 29, 2005 |
| Deadline for proposals to organize / chair sessions - please contact us ASAP. |
| February 20, 2006 |
| Draft paper Submissions due |
| March 20, 2006 |
| Notification of acceptance |
| April 20, 2006 |
| Camera-Ready papers & Pre-registration due |
| June 26-29, 2006 |
| The 2006 International Conference on Data Mining (DMIN'06) & The 2006 World Congress in Computer Science, Computer Engineering, and Applied Computing (WORLDCOMP'06 - 28 joint conferences) |

Subscribe Newsletter



$$Y_i = c + \phi_1 Y_{i-1} + \phi_2 Y_{i-2} + \dots + \phi_p Y_{i-p} + \epsilon_i$$

$$-\theta_1 \epsilon_{i-1} - \theta_2 \epsilon_{i-2} - \dots - \theta_q \epsilon_{i-q}$$

Contact

Subscribe

Contact

Conference Chair:
Sven F. Crone

eMail sven.crone@tdm.dmin-2006.com

Conference & Program Co-chairs:

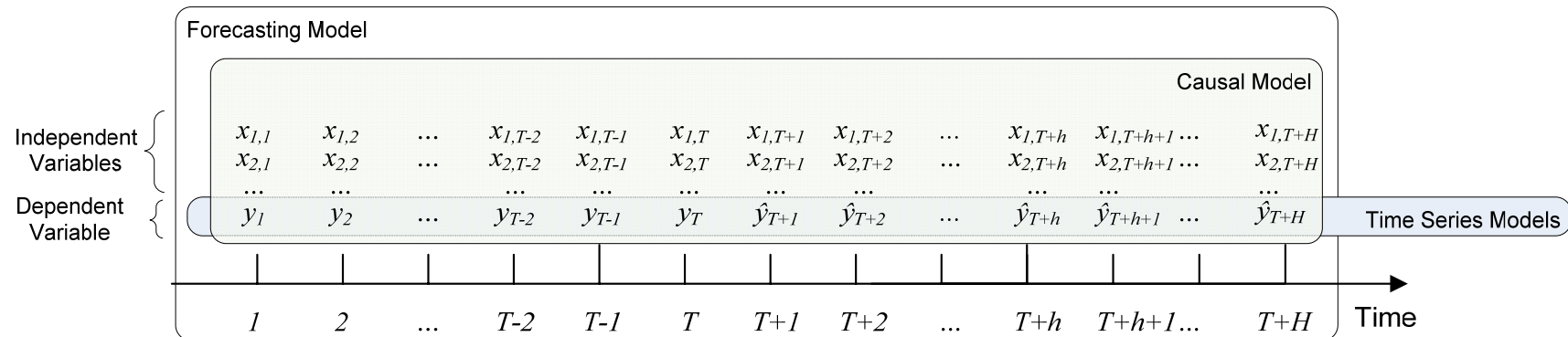
Agenda

Forecasting with Artificial Neural Networks

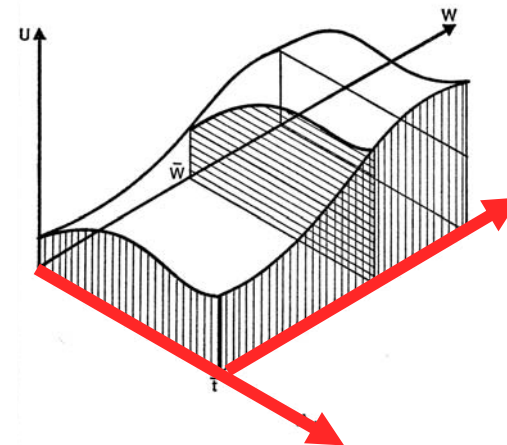
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Forecasting Models

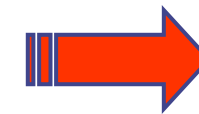
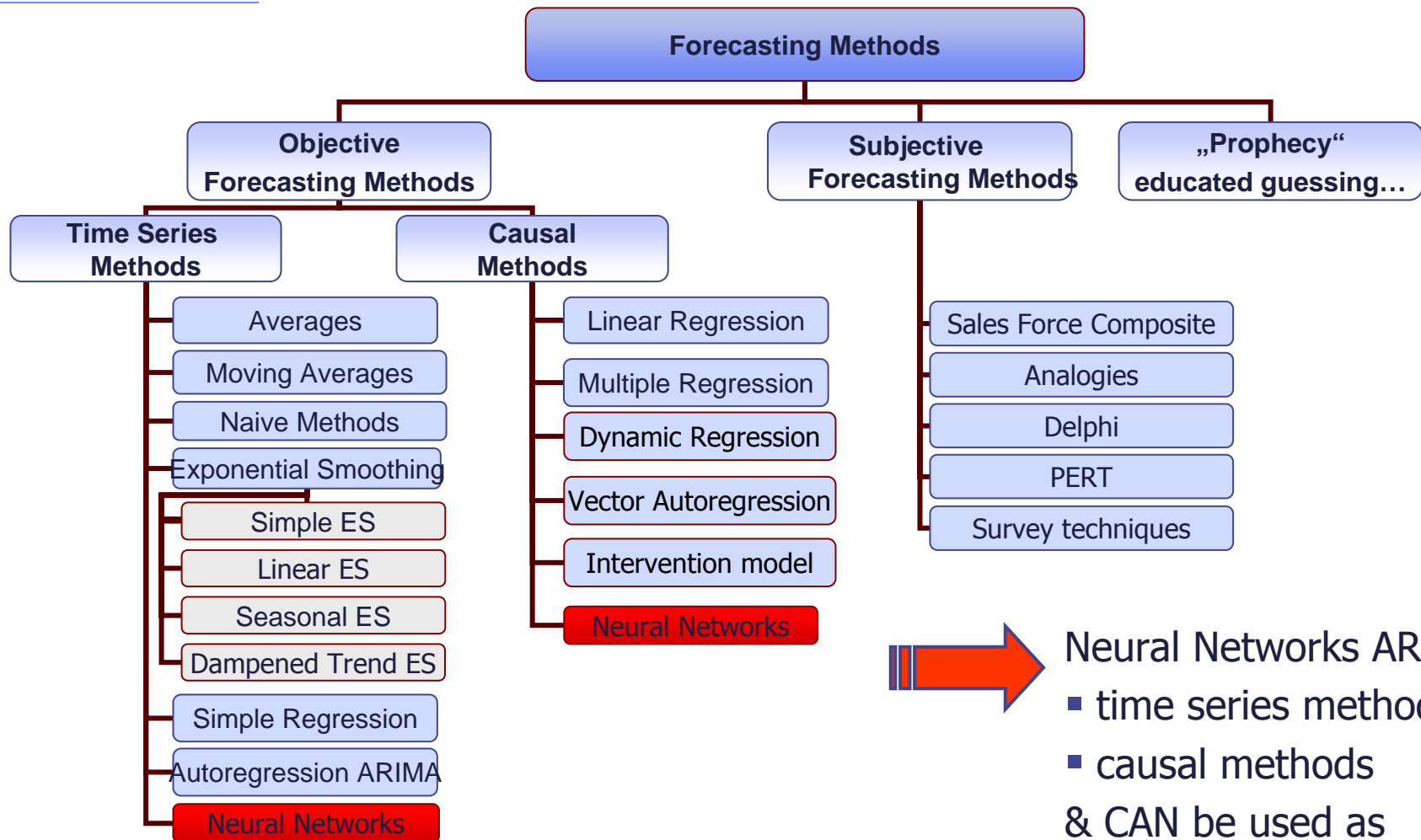
- Time series analysis vs. causal modelling



- Time series prediction (Univariate)
 - Assumes that data generating process that creates patterns can be explained only from previous observations of dependent variable
- Causal prediction (Multivariate)
 - Data generating process can be explained by interaction of causal (cause-and-effect) independent variables



Classification of Forecasting Methods



Neural Networks ARE

- time series methods
- causal methods

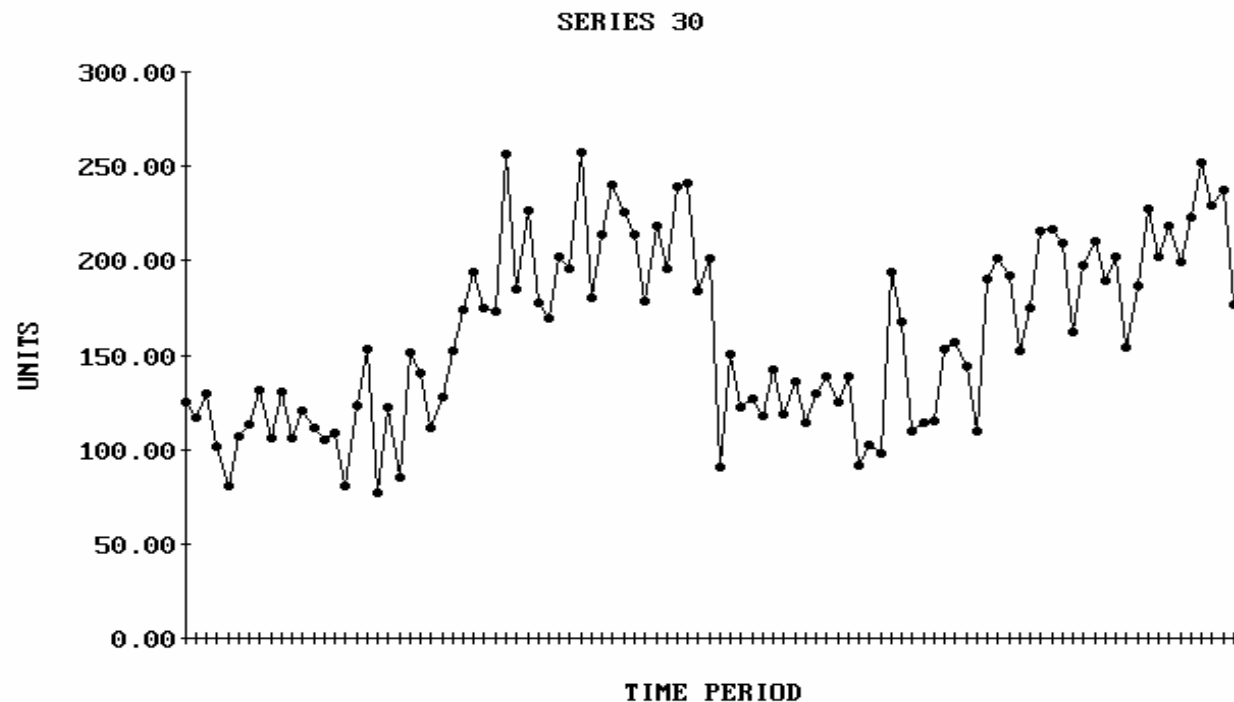
& CAN be used as

- Averages & ES
- Regression ...

Demand Planning Practice
Objektive Methoden + Subjektive correction

Time Series Definition

- Definition
 - Time Series is a series of timely ordered, comparable observations y_t recorded in equidistant time intervals
- Notation
 - Y_t represents the t th period observation, $t=1,2 \dots n$



Concept of Time Series

- An observed measurement is made up of a
 - **systematic part** and a
 - **random part**

- Approach
 - Unfortunately we cannot observe either of these !!!
 - Forecasting methods try to isolate the systematic part
 - Forecasts are based on the systematic part
 - The random part determines the distribution shape

- Assumption
 - Data observed over time is comparable
 - The time periods are of identical lengths (check!)
 - The units they are measured in change (check!)
 - The definitions of what is being measured remain unchanged (check!)
 - They are correctly measured (check!)
 - data errors arise from sampling, from bias in the instruments or the responses, from transcription.

Objective Forecasting Methods – Time Series

Methods of Time Series Analysis / Forecasting

- Class of objective Methods
- based on analysis of past observations of dependent variable alone

■ Assumption

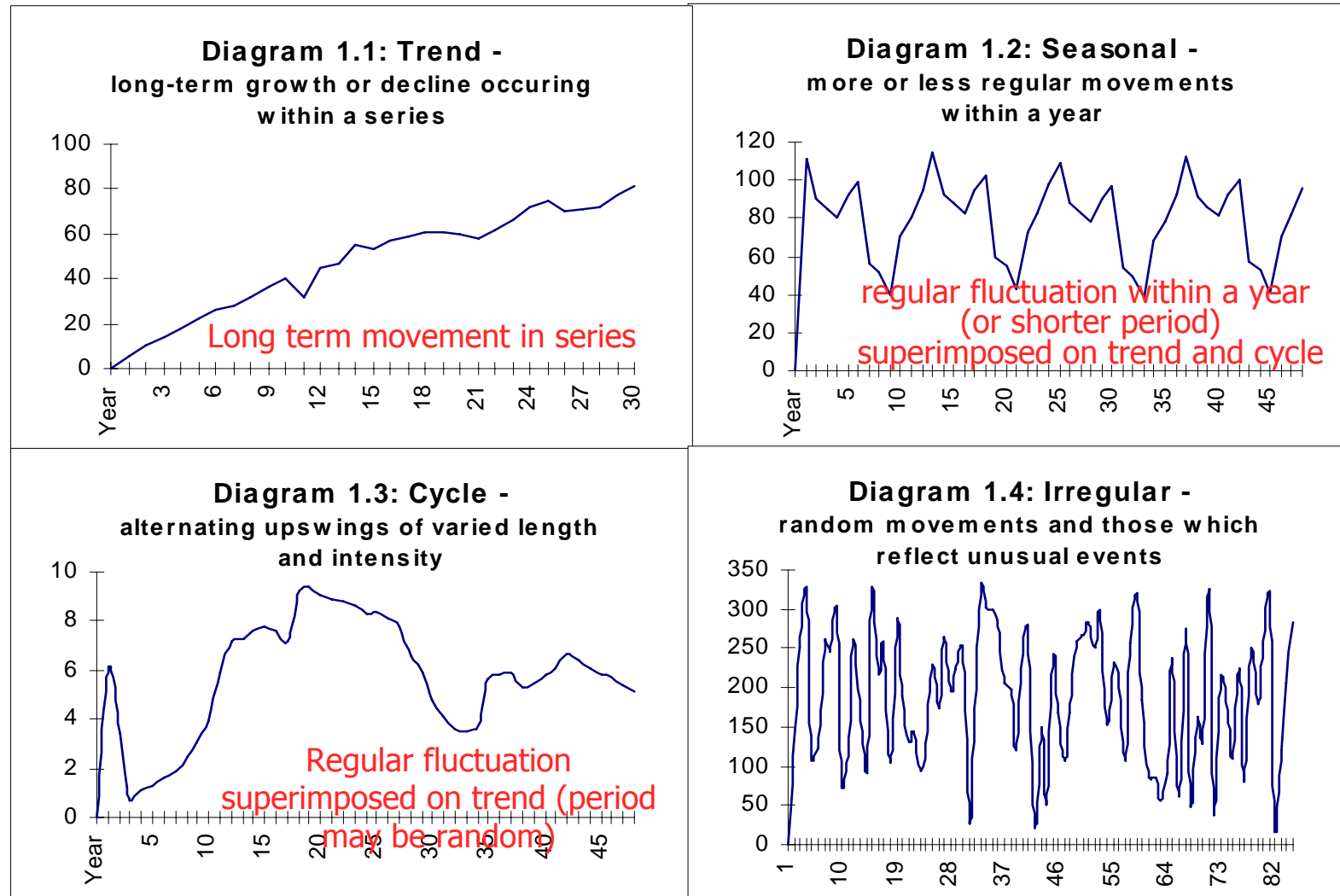
- there exists a cause-effect relationship, that keeps repeating itself with the yearly calendar
- Cause-effect relationship may be treated as a BLACK BOX
- TIME-STABILITY-HYPOTHESIS ASSUMES NO CHANGE:
→ Causal relationship remains intact indefinitely into the future!
- the time series can be explained & predicted solely from previous observations of the series

→ Time Series Methods consider only past patterns of same variable

→ Future events (no occurrence in past) are explicitly NOT considered!

→ external EVENTS relevant to the forecast must be corrected
MANUALLY

Simple Time Series Patterns



Regular Components of Time Series

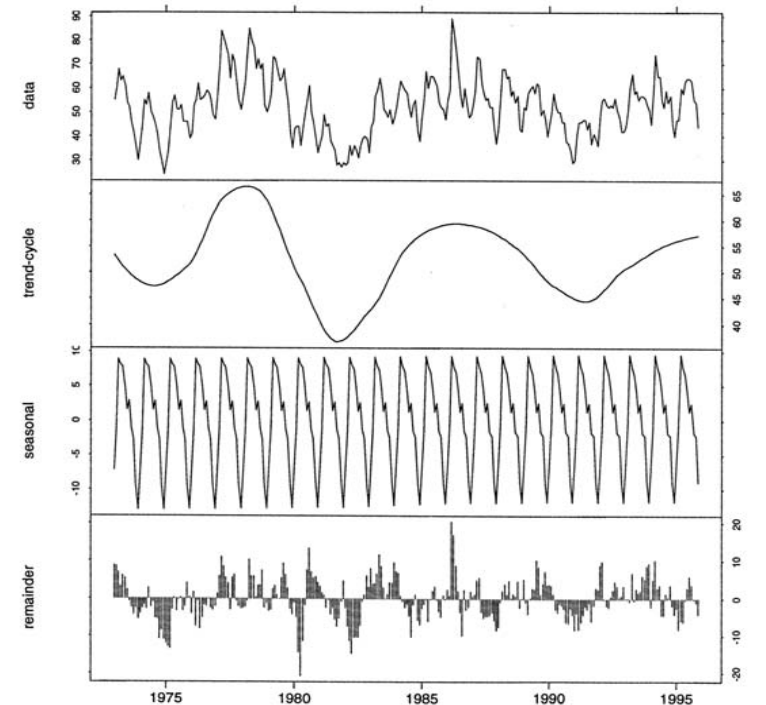
A Time Series consists of superimposed components / patterns:

➤ Signal

- level 'L'
- trend 'T'
- seasonality 'S'

➤ Noise

- irregular, error 'e'



$$Y = L + S + T + E$$

Sales = LEVEL + SEASONALITY + TREND + RANDOM ERROR

$$Y = L * S * T * E$$

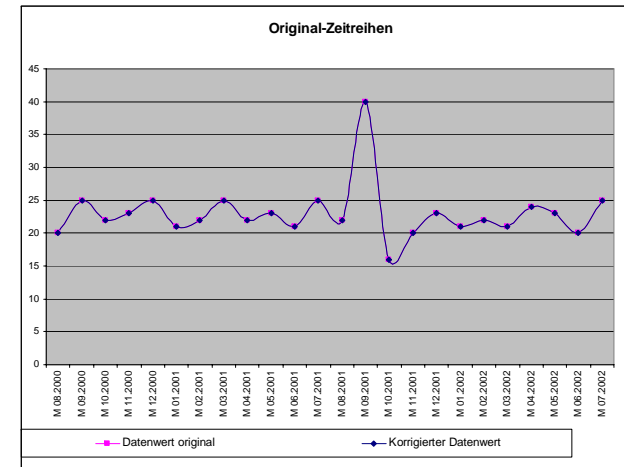
Irregular Components of Time Series

Structural changes in systematic data

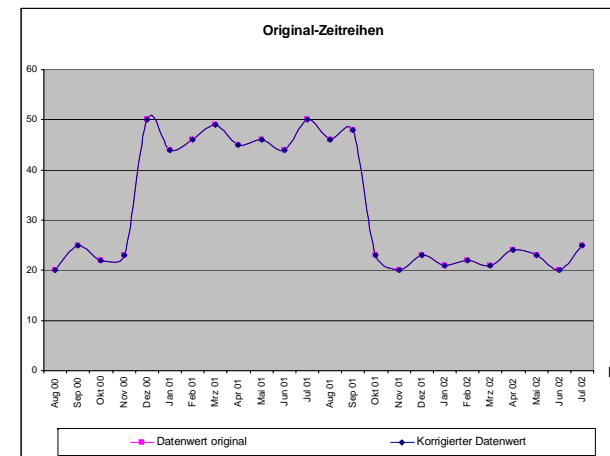
- **PULSE**
 - one time occurrence
 - on top of systematic stationary / trended / seasonal development

- **LEVEL SHIFT**
 - one time / multiple time shifts
 - on top of systematic stationary / trended / seasonal etc. development

- **STRUCTURAL BREAKS**
 - Trend changes (slope, direction)
 - Seasonal pattern changes & shifts



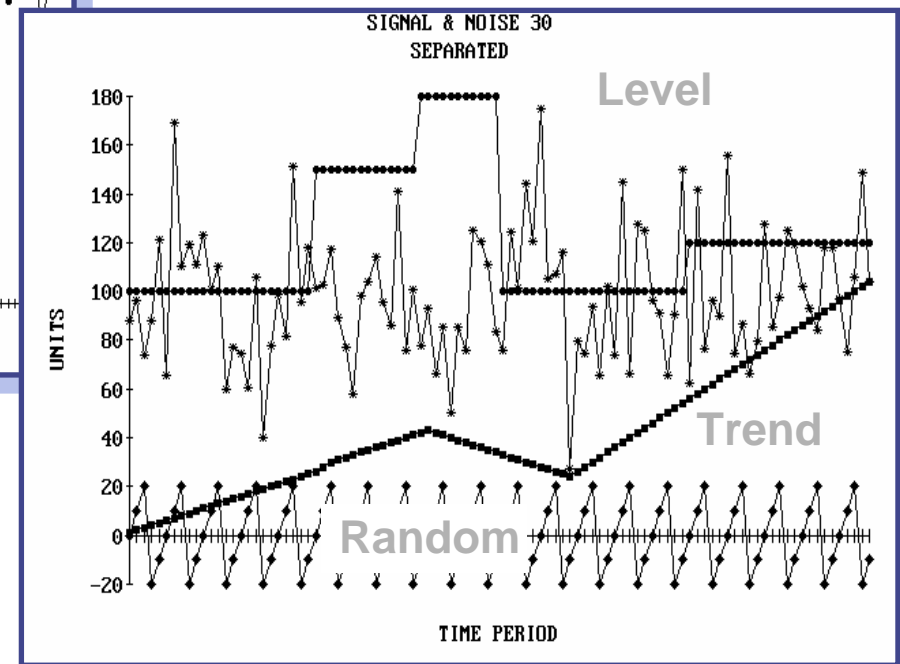
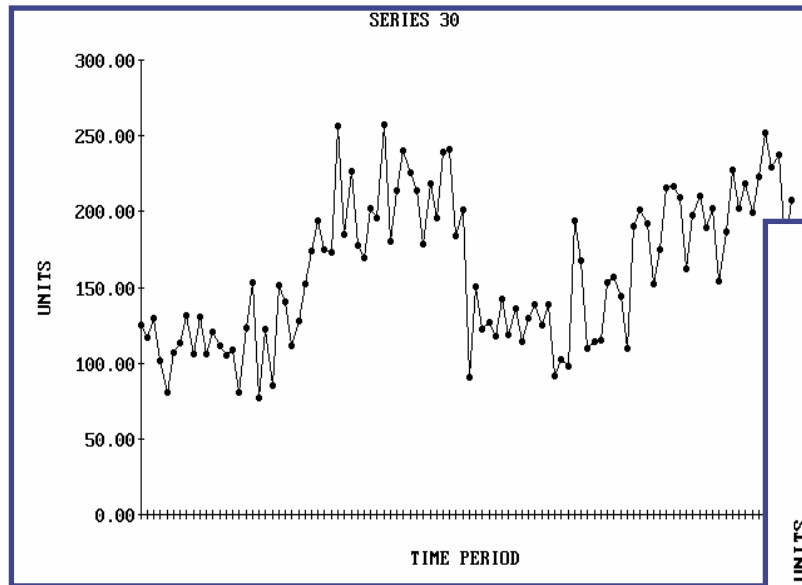
STATIONARY time series with PULSE



STATIONARY time series with level shift

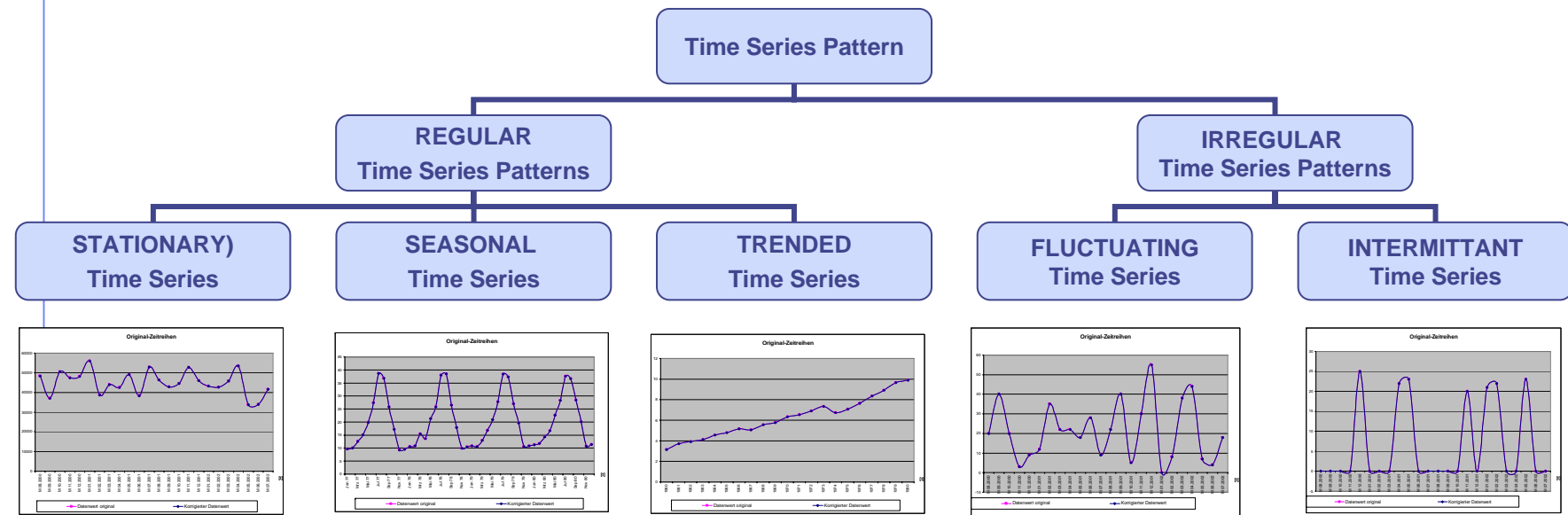
Components of Time Series

■ Time Series



- Time Series → decomposed into Components

Time Series Patterns



$Y_t = f(E_t)$
time series is influenced by level & random fluctuations

$Y_t = f(S_t, E_t)$
time series is influenced by level, season and random fluctuations

$Y_t = f(T_t, E_t)$
time series is influenced by trend from level and random fluctuations

time series fluctuates very strongly around level (mean deviation > ca. 50% around mean)

Number of periods with zero sales is high (ca. 30%-40%)

Combination of individual Components

$$Y_t = f(S_t, T_t, E_t)$$

+ PULSES!

+ LEVEL SHIFTS!

+ STRUCTURAL BREAKS!

Components of complex Time Series

Sales or observation of time series at point t

→ Y_t

consists of a combination of

= $f()$

Base Level + Seasonal Component

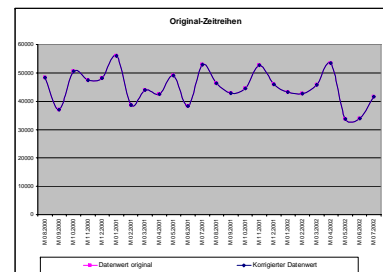
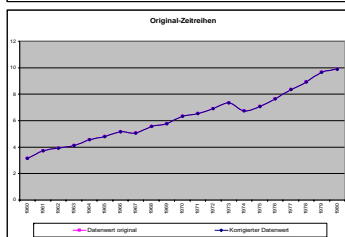
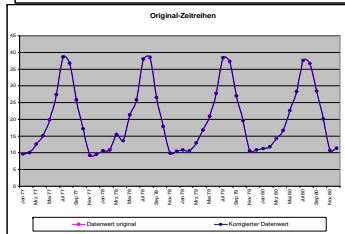
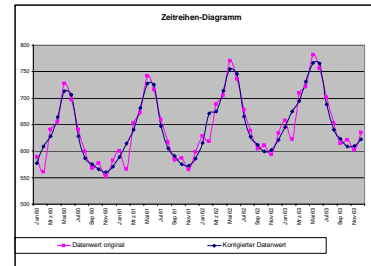
→ S_t ,

Trend-Component

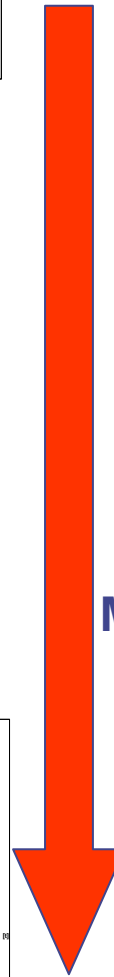
→ T_t ,

Irregular or random Error-Component

→ E_t



Different possibilities to combine components



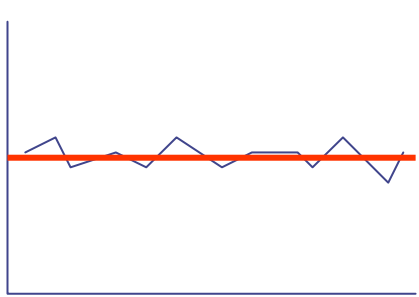
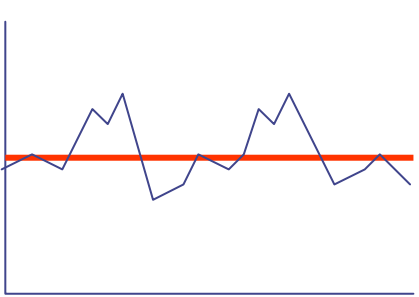
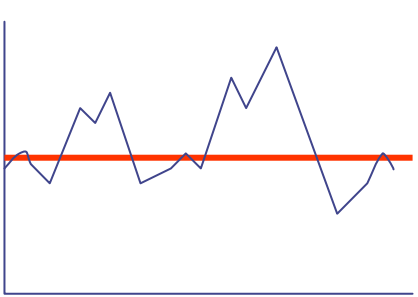
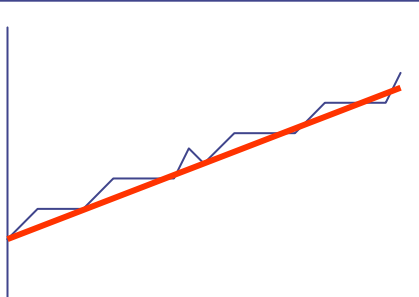
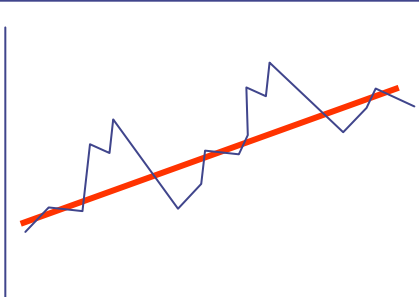
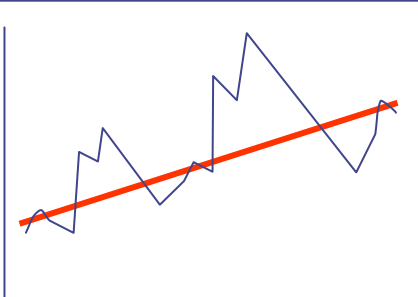
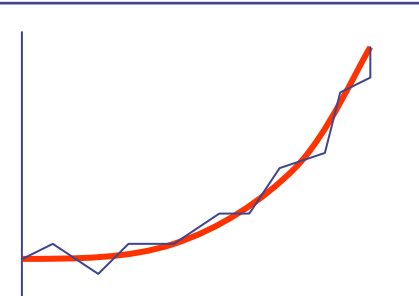
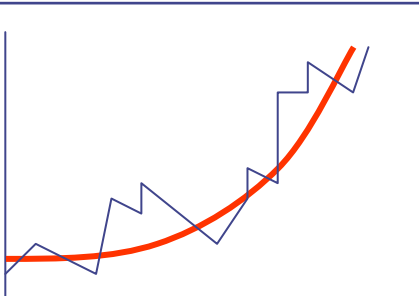
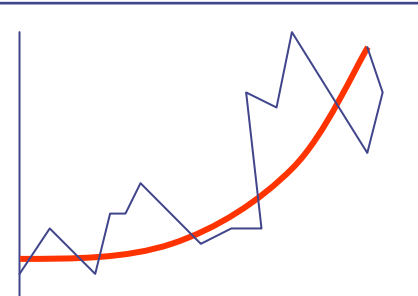
Additive Model

$$Y_t = L + S_t + T_t + E_t$$

Multiplicative Model

$$Y_t = L * S_t * T_t * E_t$$

Classification of Time Series Patterns

| | No Seasonal Effect | Additive Seasonal Effect | Multiplicative Seasonal Effect |
|-----------------------------|---|---|---|
| No Trend Effect |  |  |  |
| Additive Trend Effect |  |  |  |
| Multiplicative Trend Effect |  |  |  |

Agenda

Forecasting with Artificial Neural Networks

1. Forecasting?
 1. Forecasting as predictive Regression
 2. Time series prediction vs. causal prediction
 3. SARIMA-Modelling
 1. SARIMA – Differencing
 2. SARIMA – Autoregressive Terms
 3. SARIMA – Moving Average Terms
 4. SARIMA – Seasonal Terms
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Introduction to ARIMA Modelling

- Seasonal Autoregressive Integrated Moving Average Processes: SARIMA
 - popularised by George Box & Gwilym Jenkins in 1970s (names often used synonymously)
 - models are widely studied
 - Put together theoretical underpinning required to understand & use ARIMA
 - Defined general notation for dealing with ARIMA models

→ **claim that most time series can be parsimoniously represented by the ARIMA class of models**

- **ARIMA (p, d, q)-Models** attempt to describe the systematic pattern of a time series by **3 parameters**
 - **p**: Number of autoregressive terms (AR-terms) in a time series
 - **d**: Number of differences to achieve stationarity of a time series
 - **q**: Number of moving average terms (MA-terms) in a time series

$$\Phi_p(B)(1-B)^d Z_t = \delta + \Theta_q(B)e_t$$

The Box-Jenkins Methodology for ARIMA models

Model Identification

Data Preparation

- Transform time series for stationarity
- Difference time series for stationarity

Model selection

- Examine ACF & PACF
- Identify potential Models $(p,q)(sq,sp)$ auto

Model Estimation & Testing

Model Estimation

- Estimate parameters in potential models
- Select best model using suitable criterion

Model Diagnostics / Testing

- Check ACF / PACF of residuals → white noise
- Run portmanteau test of residuals

Re-identify

Model Application

Model Application

- Use selected model to forecast

ARIMA-Modelling

■ ARIMA(p,d,q)-Models

- **AR**IMA - Autoregressive Terms AR(p), with p=order of the autoregressive part
- **AR**IMA - Order of Integration, d=degree of first differencing/integration involved
- **AR**IMA - Moving Average Terms MA(q), with q=order of the moving average of error
- **S**ARIMA_t (p,d,q)(P,D,Q) with S the (P,D,Q)-process for the seasonal lags

■ Objective

- Identify the appropriate ARIMA model for the time series
- Identify AR-term
- Identify I-term
- Identify MA-term

■ Identification through

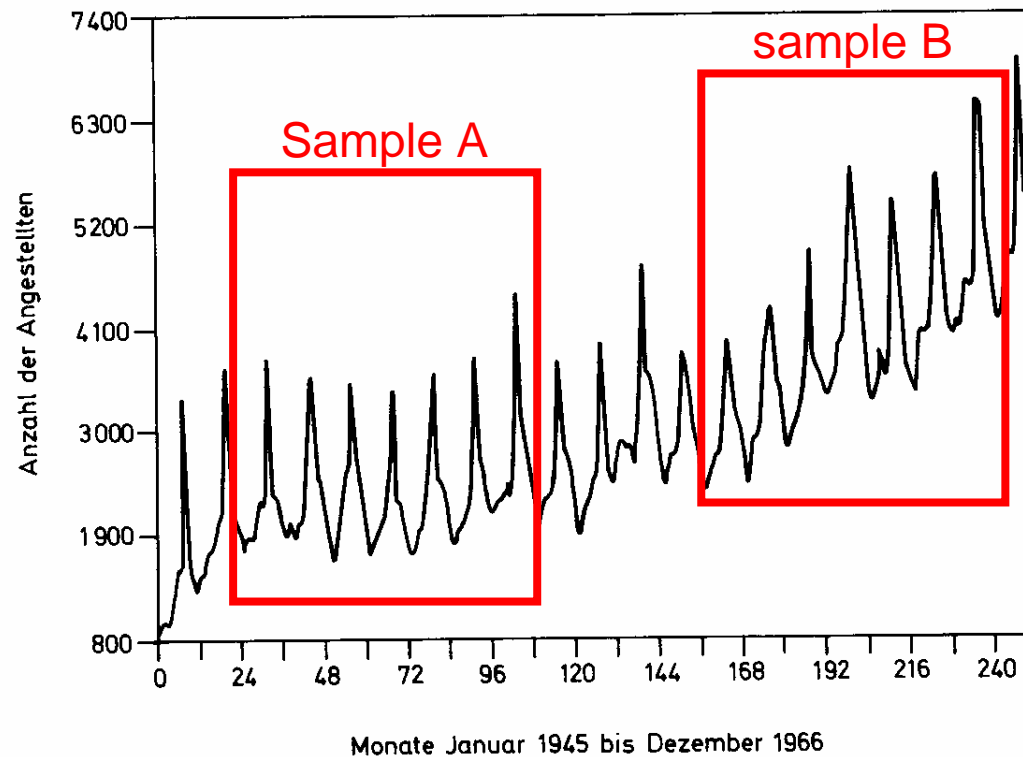
- Autocorrelation Function
- Partial Autocorrelation Function

ARIMA-Models: Identification of d -term

- Parameter d determines order of integration
- ARIMA models assume stationarity of the time series
 - Stationarity in the mean
 - Stationarity of the variance (homoscedasticity)
- Recap:
 - Let the mean of the time series at t be $\mu_t = E(Y_t)$
 - and $\lambda_{t,t-\tau} = \text{cov}(Y_t, Y_{t-\tau})$
 $\lambda_{t,t} = \text{var}(Y_t)$
- Definition
 - A time series is **stationary** if its mean level μ_t is constant for all t and its variance and covariances $\lambda_{t-\tau}$ are constant for all t
 - In other words:
 - all properties of the distribution (mean, variance, skewness, kurtosis etc.) of a random sample of the time series are independent of the absolute time t of drawing the sample → identity of mean & variance across time

ARIMA-Models: Stationarity and parameter d

- Is the time series stationary

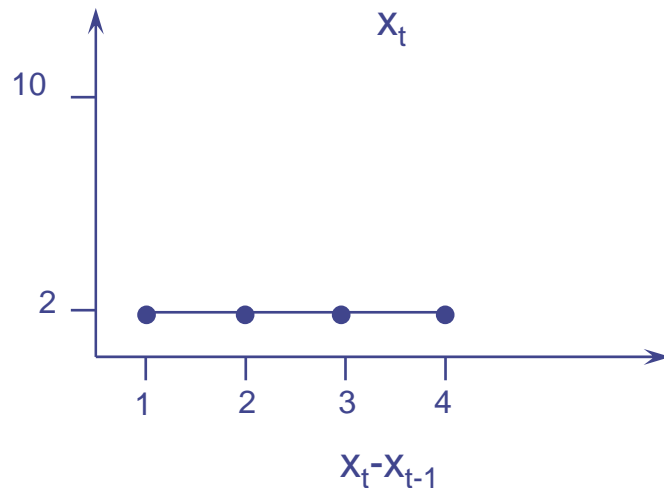
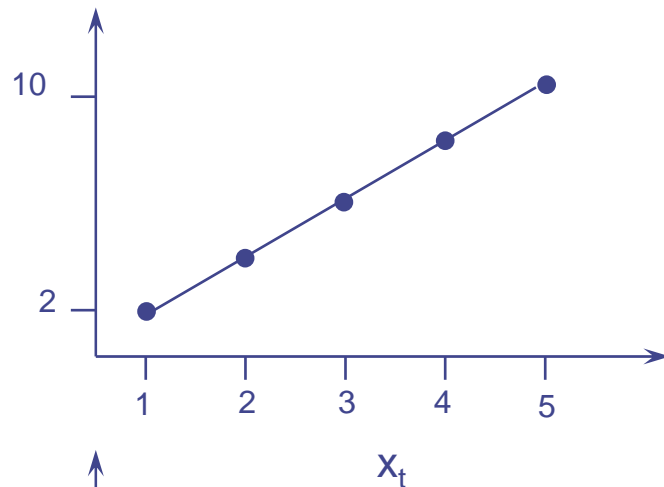


Stationarity:
 $\mu(A) = \mu(B)$
 $\text{var}(A) = \text{var}(B)$
etc.

this time series:
 $\mu(B) > \mu(A) \rightarrow$ trend
 \rightarrow instationary time series

ARIMA-Modells: Differencing for Stationarity

- Differencing time series



- E.g. : time series $Y_t = \{2, 4, 6, 8, 10\}$.
- time series exhibits linear trend
- 1st order differencing between observation Y_t and predecessor Y_{t-1} derives a transformed time series:

$$4 - 2 = 2$$

$$6 - 4 = 2$$

$$8 - 6 = 2$$

$$10 - 8 = 2$$

- The new time series $\Delta Y_t = \{2, 2, 2, 2\}$ is stationary through 1st differencing
- $d=1 \rightarrow$ ARIMA (0, 1, 0) model
- 2nd order differences: $d=2$

ARIMA-Modells: Differencing for Stationarity

- **Integration**

- **Differencing**

$$Z_t = Y_t - Y_{t-1}$$

- **Transforms: Logarithms etc.**

- ...

- **Where Z_t is a transform of the variable of interest Y_t chosen to make $Z_t - Z_{t-1} - (Z_{t-1} - Z_{t-2}) - \dots$ stationary**

- **Tests for stationarity:**

- Dickey-Fuller Test
 - Serial Correlation Test
 - Runs Test

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4. How to write a good Neural Network forecasting paper!

ARIMA-Models – Autoregressive Terms

- Description of Autocorrelation structure → auto regressive (AR) term
 - If a dependency exists between lagged observations Y_t and Y_{t-1} we can describe the realisation of Y_{t-1}

$$Y_t = c + \phi_1 Y_{t-1} + \phi_2 Y_{t-2} + \dots + \phi_p Y_{t-p} + e_t$$

Observation in time t Weight of the AR relationship Observation in t-1 (independent) random component („white noise“)

- Equations include only lagged realisations of the forecast variable
 - ARIMA(p,0,0) model = AR(p)-model
- Problems
 - Independence of residuals often violated (heteroscedasticity)
 - Determining number of past values problematic
- Tests for Autoregression: Portmanteau-tests
 - Box-Pierce test
 - Ljung-Box test

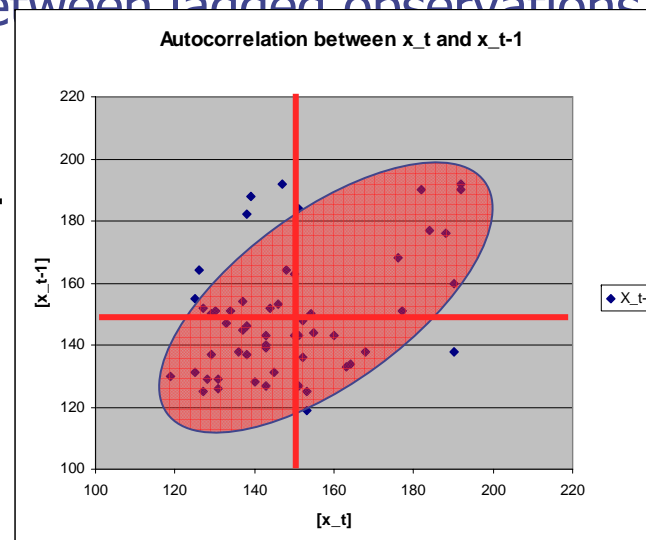
ARIMA-Modells: Parameter p of Autocorrelation

- stationary time series can be analysed for autocorrelation-structure
- The autocorrelation coefficient for lag k

$$\rho_k = \frac{\sum_{t=k+1}^n (Y_t - \bar{Y})(Y_{t-k} - \bar{Y})}{\sum_{t=1}^n (Y_t - \bar{Y})^2}$$

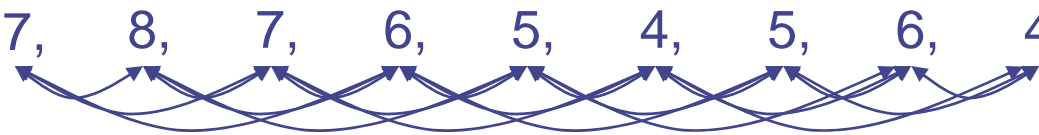
denotes the correlation between lagged observations of distance k

- Graphical interpretation ...
 - Uncorrelated data has low autocorrelations
 - Uncorrelated data shows no correlation pattern
 - ...



ARIMA-Modells: Parameter p

- E.g. time series Y_t 7, 8, 7, 6, 5, 4, 5, 6, 4.



lag 1:

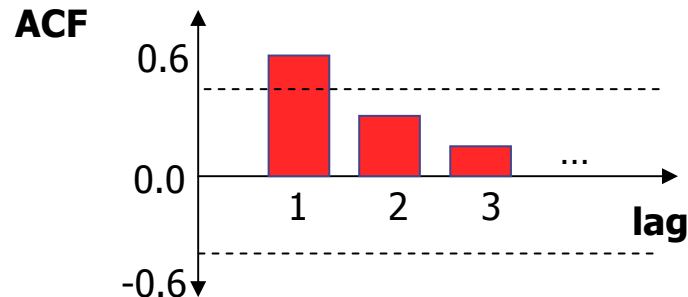
| |
|-------------|
| 7, 8 |
| 8, 7 |
| 7, 6 |
| 6, 5 |
| 5, 4 |
| 4, 5 |
| 5, 6 |
| 6, 4 |
| $r_1 = .62$ |

lag 2:

| |
|-------------|
| 7, 7 |
| 8, 6 |
| 7, 5 |
| 6, 4 |
| 5, 5 |
| 4, 6 |
| 5, 4 |
| $r_2 = .32$ |

lag 3:

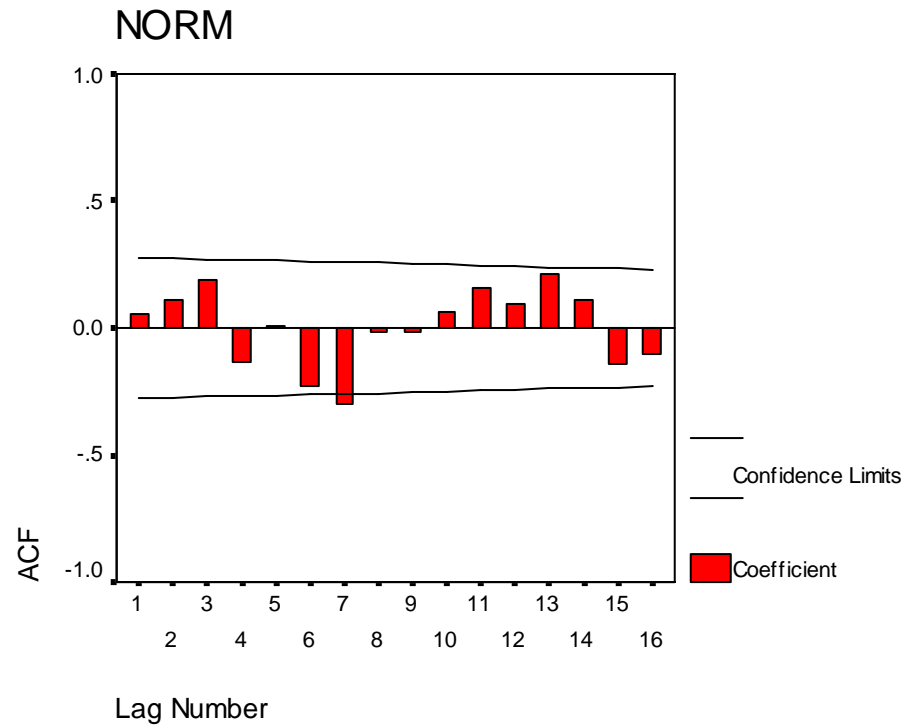
| |
|-------------|
| 7, 6 |
| 8, 5 |
| 7, 4 |
| 6, 5 |
| 5, 6 |
| 4, 5 |
| $r_3 = .15$ |



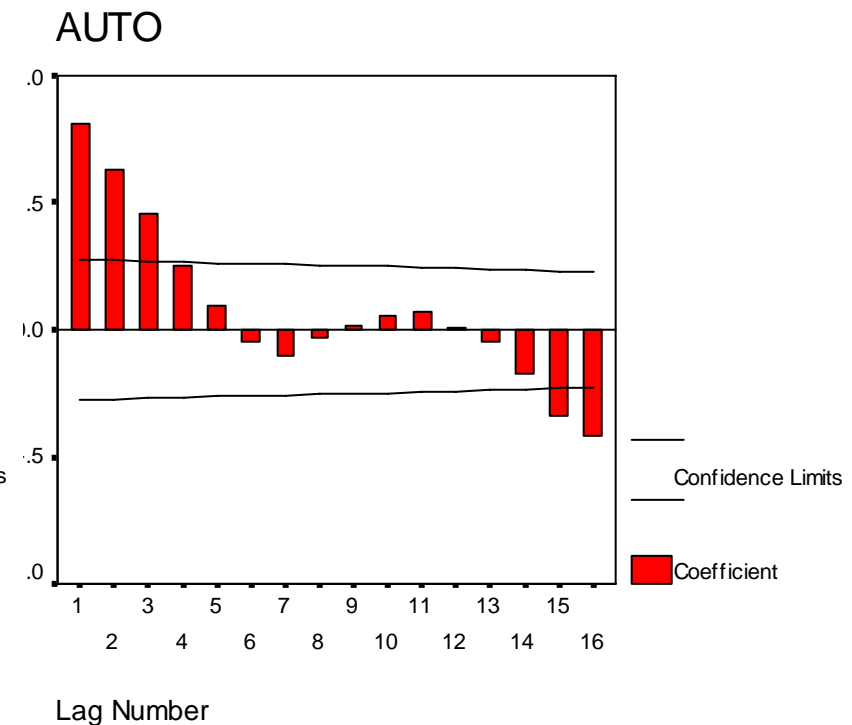
→ Autocorrelations r_t gathered at lags 1, 2, ... make up the autocorrelation function (ACF)

ARIMA-Models – Autoregressive Terms

- Identification of AR-terms ...?



- Random independent observations



- An AR(1) process?

ARIMA-Modells: Partial Autocorrelations

- Partial Autocorrelations are used to measure the degree of association between Y_t and Y_{t-k} when the effects of other time lags $1, 2, 3, \dots, k-1$ are removed
 - Significant AC between Y_t and Y_{t-1}
 - significant AC between Y_{t-1} and Y_{t-2}
 - induces correlation between Y_t and Y_{t-2} ! (1st AC = PAC!)

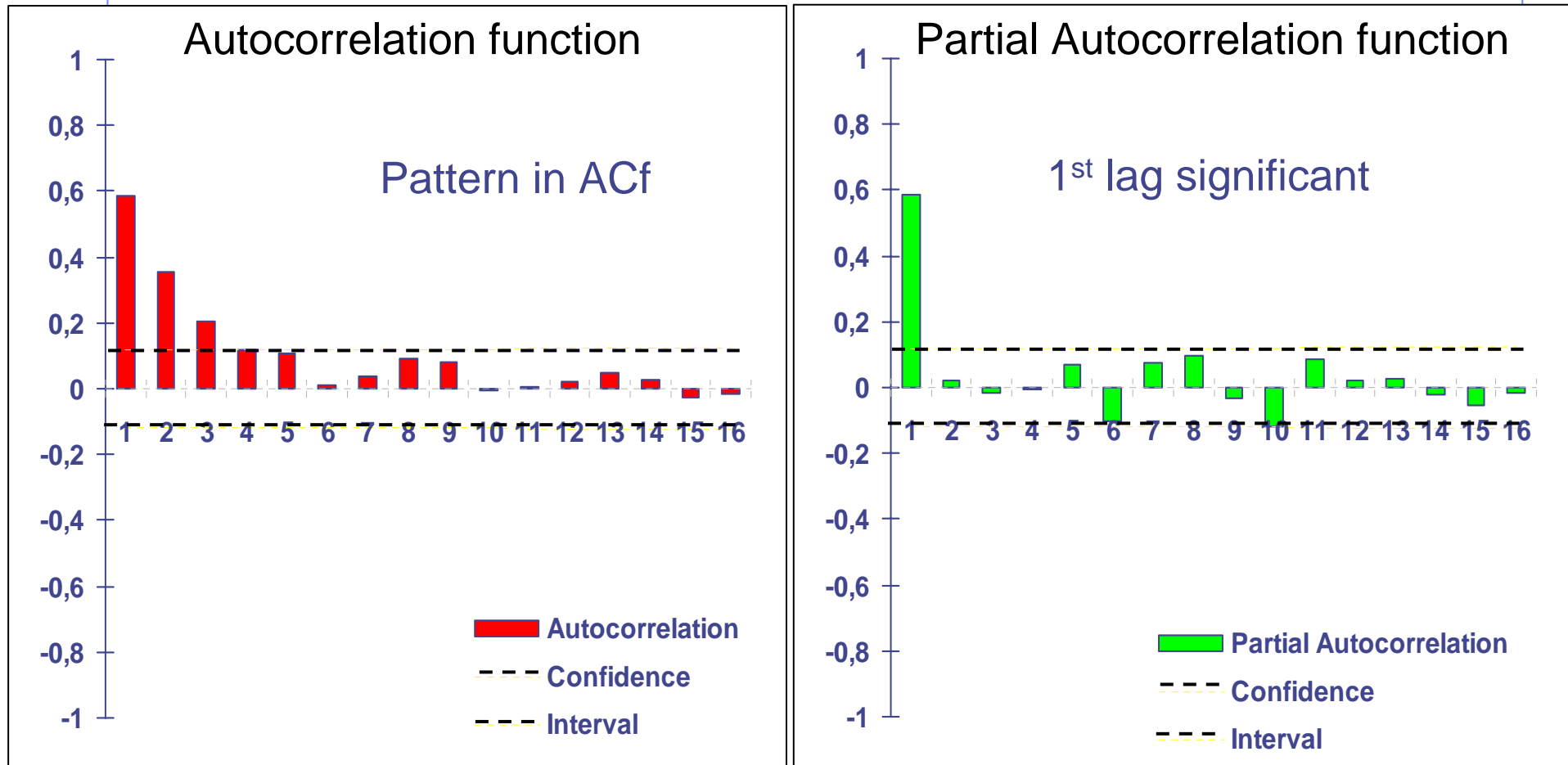
- When fitting an AR(p) model to the time series, the last coefficient ϕ_p of Y_{t-p} measures the excess correlation at lag p which is not accounted for by an AR($p-1$) model. π_p is called the p th order partial autocorrelation, i.e.

$$\pi_p = \text{corr}(Y_t, Y_{t-p} \mid Y_{t-1}, Y_{t-2}, \dots, Y_{t-p+1})$$

- Partial Autocorrelation coefficient measures true correlation at Y_{t-p}

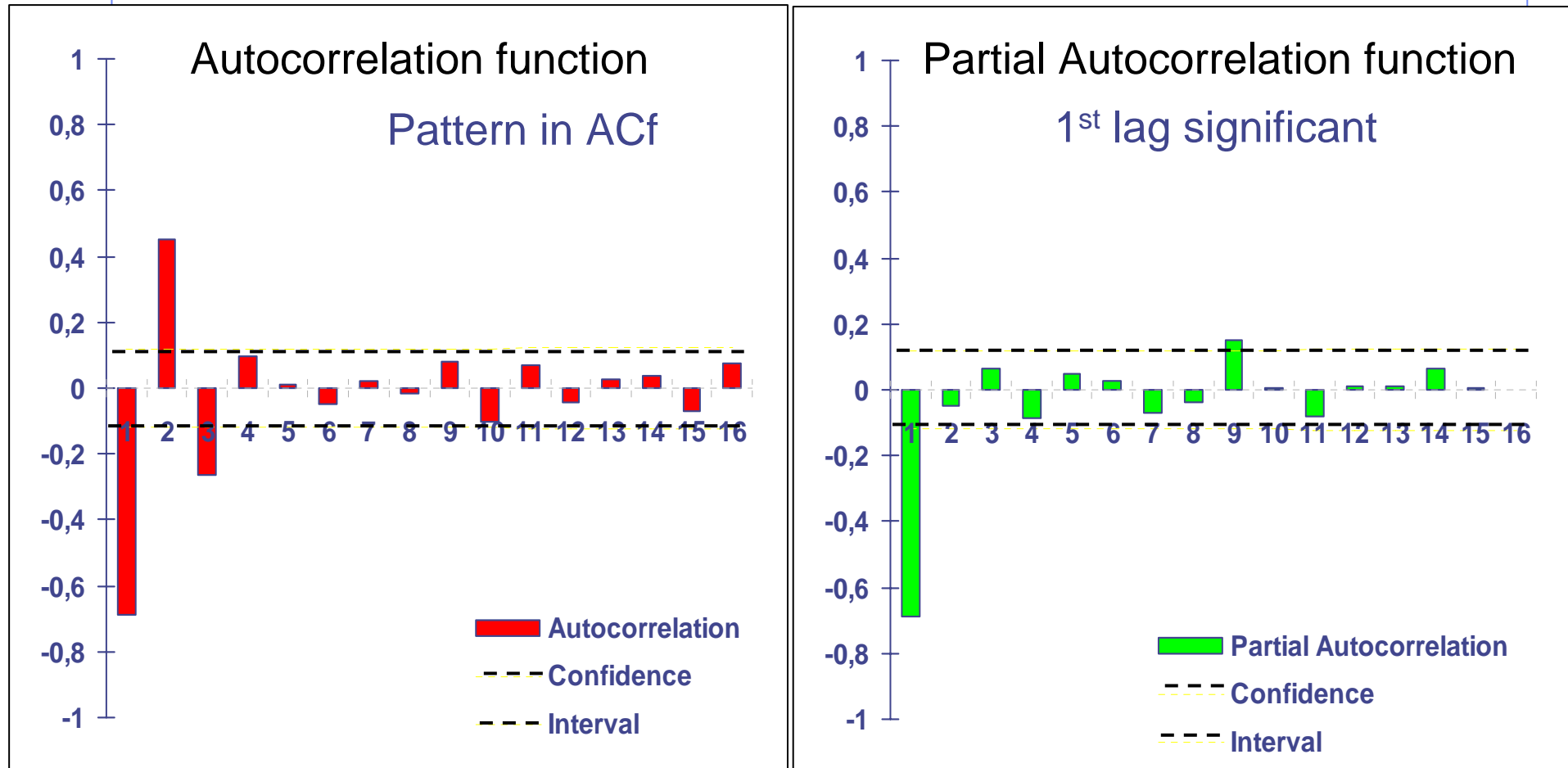
$$Y_t = \phi_0 + \phi_{p1} Y_{t-1} + \phi_{p2} Y_{t-2} + \dots + \pi_p Y_{t-p} + v_t$$

ARIMA Modelling – AR-Model patterns



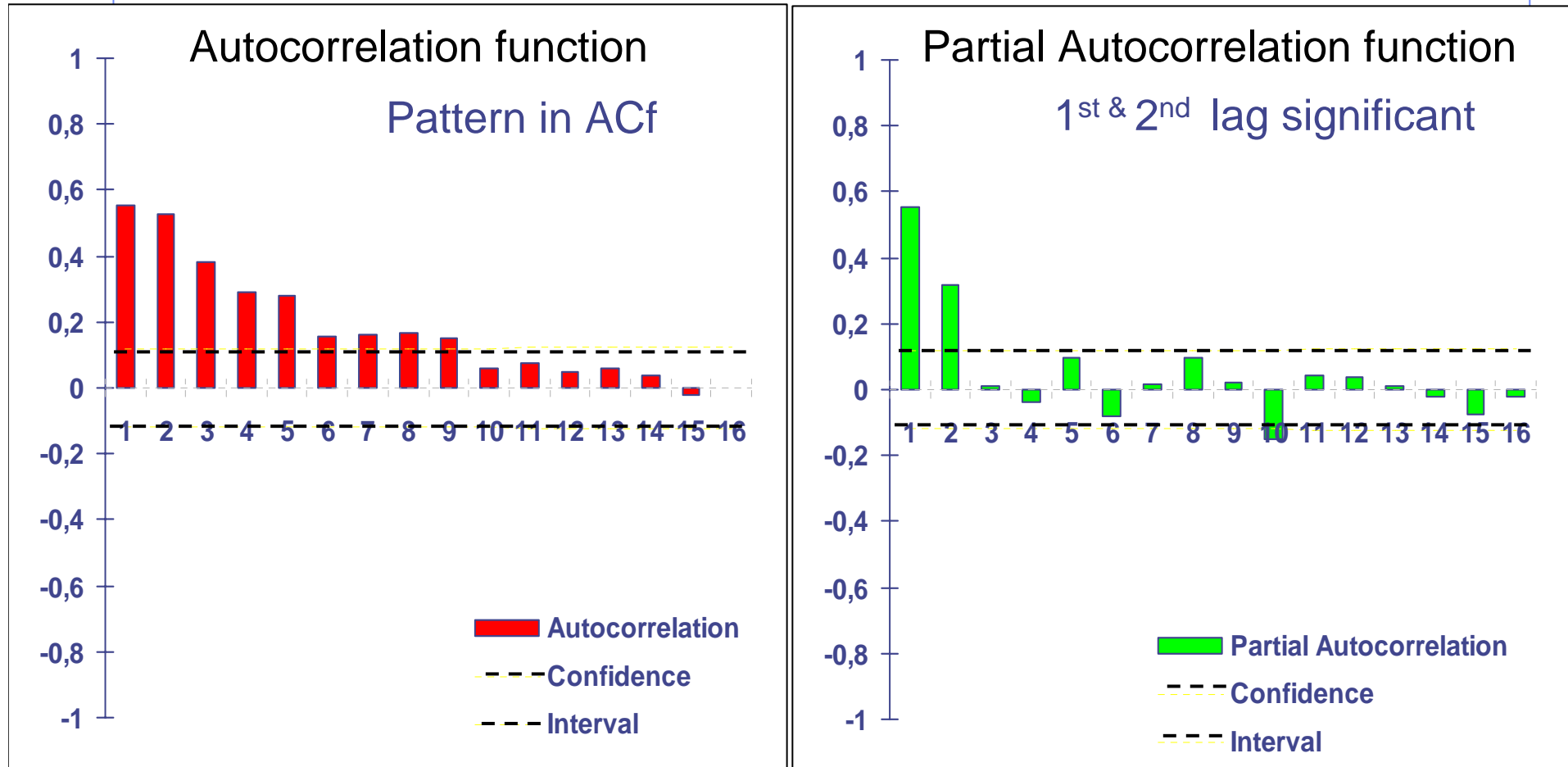
- AR(1) model: $Y_t = c + \phi_1 Y_{t-1} + e_t$ =ARIMA (1,0,0)

ARIMA Modelling – AR-Model patterns



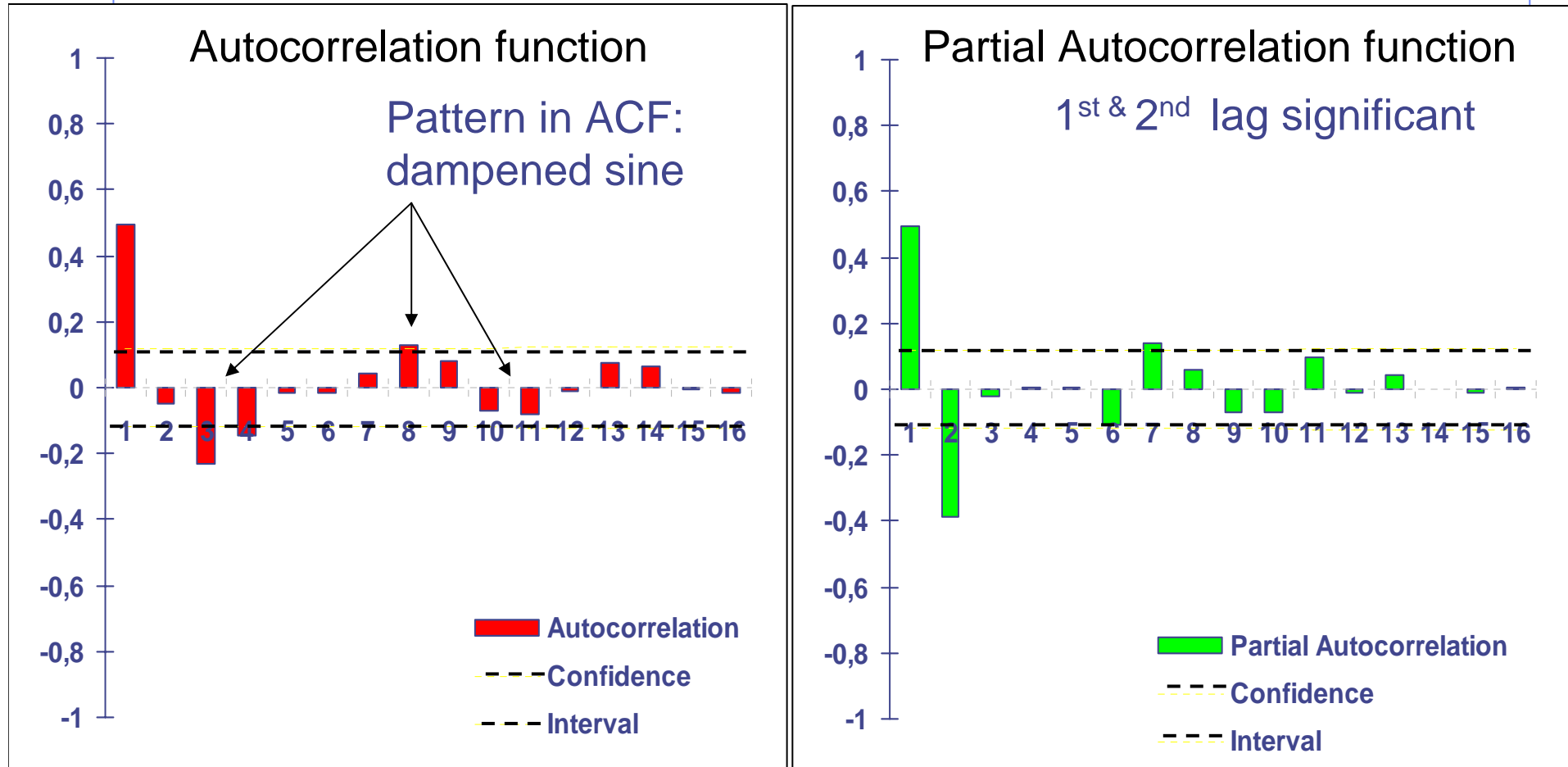
- AR(1) model: $Y_t = c + \phi_1 Y_{t-1} + e_t$ =ARIMA (1,0,0)

ARIMA Modelling – AR-Model patterns



- AR(2) model: $Y_t = c + \phi_1 Y_{t-1} + \phi_2 Y_{t-2} + e_t$
=ARIMA (2,0,0)

ARIMA Modelling – AR-Model patterns



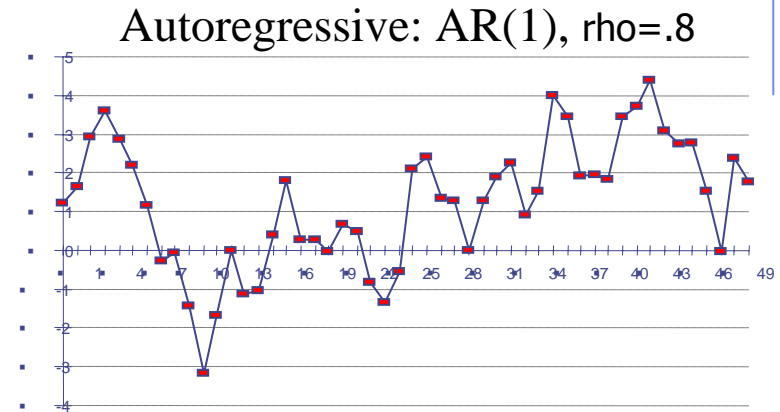
- AR(2) model: $Y_t = c + \phi_1 Y_{t-1} + \phi_2 Y_{t-2} + e_t$
 =ARIMA (2,0,0)

ARIMA Modelling – AR-Models

- Autoregressive Model of order one ARIMA(1,0,0), AR(1)

$$Y_t = c + \phi_1 Y_{t-1} + e_t$$

$$= 1.1 + 0.8Y_{t-1} + e_t$$



- Higher order AR models

$$Y_t = c + \phi_1 Y_{t-1} + \phi_2 Y_{t-2} + \dots + \phi_p Y_{t-p} + e_t$$

for $p = 1, -1 < \phi_1 < 1$

$$p = 2, -1 < \phi_2 < 1 \wedge \phi_2 + \phi_1 < 1 \wedge \phi_2 - \phi_1 < 1$$

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ARIMA Modelling – Moving Average Prozesse

- Description of Moving Average structure
 - AR-Models may not approximate data generator underlying the observations perfectly → residuals $e_t, e_{t-1}, e_{t-2}, \dots, e_{t-q}$
 - Observation Y_t may depend on realisation of previous errors e
 - Regress against past errors as explanatory variables

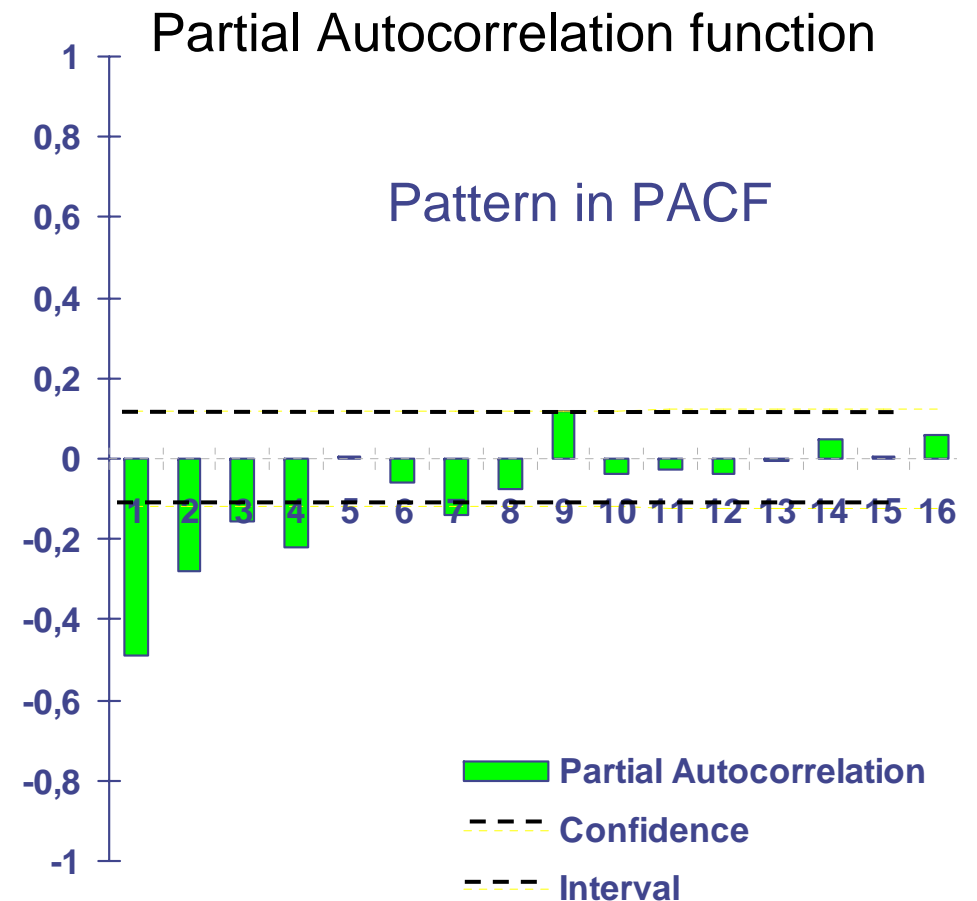
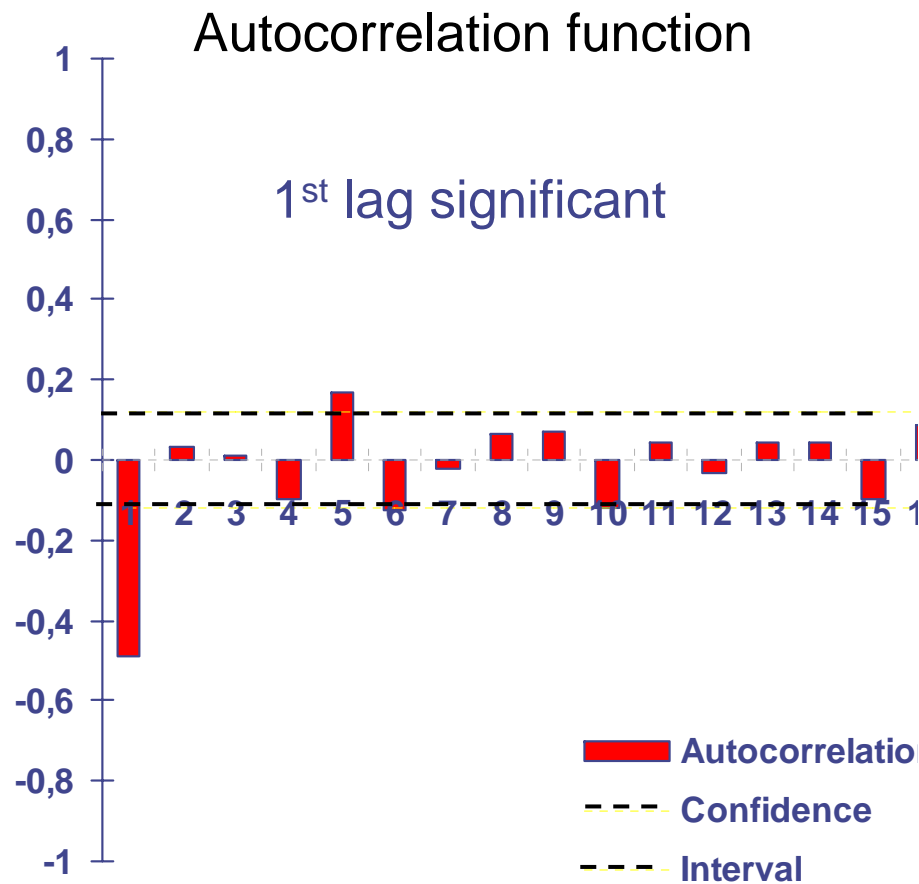
$$Y_t = c + e_t - \theta_1 e_{t-1} - \theta_2 e_{t-2} - \dots - \theta_q e_{t-q}$$

- ARIMA(0,0,q)-model = MA(q)-model

for $q = 1, -1 < \theta_1 < 1$

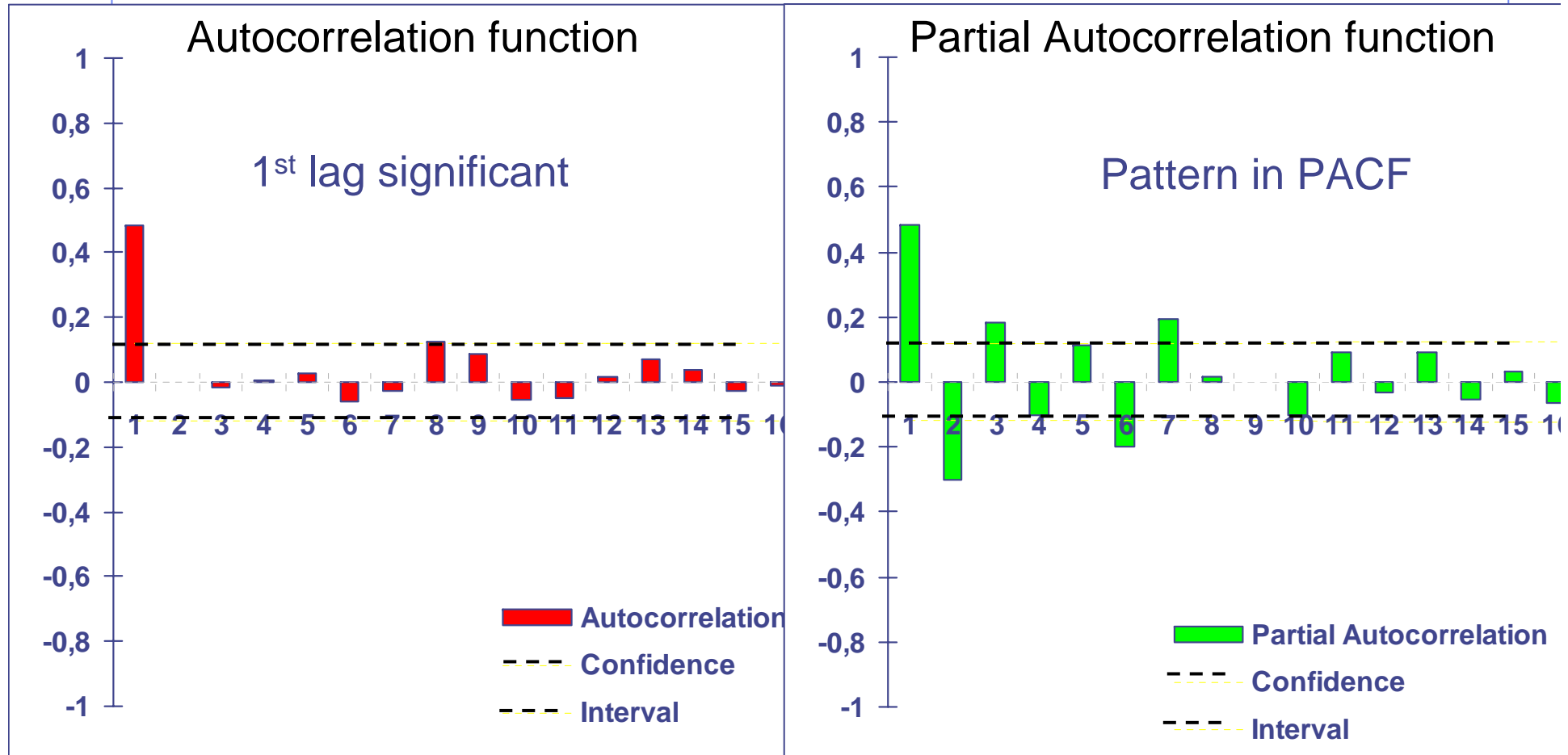
$q = 2, -1 < \theta_2 < 1 \wedge \theta_2 + \theta_1 < 1 \wedge \theta_2 - \theta_1 < 1$

ARIMA Modelling – MA-Model patterns



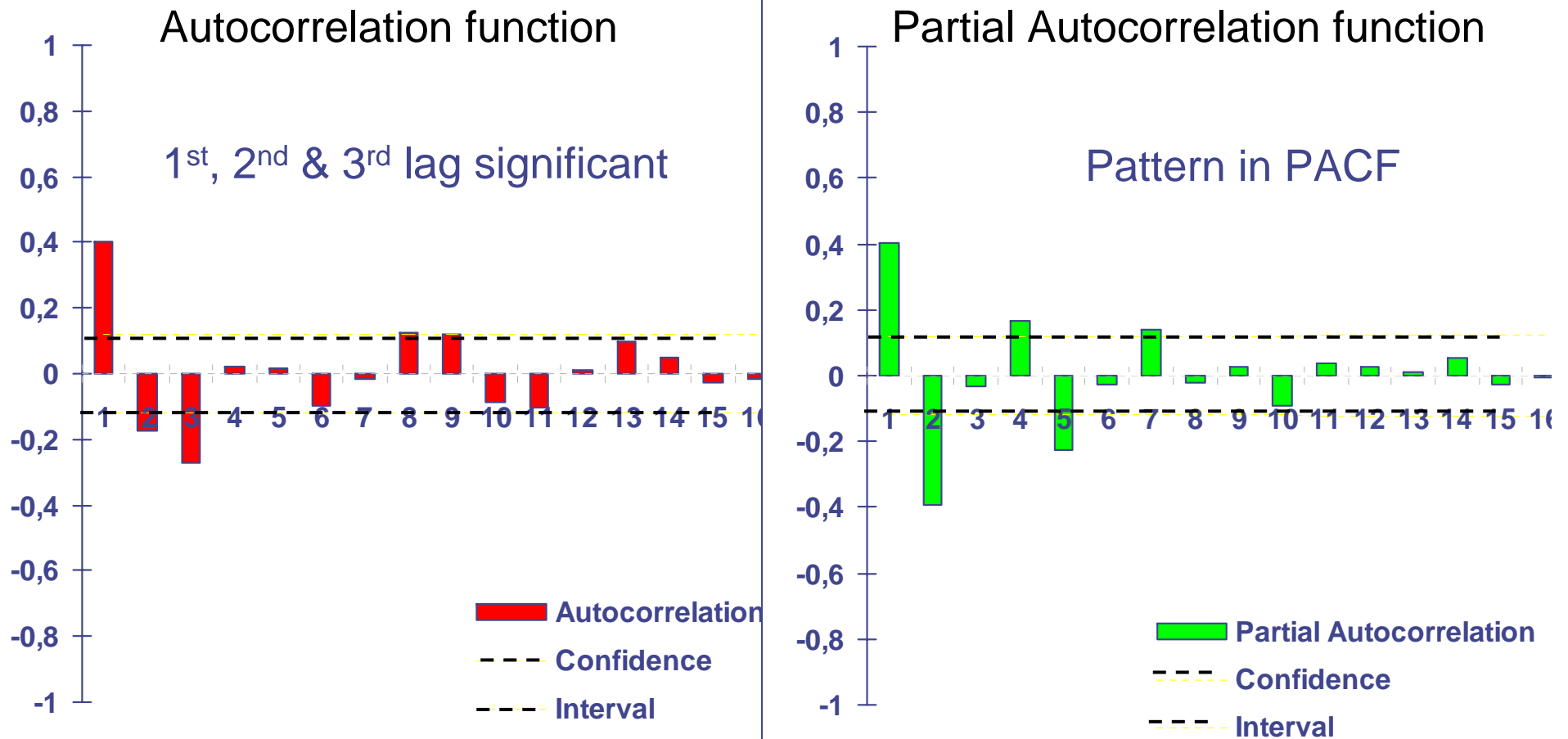
- MA(1) model: $Y_t = c + e_t - \theta_1 e_{t-1}$ =ARIMA
(0,0,1)

ARIMA Modelling – MA-Model patterns



- MA(1) model: $Y_t = c + e_t - \theta_1 e_{t-1}$ =ARIMA (0,0,1)

ARIMA Modelling – MA-Model patterns

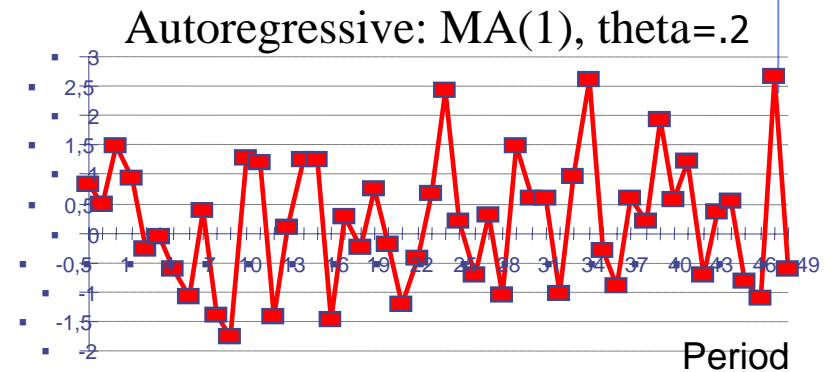


- MA(3) model: $Y_t = c + e_t - \theta_1 e_{t-1} - \theta_1 e_{t-2} - \theta_1 e_{t-3}$
 =ARIMA (0,0,3)

ARIMA Modelling – MA-Models

- Autoregressive Model of order one ARIMA(0,0,1)=MA(1)

$$\begin{aligned} Y_t &= c + e_t - \theta_1 e_{t-1} \\ &= 10 + e_t + 0.2e_{t-1} \end{aligned}$$



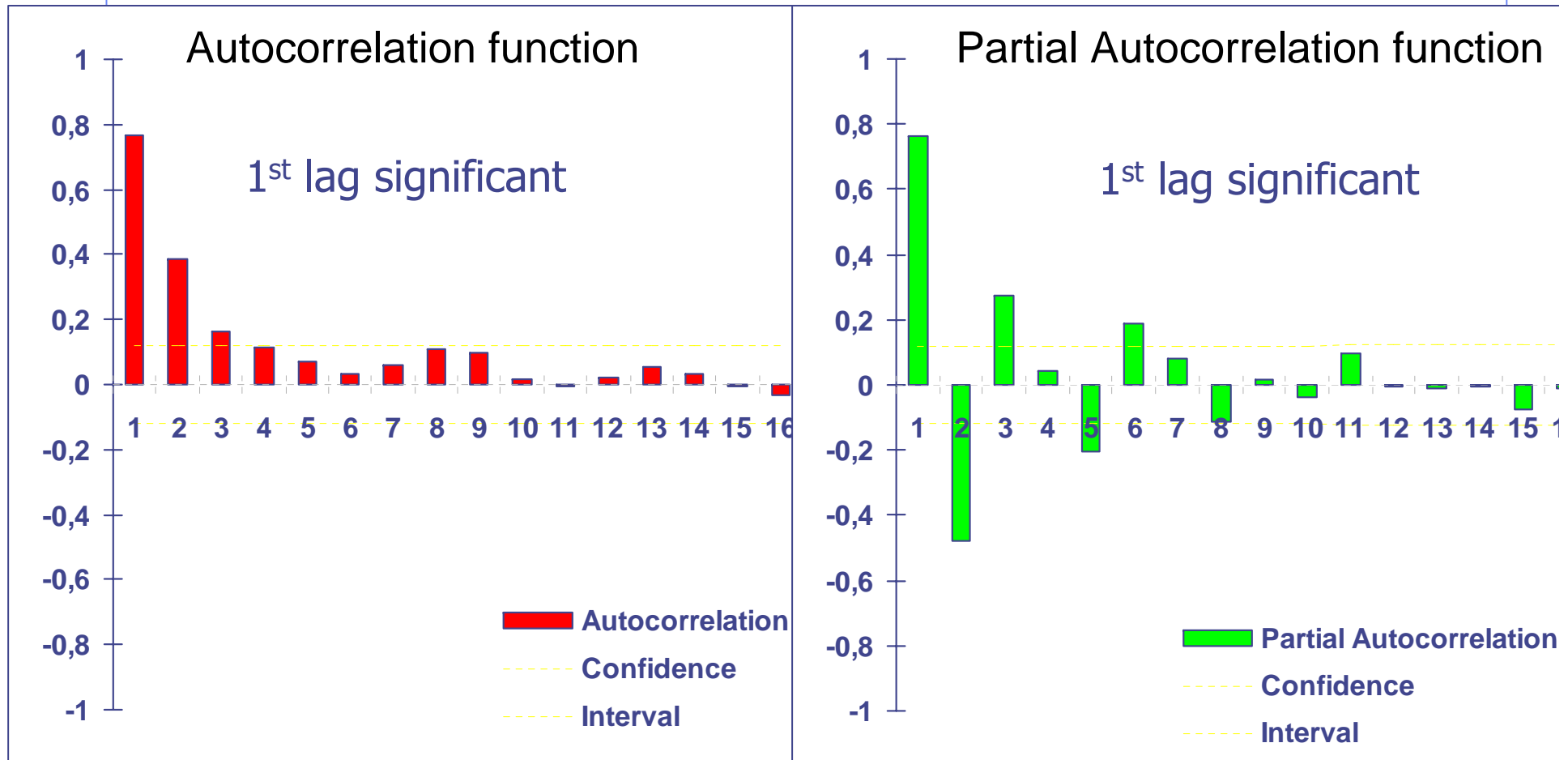
ARIMA Modelling – Mixture ARMA-Models

- complicated series may be modelled by combining AR & MA terms
 - ARMA(1,1)-Model = ARIMA(1,0,1)-Model

$$Y_t = c + \phi_1 Y_{t-1} + e_t - \theta_1 e_{t-1}$$

- Higher order ARMA(p,q)-Models

$$Y_t = c + \phi_1 Y_{t-1} + \phi_2 Y_{t-2} + \dots + \phi_p Y_{t-p} + e_t \\ - \theta_1 e_{t-1} - \theta_2 e_{t-2} - \dots - \theta_q e_{t-q}$$



- AR(1) and MA(1) model:
=ARMA(1,1)=ARIMA (1,0,1)

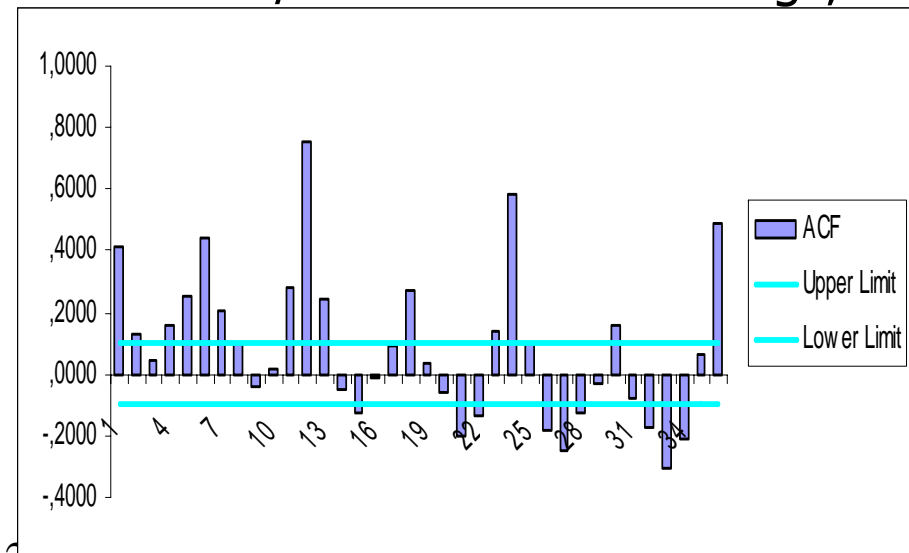
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Seasonality in ARIMA-Models

- Identifying seasonal data: Spikes in ACF / PACF at seasonal lags, e.g.
 - $t-12$ & $t-13$ for yearly
 - $t-4$ & $t-5$ for quarterly

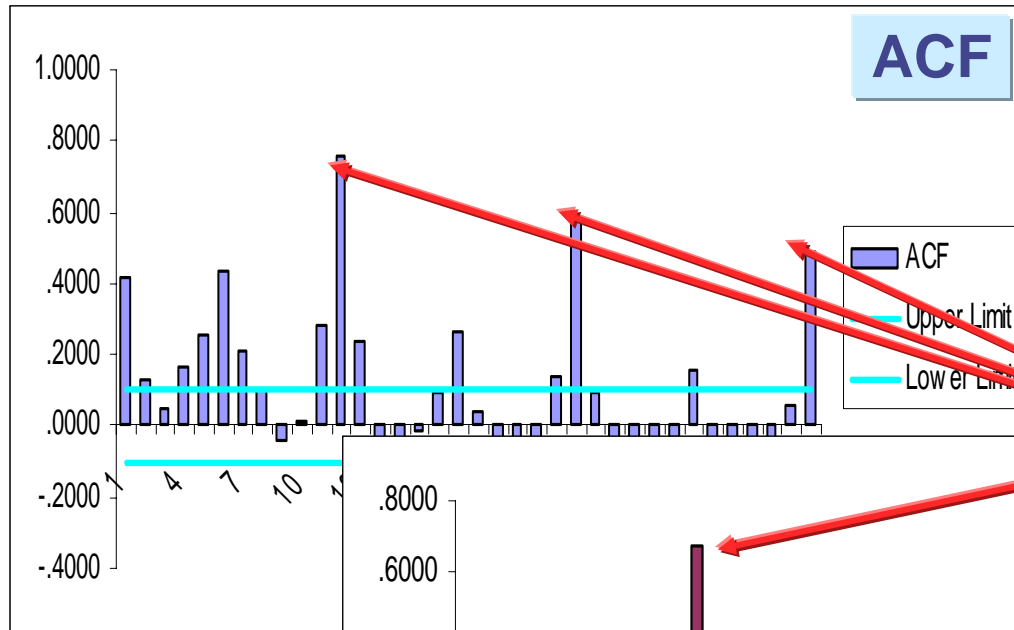


- Differences

- Simple: $\Delta Y_t = (1-B)Y_t$
- Seasonal: $\Delta^s Y_t = (1-B^s)Y_t$
with $s =$ seasonality, eg. 4, 12

- Data may require seasonal differencing to remove seasonality
 - To identify model, specify seasonal parameters: (P,D,Q)
 - the seasonal autoregressive parameters P
 - seasonal difference D and
 - seasonal moving average Q
- Seasonal ARIMA (p,d,q)(P,D,Q)-model

Seasonality in ARIMA-Models



**Seasonal spikes
= monthly data**

Seasonality in ARIMA-Models

- Extension of Notation of Backshift Operator

$$\Delta^s Y_t = Y_t - Y_{t-s} = Y_t - B^s Y_t = (1 - B^s) Y_t$$

- Seasonal difference followed by a first difference: $(1 - B) (1 - B^s)$
 Y_t

$$(1 - \phi_1 B) (1 - \Phi_1 B^4) (1 - B) (1 - B^4) Y_t = c + (1 - \theta_1 B) (1 - \Theta_1 B^4) e_t$$

Diagram illustrating the components of the ARIMA model equation:

- Non-seasonal AR(1)**: $(1 - \phi_1 B)$
- Seasonal AR(1)**: $(1 - \Phi_1 B^4)$
- Non-seasonal difference**: $(1 - B)$
- Seasonal difference**: $(1 - B^4)$
- Non-seasonal MA(1)**: $(1 - \theta_1 B)$
- Seasonal MA(1)**: $(1 - \Theta_1 B^4)$

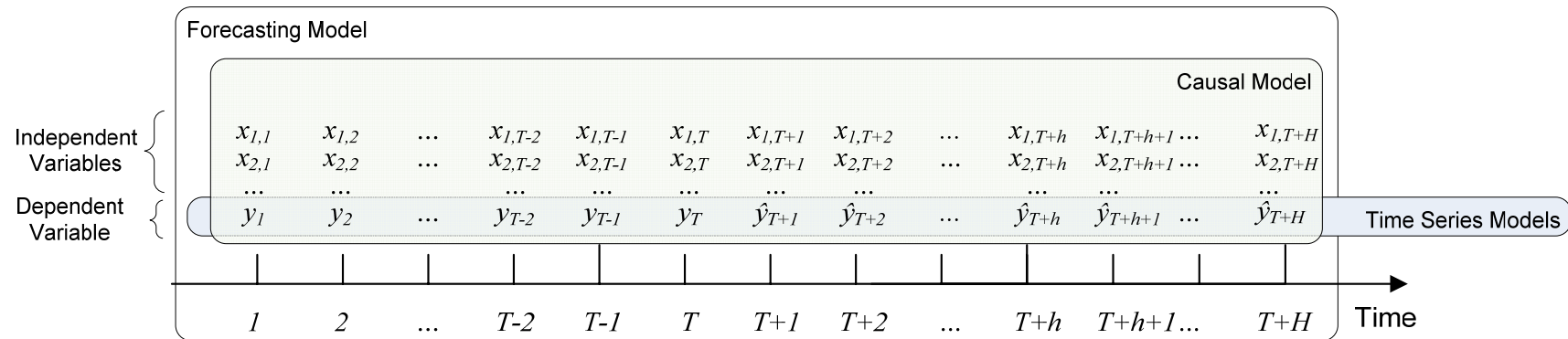
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Forecasting with Artificial Neural Networks

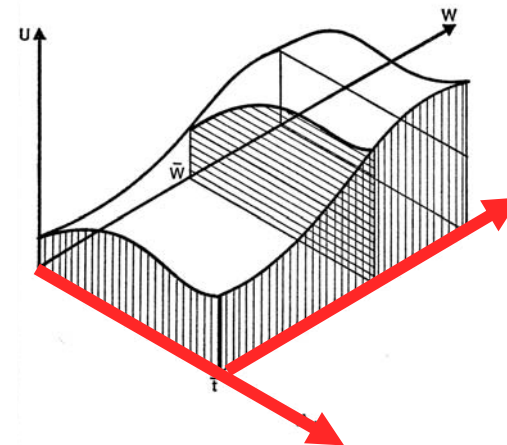
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Forecasting Models

- Time series analysis vs. causal modelling

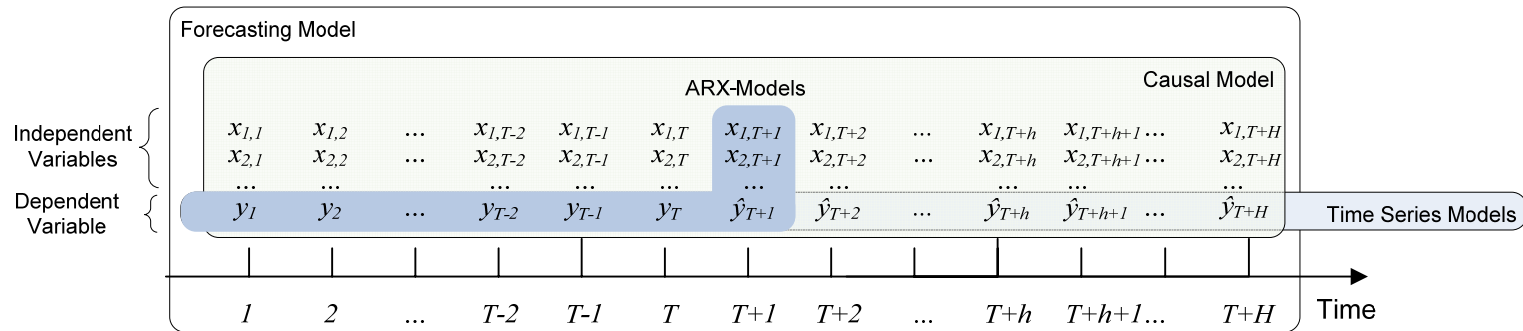


- Time series prediction (Univariate)
 - Assumes that data generating process that creates patterns can be explained only from previous observations of dependent variable
- Causal prediction (Multivariate)
 - Data generating process can be explained by interaction of causal (cause-and-effect) independent variables

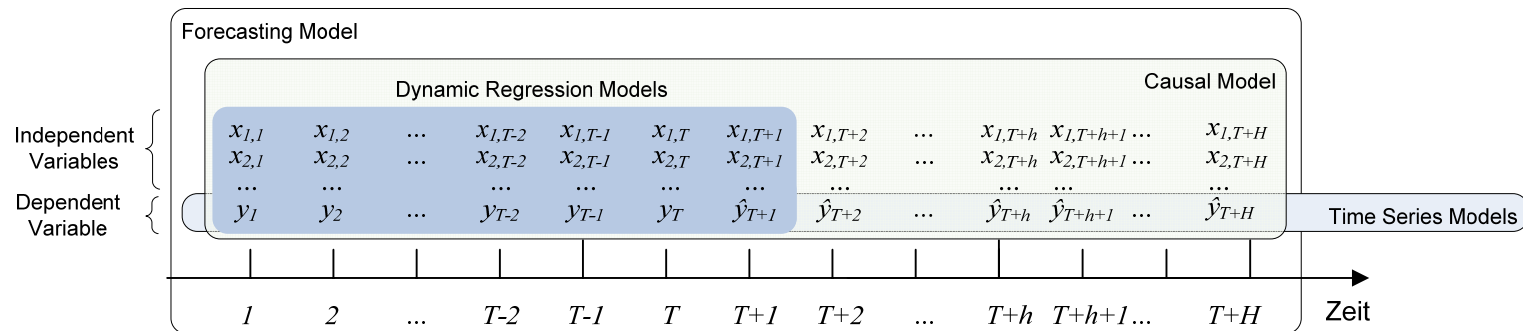


Causal Prediction

- ARX(p)-Models



- General Dynamic Regression Models



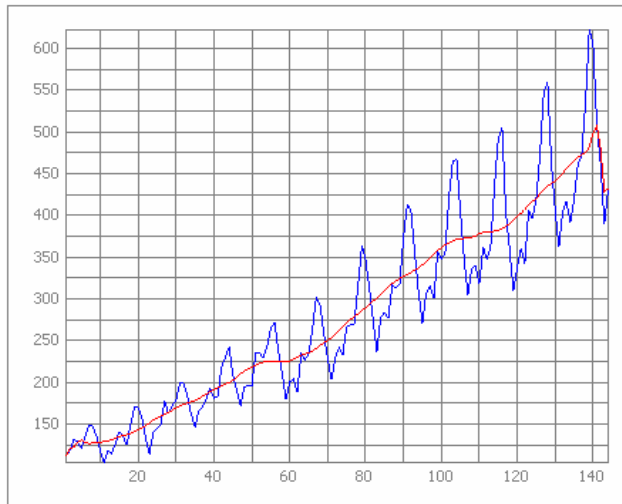
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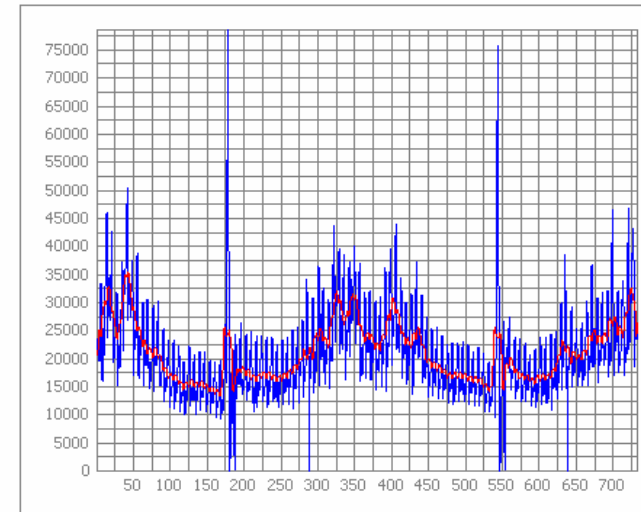
Why forecast with NN?

- Pattern or noise?



— Time Series — Moving Average (12)

- Airline Passenger data
 - Seasonal, trended
- Real "model" disagreed:
 - multiplicative seasonality
 - or additive seasonality
 - with level shifts?

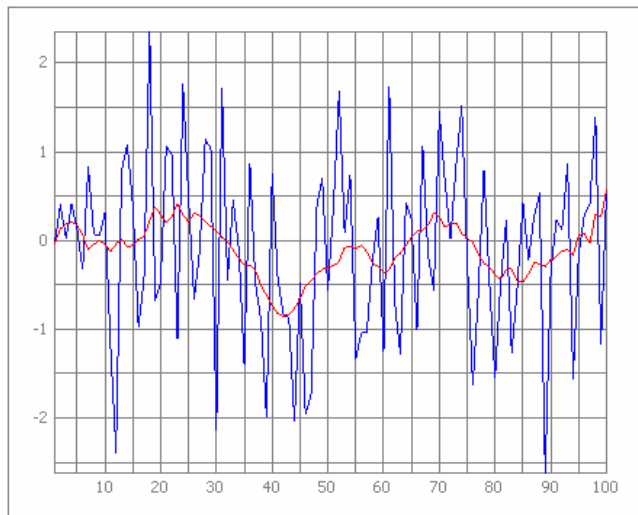


— Time Series — Moving Average (12)

- Fresh products
 - supermarket Sales
- Seasonal, events,
 - heteroscedastic noise
- Real "model" unknown

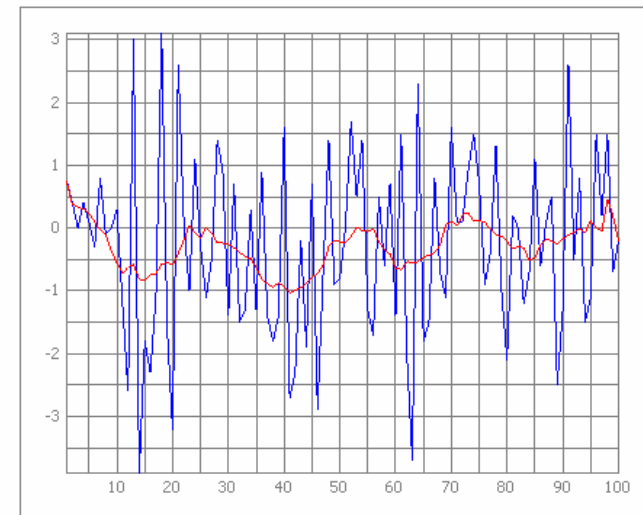
Why forecast with NN?

- Pattern or noise?



— Time Series — Moving Average (12)

→ **Random Noise iid**
(normally distributed:
mean 0; std.dev. 1)

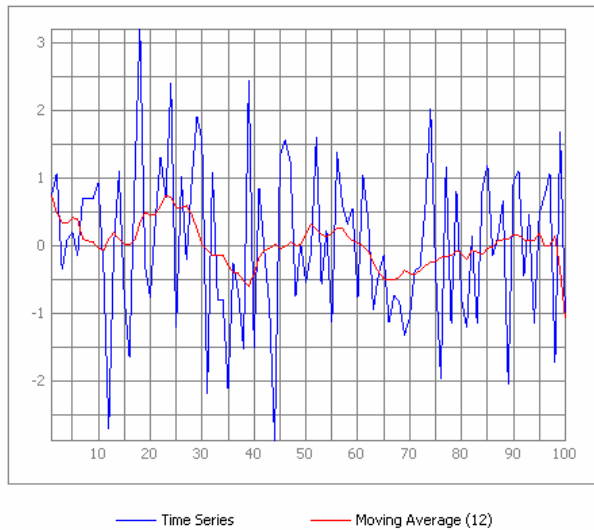


→ **BL(p,q) Bilinear**
Autoregressive Model

$$y_t = 0.7y_{t-1}\varepsilon_{t-2} + \varepsilon_t$$

Why forecast with NN?

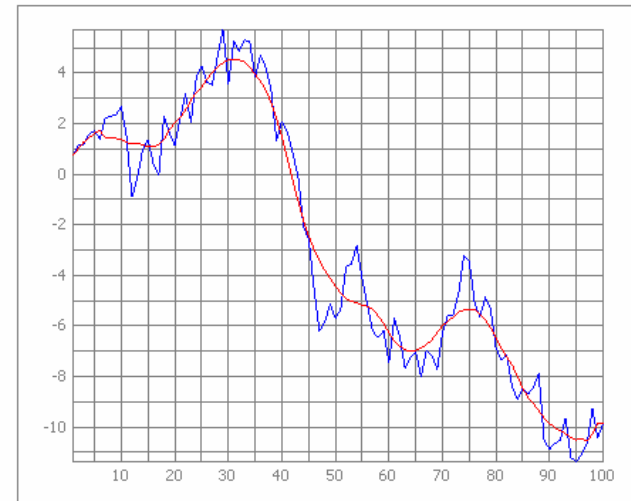
- Pattern or noise?



→ **TAR(p) Threshold
Autoregressive model**

$$y_t = 0.9y_{t-1} + \varepsilon_t \quad \text{for } |y_{t-1}| \leq 1$$

$$= -0.3y_{t-1} - \varepsilon_t \quad \text{for } |y_{t-1}| > 1$$



→ **Random walk**

$$y_t = y_{t-1} + \varepsilon_t$$

Motivation for NN in Forecasting – Nonlinearity!

- True data generating process is unknown & hard to identify
 - Many interdependencies in business are nonlinear

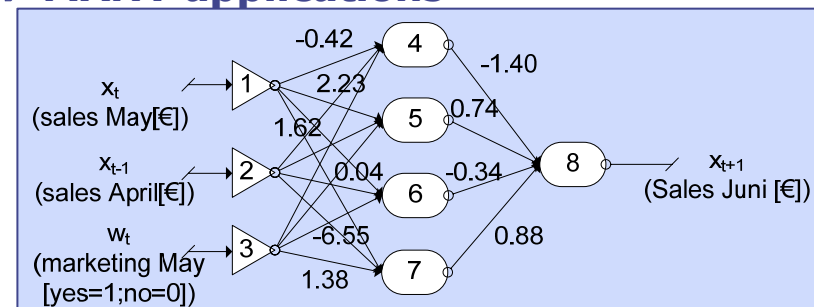
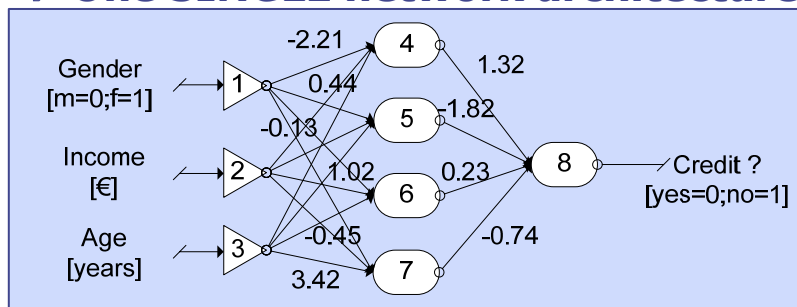
 - NN can approximate any LINEAR and NONLINEAR function to any desired degree of accuracy
 - Can learn linear time series patterns
 - Can learn nonlinear time series patterns
 - Can extrapolate linear & nonlinear patterns = generalisation!
 - NN are nonparametric
 - Don't assume particular noise process, i.e. gaussian
 - NN model (learn) linear and nonlinear process directly from data
 - Approximate underlying data generating process
- **NN are flexible forecasting paradigm**

Motivation for NN in Forecasting - Modelling Flexibility

→ Unknown data processes require building of many candidate models!

- Flexibility on Input Variables → flexible coding
 - binary scale [0;1]; [-1,1]
 - nominal / ordinal scale (0,1,2,...,10 → binary coded [0001,0010,...])
 - metric scale (0.235; 7.35; 12440.0; ...)
- Flexibility on Output Variables
 - binary → prediction of single class membership
 - nominal / ordinal → prediction of multiple class memberships
 - metric → regression (point predictions) OR probability of class membership!
- Number of Input Variables
 - ...
- Number of Output Variables
 - ...

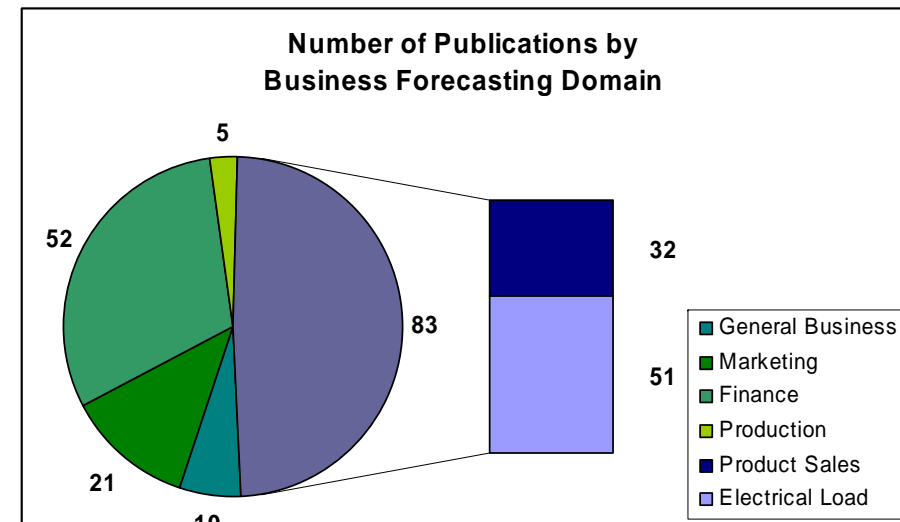
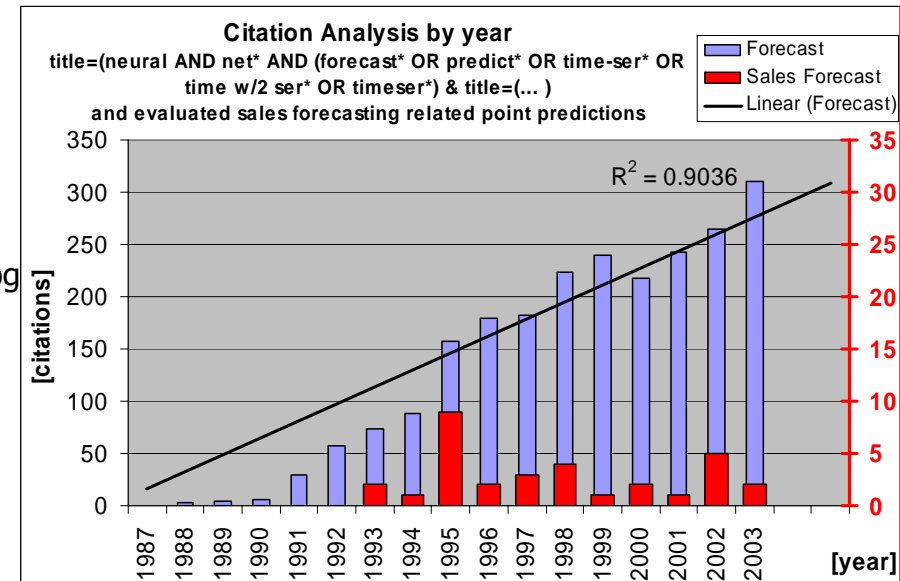
→ **One SINGLE network architecture** → **MANY applications**



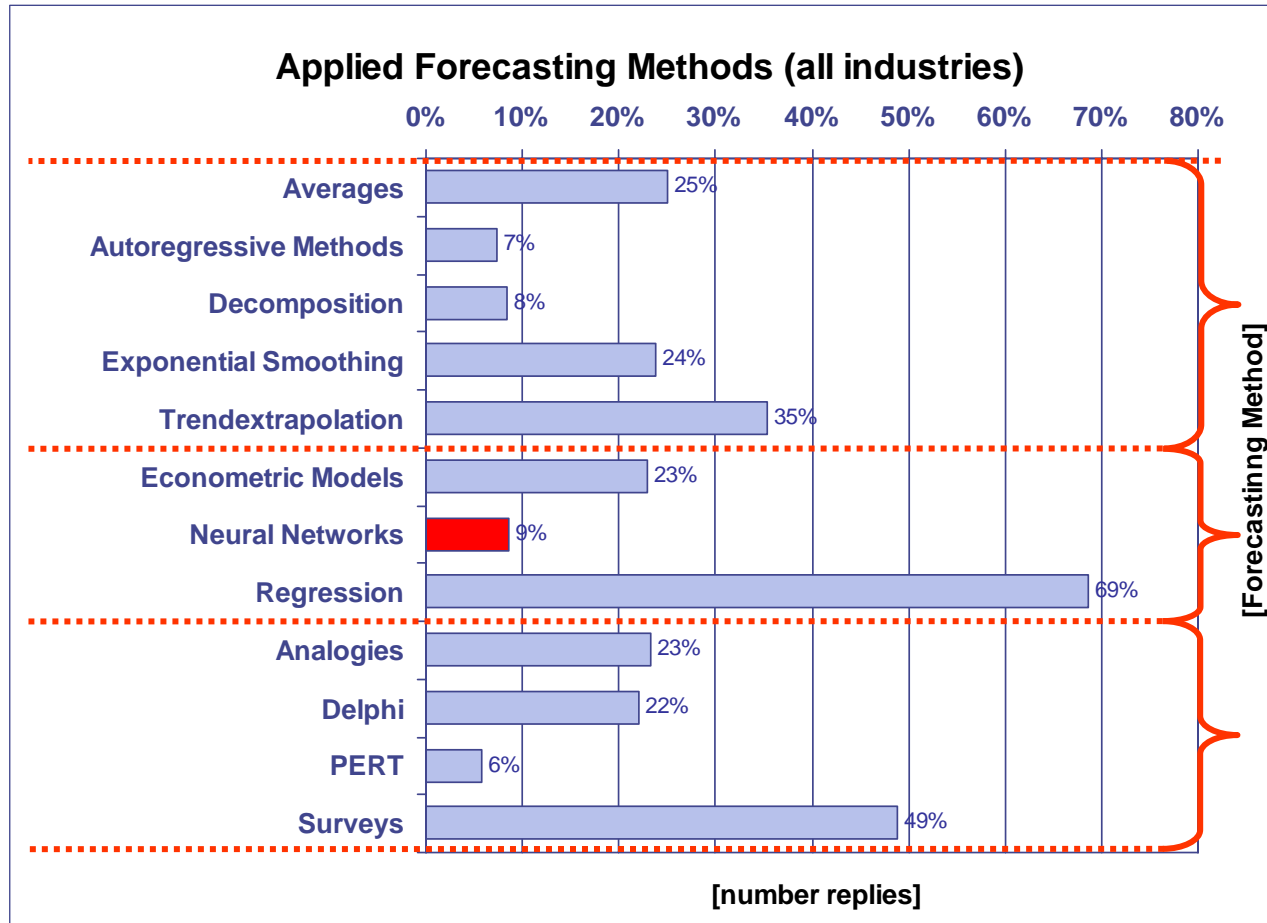
Applications of Neural Nets in diverse Research Fields

→ 2500+ journal publications on NN & Forecasting alone!

- **Neurophysiology**
→ simulate & explain brain
 - **Informatics**
→ eMail & url filtering
→ VirusScan (Symmantec Norton Antivirus)
→ Speech Recognition & Optical Character Recog
 - **Engineering**
→ control applications in plants
→ automatic target recognition (DARPA)
→ explosive detection at airports
→ Mineral Identification (NASA Mars Explorer)
→ starting & landing of Jumbo Jets (NASA)
 - **Meteorology / weather**
→ Rainfall prediction
→ ElNino Effects
 - **Corporate Business**
→ credit card fraud detection
→ simulate forecasting methods
 - **Business Forecasting Domains**
 - Electrical Load / Demand
 - Financial Forecasting
 - Currency / Exchange rate
 - stock forecasting etc.
 - Sales forecasting
- not all NN recommendations are useful for your DOMAIN!



IBF Benchmark– Forecasting Methods used



Time Series methods
(objective) → 61%

Causal Methods
(objective) → 23%

Judgemental Methods
(subjective) → 2x%

→ Survey 5 IBF conferences in 2001
 □ 240 forecasters, 13 industries

→ NN are applied in corporate Demand Planning / S&OP processes!

[Warning: limited sample size]

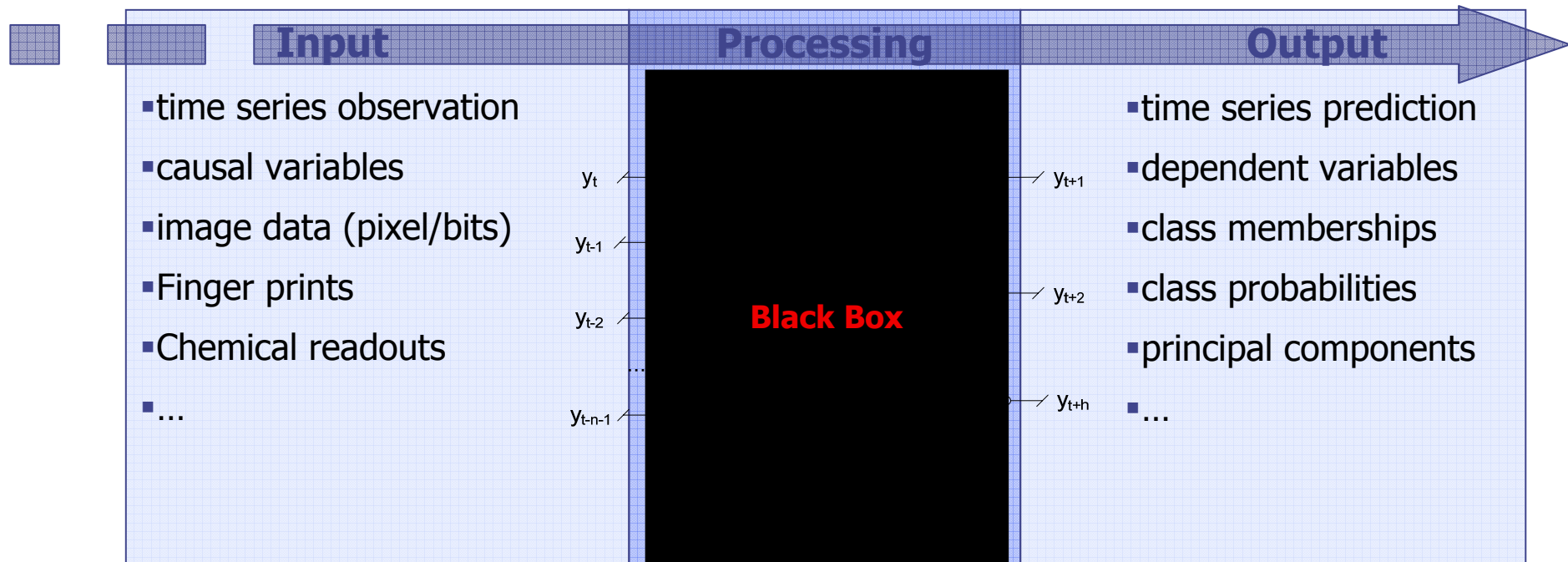
Agenda

Forecasting with Artificial Neural Networks

1. Forecasting?
2. Neural Networks?
 1. What are NN? Definition & Online Preview ...
 2. Motivation & brief history of Neural Networks
 3. From biological to artificial Neural Network Structures
 4. Network Training
3. Forecasting with Neural Networks ...
4. How to write a good Neural Network forecasting paper!

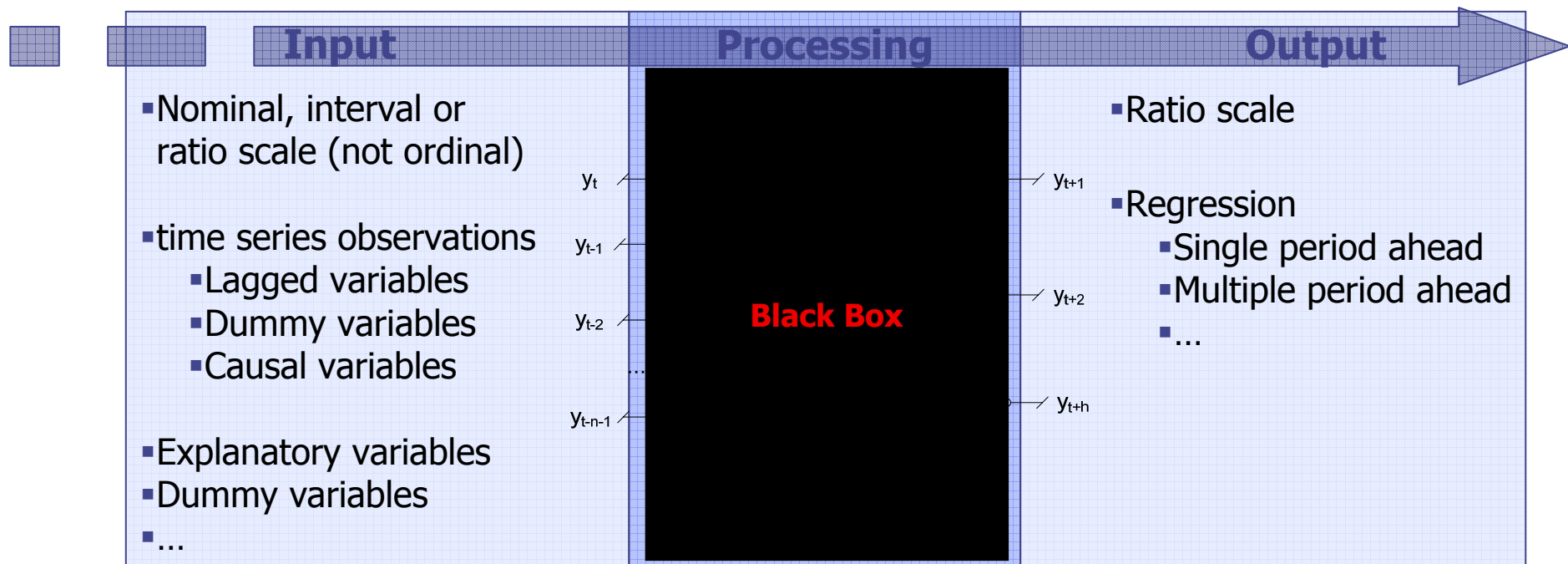
What are Artificial Neural Networks?

- Artificial Neural Networks (NN)
 - „a machine that is designed to *model* the way in which the brain performs a particular task ...; the network is ... implemented ... or .. simulated in software on a digital computer.“ [Haykin98]
 - class of statistical methods for information processing consisting of large number of simple processing units (neurons), which exchange information of their activation via directed connections. [Zell97]



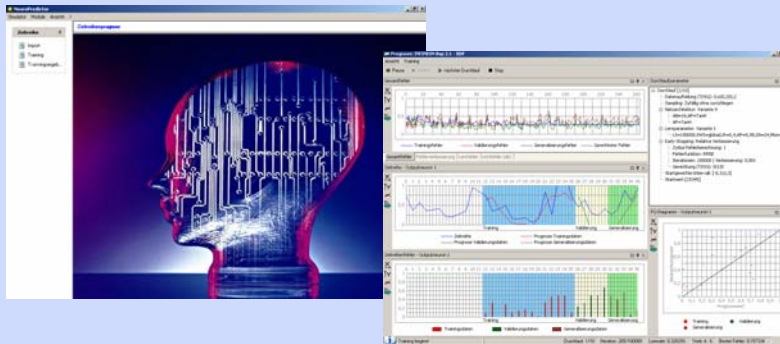
What are Neural Networks in Forecasting?

- Artificial Neural Networks (NN) → a flexible forecasting paradigm
 - A class of statistical methods for time-series and causal forecasting
 - Highly flexible processing → arbitrary input to output relationships
 - Properties → non-linear, nonparametric (assumed), error robust (not outlier!)
 - Data driven modelling → "learning" directly from data



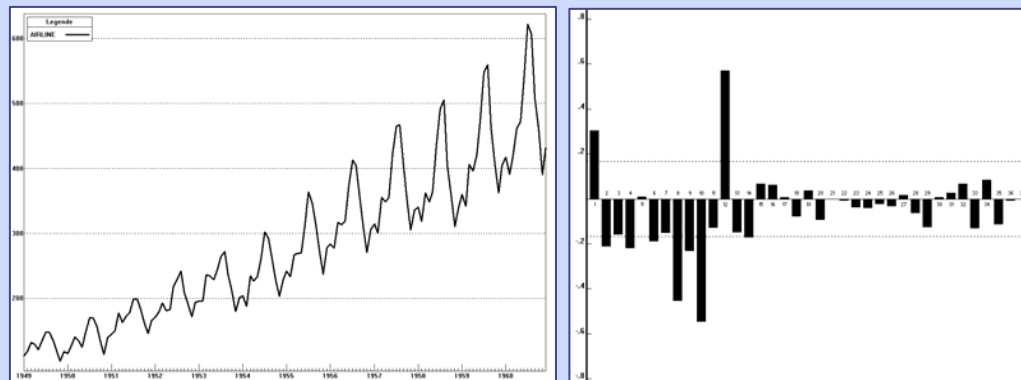
DEMO: Preview of Neural Network Forecasting

Simulation of NN for Business Forecasting



Airline Passenger Data Experiment

- 3 layered NN: (12-8-1) 12 Input units - 8 hidden units – 1 output unit
- 12 input lags $t, t-1, \dots, t-11$ (past 12 observations) \rightarrow time series prediction
- $t+1$ forecast \rightarrow single step ahead forecast



\rightarrow **Benchmark Time Series**
[Brown / Box&Jenkins]

- **132 observations**
- **13 periods of monthly data**

Demonstration: Preview of Neural Network Forecasting

- NeuraLab Predict! → „look inside neural forecasting“

The screenshot displays the NeuraLab Predict! software interface for an 'Airline Demo'. The main window shows training progress with a 'Gesamtfehler' (Total Error) plot. The plot shows training error (blue), validation error (red), and generalization error (green) over 1200 iterations. A red box highlights this plot with the text 'Errors on training / validation / test dataset'.

Below the error plot is a 'Time Series versus Neural Network Forecast' plot. It shows the time series (blue line) and the neural network forecast (red line) over 130 time steps. The plot is divided into three regions: Training (blue background, 0-80), Validation (yellow background, 80-110), and Generalization (green background, 110-130). A red box highlights this plot with the text 'Time Series versus Neural Network Forecast' and '→ updated after each learning step'. Below the plot, it says 'in sample observations & forecasts ←→ validate' and 'out of sample = Test'.

At the bottom is an 'Absolute Forecasting Errors' plot, showing the absolute error (red bars) over 130 time steps. A red box highlights this plot with the text 'Absolute Forecasting Errors'.

On the right side, there is a 'Durchlaufparameter' (Run Parameters) window showing the configuration for the neural network, including the network architecture (AN=13; AF=TanH), learning parameters (LS=30000; SWS=global; LR=0,6; AF=0,995; ZA=80; Mom=0,05), and the error function (RMSE).

At the bottom right, there is a 'PQ-Diagramm - Output neuron 1' (PQ-Diagram - Output neuron 1) showing a scatter plot of predicted values versus actual values. The plot shows a strong positive correlation between predicted and actual values. A red box highlights this plot with the text 'PQ-Diagramm' and 'NN forecasted value'.

The status bar at the bottom shows the current iteration (1297/30000), learning rate (0.553753), and best error (0.025200).

Agenda

Forecasting with Artificial Neural Networks

1. Forecasting?
2. Neural Networks?
 1. What are NN? Definition & Online Preview ...
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 3. From biological to artificial Neural Network Structures
 4. Network Training
3. Forecasting with Neural Networks ...
4. How to write a good Neural Network forecasting paper!

Motivation for using NN ... BIOLOGY!

- Human & other nervous systems (animals, insects → e.g. bats)
 - Ability of various complex functions: perception, motor control, pattern recognition, classification, prediction etc.
 - Speed: e.g. detect & recognize changed face in crowd=100-200ms
 - Efficiency etc.

→ brains are the most efficient & complex computer known to date

| | Human Brain | Computer (PCs) |
|---------------------|-----------------------------------|----------------------------|
| Processing Speed | 10^{-3} ms (0.25 MHz) | 10^{-9} ms (2500 MHz PC) |
| Neurons/Transistors | 10 billion & 10^3 billion conn. | 50 million (PC chip) |
| Weight | 1500 grams | kilograms to tons! |
| Energy consumption | 10^{-16} Joule | 10^{-6} Joule |
| Computation: Vision | 100 steps | billions of steps |

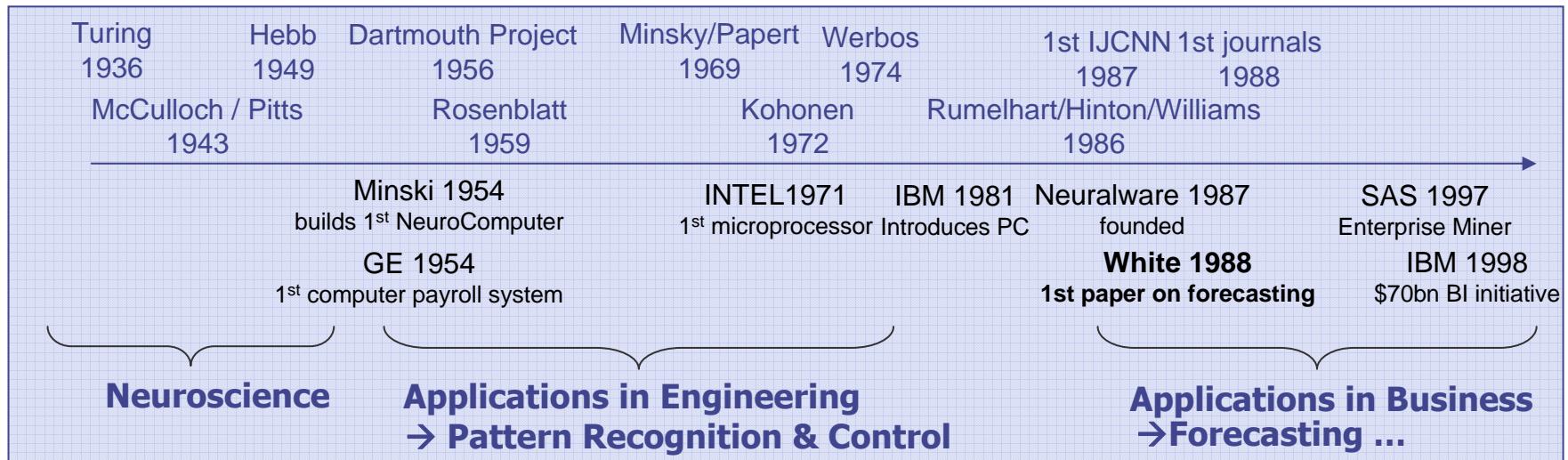
→ Comparison: Human = 10.000.000.000 → ant 20.000 neurons

Brief History of Neural Networks

History

- Developed in interdisciplinary Research (McCulloch/Pitts1943)
- Motivation from Functions of natural Neural Networks
 - ↳ neurobiological motivation
 - ↳ application-oriented motivation

[Smith & Gupta, 2000]



↳ Research field of Soft-Computing & Artificial Intelligence

↳ Neuroscience, Mathematics, Physics, Statistics, Information Science, Engineering, Business Management

↳ different VOCABULARY: statistics versus neurophysiology !!!

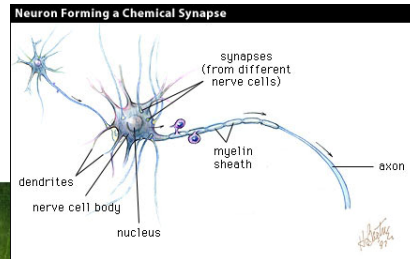
Agenda

Forecasting with Artificial Neural Networks

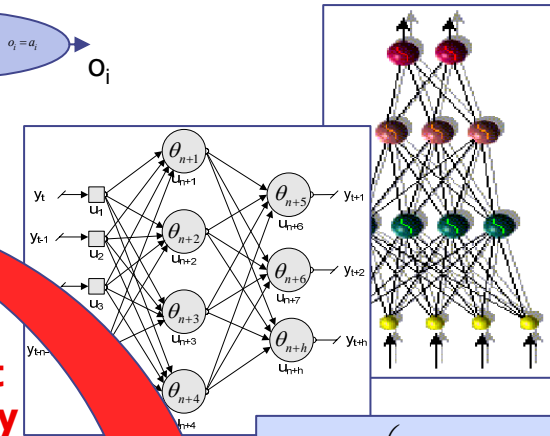
1. Forecasting?
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Motivation & Implementation of Neural Networks

- From biological neural networks ... to artificial neural networks



$$O_i = \sum_j W_{i,j} o_j - \theta_i, \quad a_i = f(\text{net}_i), \quad o_i = a_i$$



Mathematics as abstract representations of reality

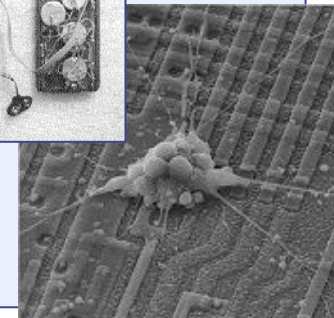
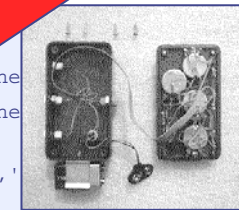
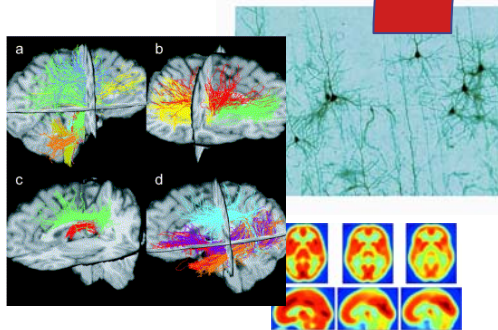
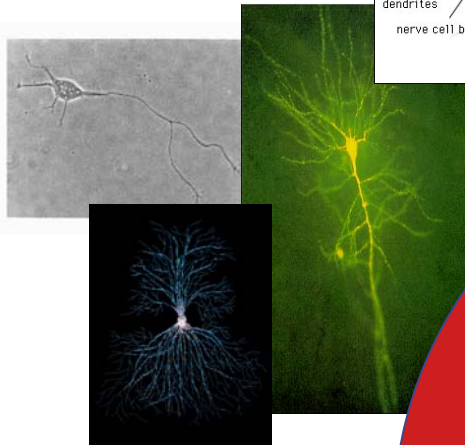
→ use in software simulators, hardware, engineering etc.

$$o_i = \tanh \left(\sum_j w_{ji} o_j - \theta_i \right)$$

```

neural_net = eval(net_name)
[num_rows, ins] = size(neural_net)
[outs, num_cols] = size(neural_net, neural_net.numLayers-1);
if (strcmp(neural_net.adaptFcn, '
net_type = 'RBF';
else net_type = 'MLP';
end

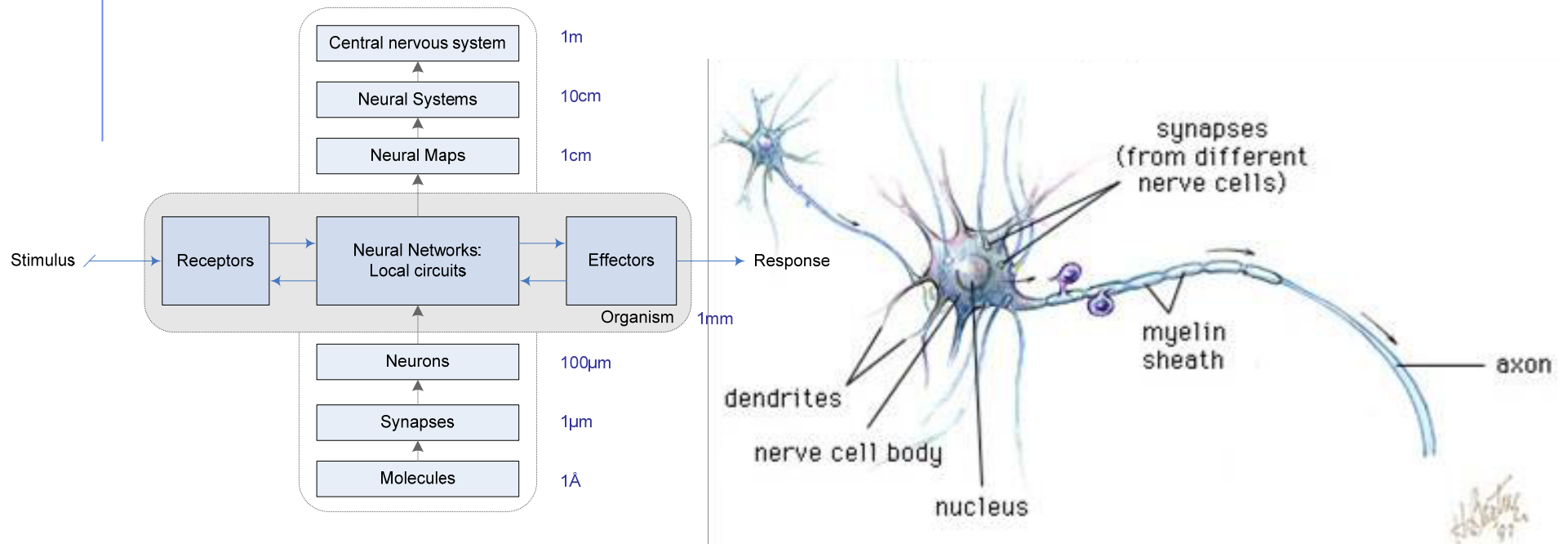
fid = fopen(path, 'w');
    
```



Information Processing in biological Neurons

■ Modelling of biological functions in Neurons

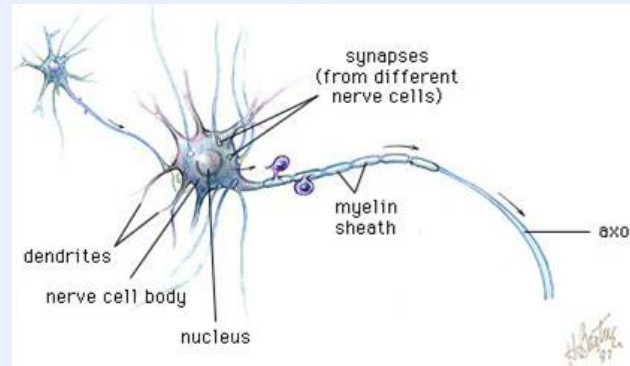
- 10-100 Billion Neurons with 10000 connections in Brain
- Input (sensory), Processing (internal) & Output (motoric) Neurons



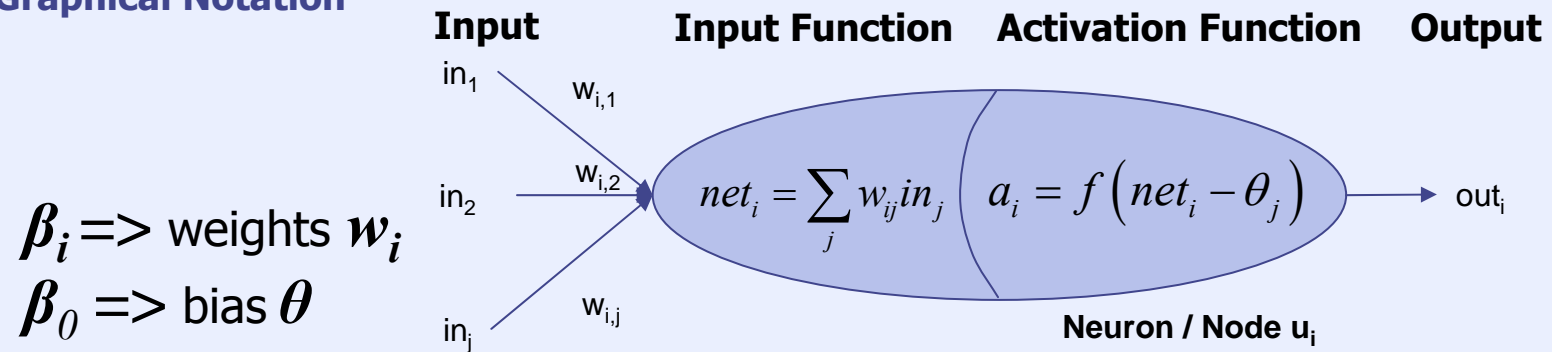
- **CONCEPT of Information Processing in Neurons ...**

Alternative notations – Information processing in neurons / nodes

Biological Representation



Graphical Notation



Mathematical Representation

$$y_i = \begin{cases} 1 & \text{if } \sum_j w_{ji} x_j - \theta_i \geq 0 \\ 0 & \text{if } \sum_j w_{ji} x_j - \theta_i < 0 \end{cases}$$

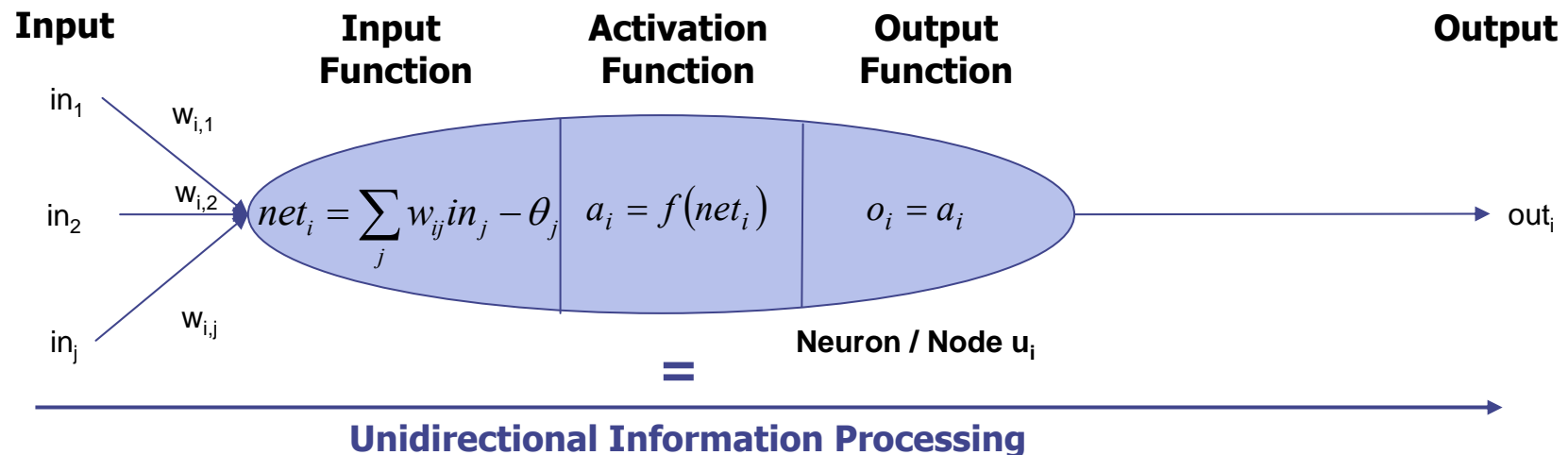
alternative:

$$y_i = \tanh \left(\sum_j w_{ji} x_j - \theta_i \right) \dots$$

Information Processing in artificial Nodes

■ CONCEPT of Information Processing in Neurons

- Input Function (Summation of previous signals)
- Activation Function (nonlinear)
 - binary step function $\{0;1\}$
 - sigmoid function: logistic, hyperbolic tangent etc.
- Output Function (linear / Identity, SoftMax ...)



$$out_i = \begin{cases} 1 & \text{if } \sum_j w_{ji} o_j - \theta_i \geq 0 \\ 0 & \text{if } \sum_j w_{ji} o_j - \theta_i < 0 \end{cases}$$

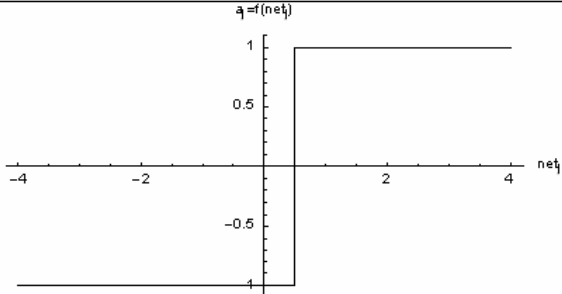
Input Functions

| Input Function | Formula |
|----------------|-----------------------------|
| Sum | $net_j = \sum_i o_i w_{ij}$ |

Binary Activation Functions

- Binary activation calculated from input

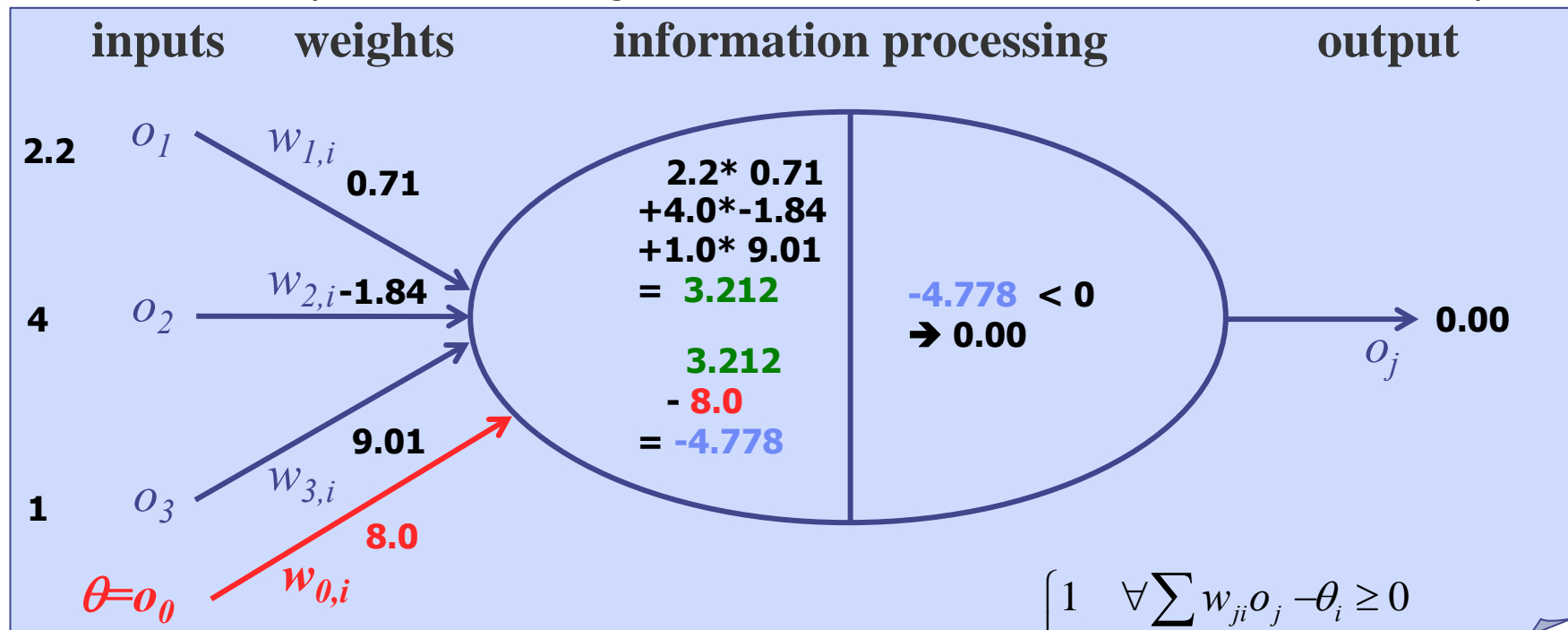
$$a_j = f_{act}(net_j, \theta_j) \quad \text{e.g.} \quad a_j = f_{act}(net_j - \theta_j)$$

| Activation Function $a_i = f(net_i)$ | Activation State a_i |
|--|---|
|  <p style="text-align: center;">Binary Stepfunction / Threshold Function</p> | <p style="text-align: center;">Binary</p> $a_j = \begin{cases} 1 & \forall net_j \geq \theta_j \\ 0 & \forall net_j < \theta_j \end{cases}$ $a_j = \text{sgn}(net_j)$ |

Information Processing: Node Threshold logic

Node Function → BINARY THRESHOLD LOGIC

1. weight individual input by connection strength
2. sum weighted inputs
3. add bias term
4. calculate output of node through BINARY transfer function → RERUN with next input

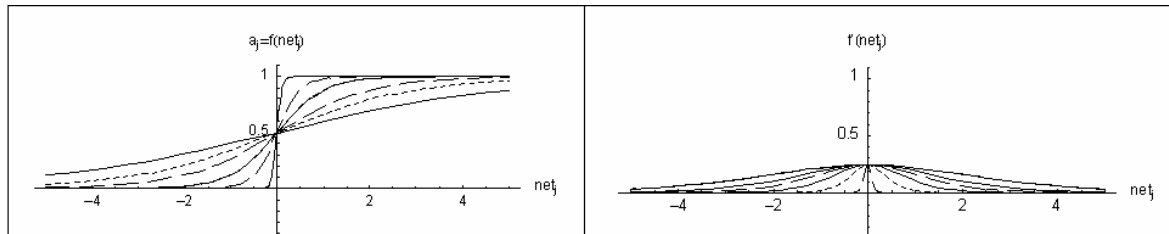


$$\Rightarrow net_i = \sum_j w_{ij} o_j - \theta_j \Rightarrow a_i = f(net_i) \Rightarrow o_i = \begin{cases} 1 & \forall \sum_j w_{ji} o_j - \theta_i \geq 0 \\ 0 & \sum_j w_{ji} o_j - \theta_i < 0 \end{cases}$$

Continuous Activation Functions

- Activation calculated from input

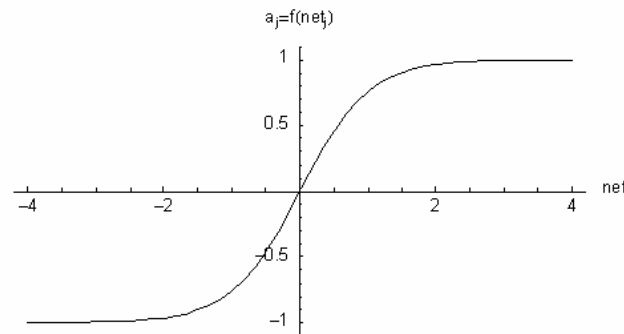
$$a_j = f_{act}(net_j, \theta_j) \quad \text{e.g.} \quad a_j = f_{act}(net_j - \theta_j)$$



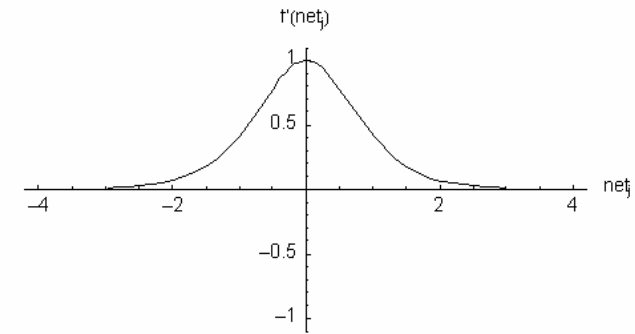
Hyperbolic Tangent

Logistic Function

$$f_{act}(net_j) = \frac{1}{1 + e^{-net_j}}$$



$$f_{act}(net_j) = \tanh(net_j) = \frac{e^{net_j} - e^{-net_j}}{e^{net_j} + e^{-net_j}}$$



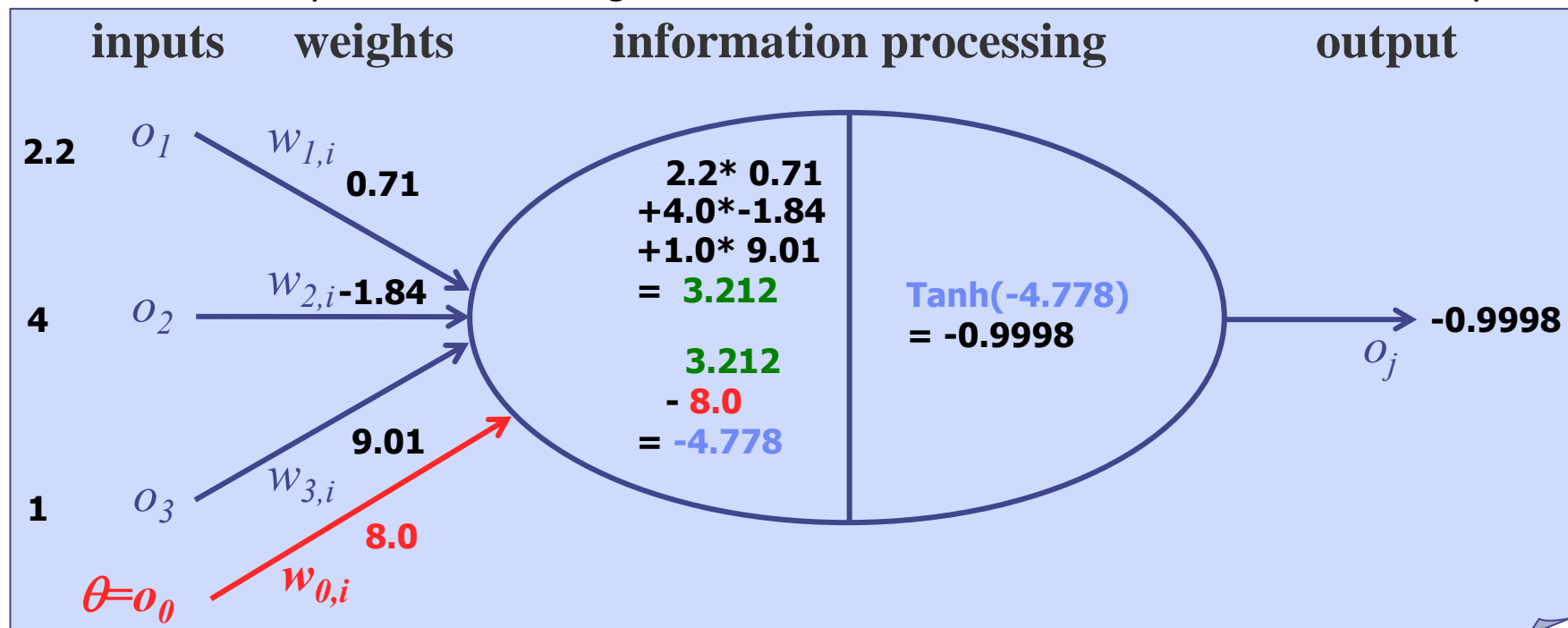
$$f'_{act}(net_j) = \frac{df_{act}(net_j)}{dnet_j} = 1 - \tanh^2(net_j)$$

$$= \frac{(e^{net_j} + e^{-net_j})^2 - (e^{net_j} - e^{-net_j})^2}{(e^{net_j} + e^{-net_j})^2}$$

Information Processing: Node Threshold logic

Node Function → Sigmoid THRESHOLD LOGIC of TanH activation function

1. weight individual input by connection strength
2. sum weighted inputs
3. add bias term
4. calculate output of node through BINARY transfer function → RERUN with next input



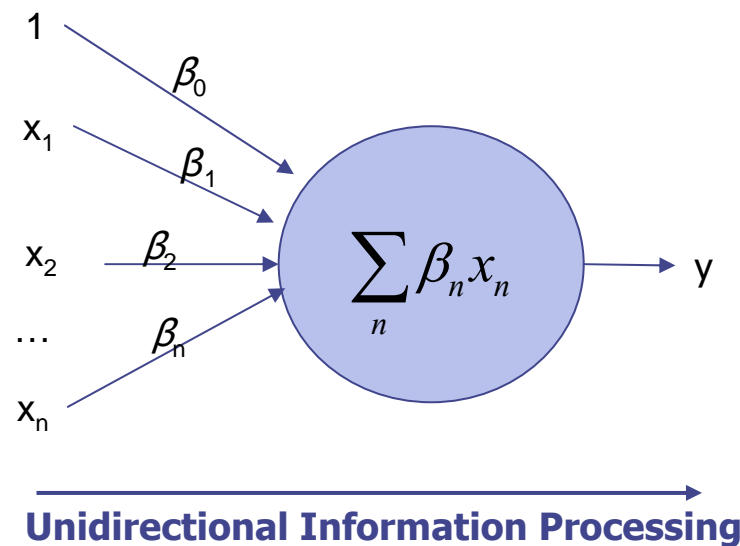
$$\Rightarrow net_i = \sum_j w_{ij} o_j - \theta_j \Rightarrow a_i = f(net_i) \Rightarrow o_i = \tanh\left(\sum_j w_{ji} o_j - \theta_i\right)$$

A new Notation ... GRAPHICS!

- Single Linear Regression ... as an equation:

$$y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \dots + \beta_n x_n + \varepsilon$$

- Single Linear Regression ... as a directed graph:



Why Graphical Notation?

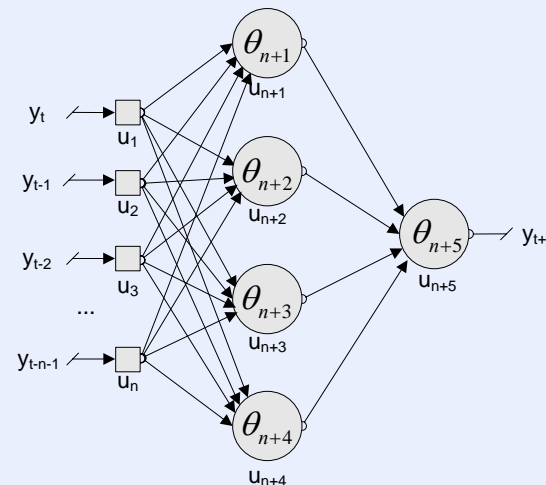
- Simple neural network equation without recurrent feedbacks:

$$y_k = \tanh \left(\sum_k w_{kj} \tanh \left(\sum_i w_{ki} \tanh \left(\sum_j w_{ji} x_j - \theta_j \right) - \theta_i \right) - \theta_k \right) \Rightarrow \text{Min!}$$

□ with ... $\beta_i \Rightarrow w_i$
 $\beta_0 \Rightarrow \theta$

$$\tanh \left(\left(\sum_{i=1}^N x_i w_{ij} \right) - \theta_j \right) = \frac{\left(e^{\left(\sum_{i=1}^N x_i w_{ij} \right) - \theta_j} - e^{-\left(\sum_{i=1}^N x_i w_{ij} \right) - \theta_j} \right)^2}{\left(e^{\left(\sum_{i=1}^N x_i w_{ij} \right) - \theta_j} + e^{-\left(\sum_{i=1}^N x_i w_{ij} \right) - \theta_j} \right)^2}$$

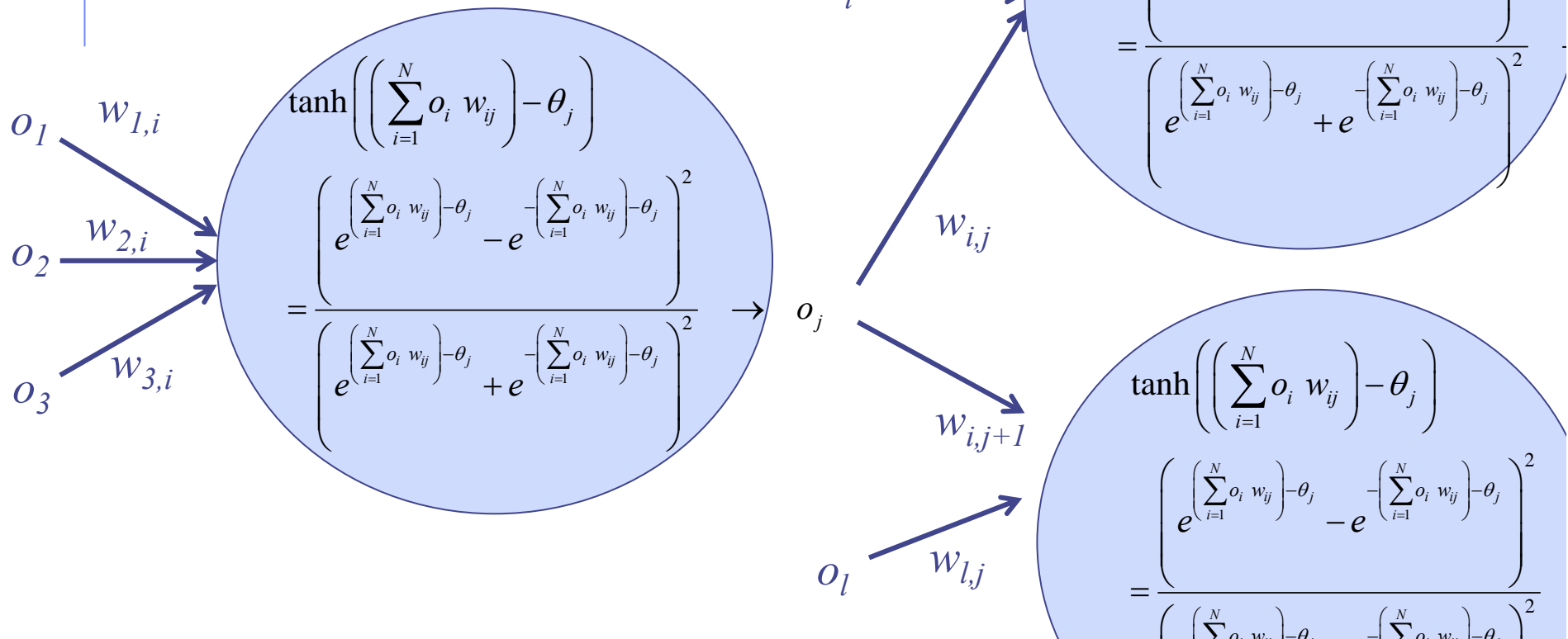
- Also:



→ Simplification
for complex models!

Combination of Nodes

- "Simple" processing per node
- Combination of simple nodes creates complex behaviour
- ...

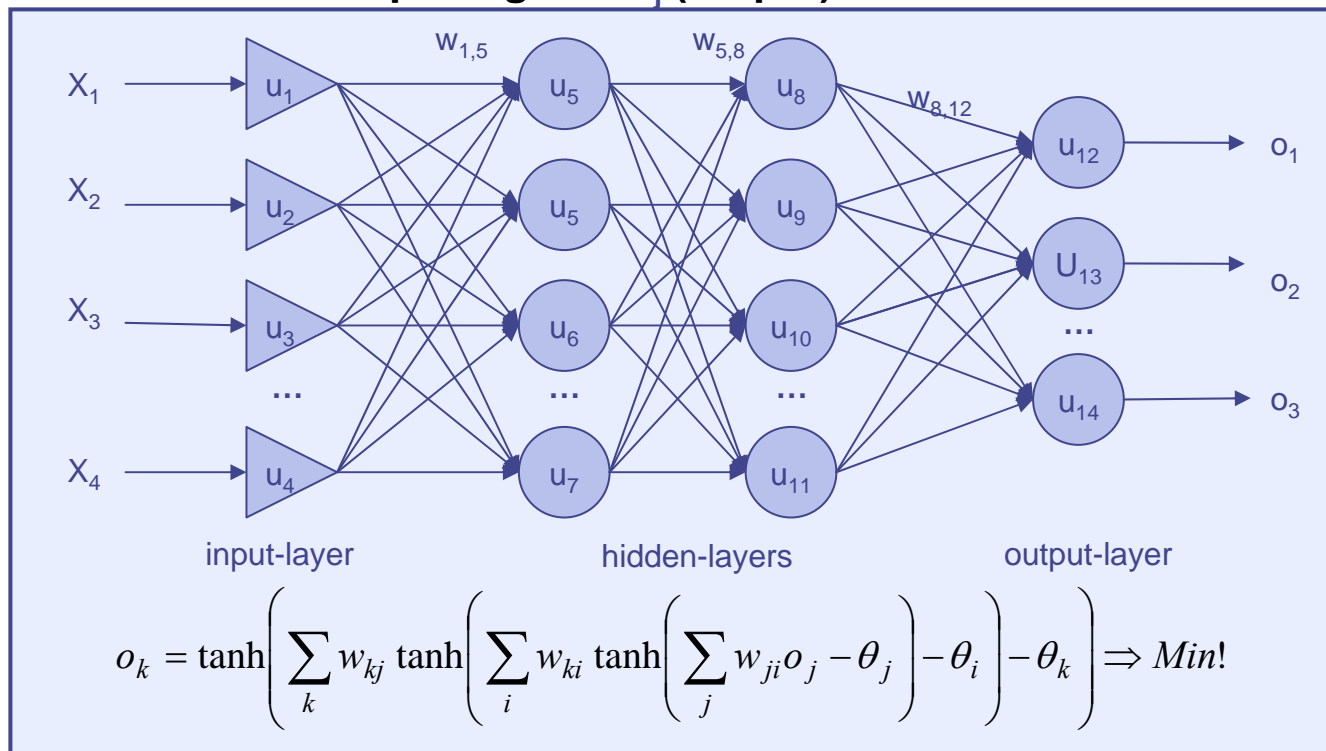


Architecture of Multilayer Perceptrons

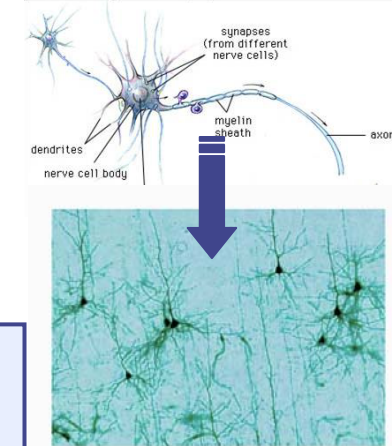
■ Architecture of a Multilayer Perceptron

→ Classic form of feed forward neural network!

- Neurons u_n (units / nodes) ordered in Layers
- unidirectional connections with trainable weights $w_{n,n}$
- Vector of input signals x_i (input)
- Vector of output signals o_j (output)



Combination of neurons



= neural network

Dictionary for Neural Network Terminology

- Due to its neuro-biological origins, NN use specific terminology

| Neural Networks | Statistics |
|-----------------|--------------------------------|
| Input Nodes | Independent / lagged Variables |
| Output Node(s) | Dependent variable(s) |
| Training | Parameterization |
| Weights | Parameters |
| ... | ... |

→ don't be confused: ASK!

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4. How to write a good Neural Network forecasting paper!

Hebbian Learning

- HEBB introduced idea of learning by adapting weights [0,1]

$$\Delta w_{ij} = \eta o_i a_j$$

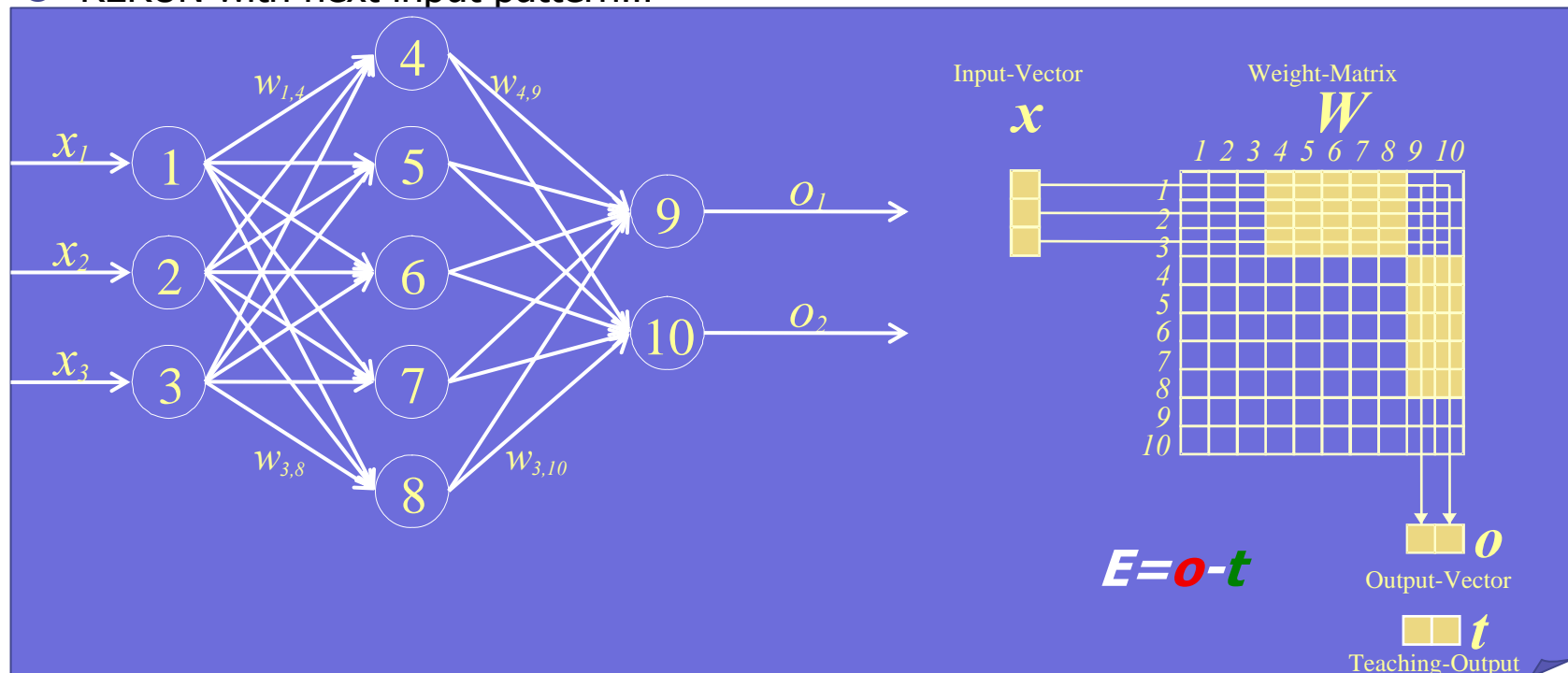
- Delta-learning rule of Widrow-Hoff

$$\begin{aligned}\Delta w_{ij} &= \eta o_i (t_j - a_j) \\ &= \eta o_i (t_j - o_j) = \eta o_i \delta_j\end{aligned}$$

Neural Network Training with Back-Propagation

Training → LEARNING FROM EXAMPLES

1. Initialize connections with randomized weights (symmetry breaking)
 2. Show first Input-Pattern (independent Variables) (demo only for 1 node!)
 3. Forward-Propagation of input values unto output layer
 4. Calculate error between NN output & actual value (using error / objective function)
 5. Backward-Propagation of errors for each weight unto input layer
- ➔ RERUN with next input pattern...



Neural Network Training

- Simple back propagation algorithm [Rumelhart et al. 1982]

$$E_p = C(t_{pj}, o_{pj}) \quad o_{pj} = f_j(\text{net}_{pj}) \quad \Delta_p w_{ji} \propto -\frac{\partial C(t_{pj}, o_{pj})}{\partial w_{ji}}$$

$$\frac{\partial C(t_{pj}, o_{pj})}{\partial w_{ji}} = \frac{\partial C(t_{pj}, o_{pj})}{\partial \text{net}_{pj}} \frac{\partial \text{net}_{pj}}{\partial w_{ji}}$$

$$\delta_{pj} = -\frac{\partial C(t_{pj}, o_{pj})}{\partial \text{net}_{pj}}$$


$$\delta_{pj} = -\frac{\partial C(t_{pj}, o_{pj})}{\partial \text{net}_{pj}} = \frac{\partial C(t_{pj}, o_{pj})}{\partial o_{pj}} \frac{\partial o_{pj}}{\partial \text{net}_{pj}}$$

$$\frac{\partial o_{pj}}{\partial \text{net}_{pj}} = f'_j(\text{net}_{pj})$$

$$\delta_{pj} = \frac{\partial C(t_{pj}, o_{pj})}{\partial o_{pj}} f'_j(\text{net}_{pj})$$

$$\begin{aligned} \sum_k \frac{\partial C(t_{pj}, o_{pj})}{\partial \text{net}_{pk}} \frac{\partial \text{net}_{pk}}{\partial o_{pj}} &= \sum_k \frac{\partial C(t_{pj}, o_{pj})}{\partial \text{net}_{pk}} \frac{\partial \sum_i w_{ki} o_{pi}}{\partial o_{pj}} \\ &= \sum_k \frac{\partial C(t_{pj}, o_{pj})}{\partial \text{net}_{pk}} w_{kj} = -\sum_k \delta_{pk} w_{kj} \end{aligned}$$

$$\delta_{pj} = f'_j(\text{net}_{pj}) \sum_k \delta_{pk} w_{kj}$$



$$\delta_{pj} = \begin{cases} \frac{\partial C(t_{pj}, o_{pj})}{\partial o_{pj}} f'_j(\text{net}_{pj}) & \text{if unit } j \text{ is in the output layer} \\ f'_j(\text{net}_{pj}) \sum_k \delta_{pk} w_{pk} & \text{if unit } j \text{ is in a hidden layer} \end{cases}$$

$$\Delta w_{ij} = \eta o_i \delta_j$$

$$\text{mit } \delta_j = \begin{cases} f'_j(\text{net}_j)(t_j - o_j) & \forall \text{output nodes } j \\ f'_j(\text{net}_j) \sum_k (\delta_k w_{jk}) & \forall \text{hidden nodes } j \end{cases}$$

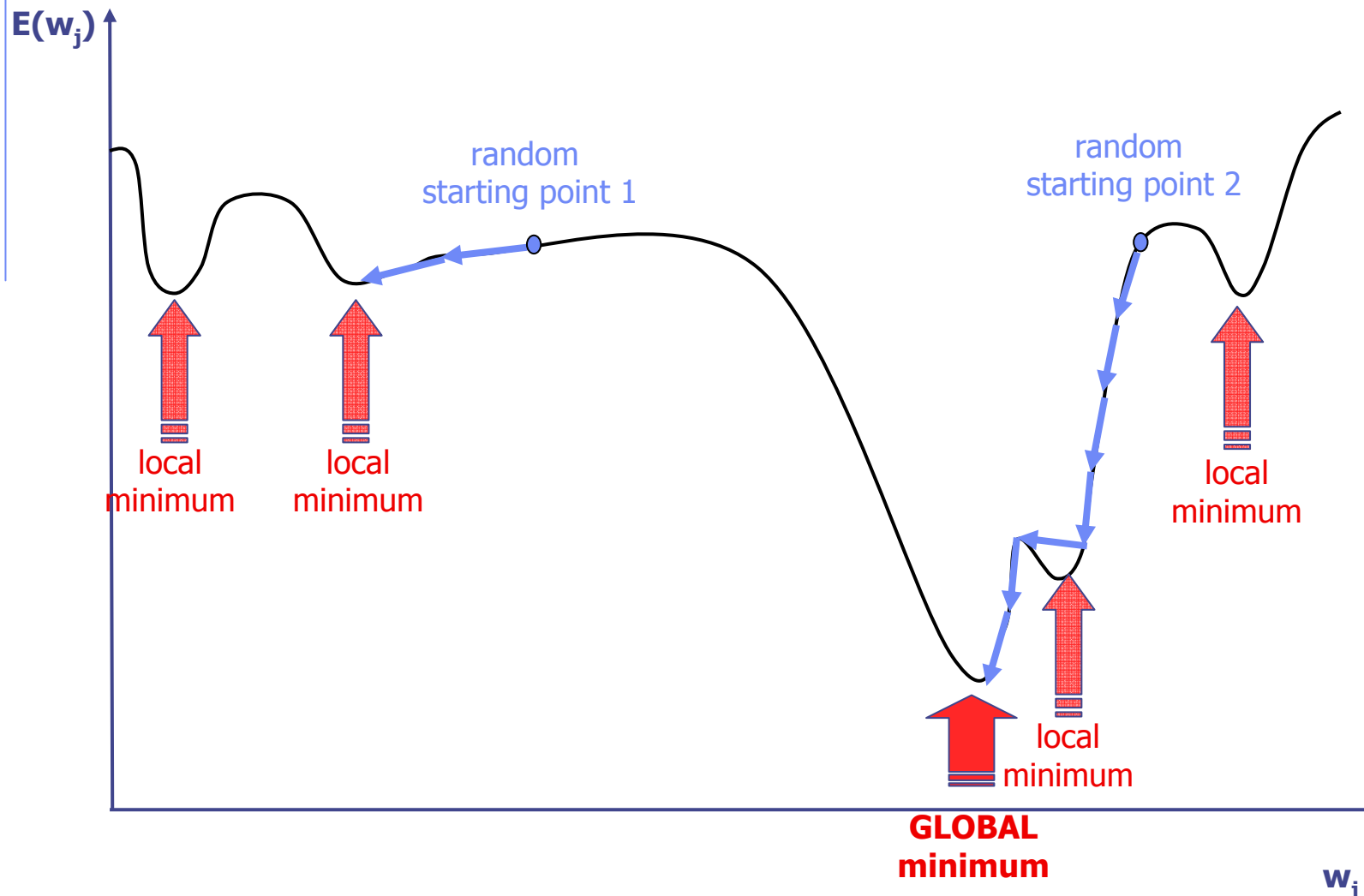
$$\Delta w_{ij} = \eta o_i \delta_j$$

$$\text{mit } f(\text{net}_j) = \frac{1}{1 + e^{-\sum_i o_i(t) w_{ij}}} \rightarrow f'(\text{net}_j) = o_j(1 - o_j)$$

$$\delta_j = \begin{cases} o_j(1 - o_j)(t_j - o_j) & \forall \text{output nodes } j \\ o_j(1 - o_j) \sum_k (\delta_k w_{jk}) & \forall \text{hidden nodes } j \end{cases}$$

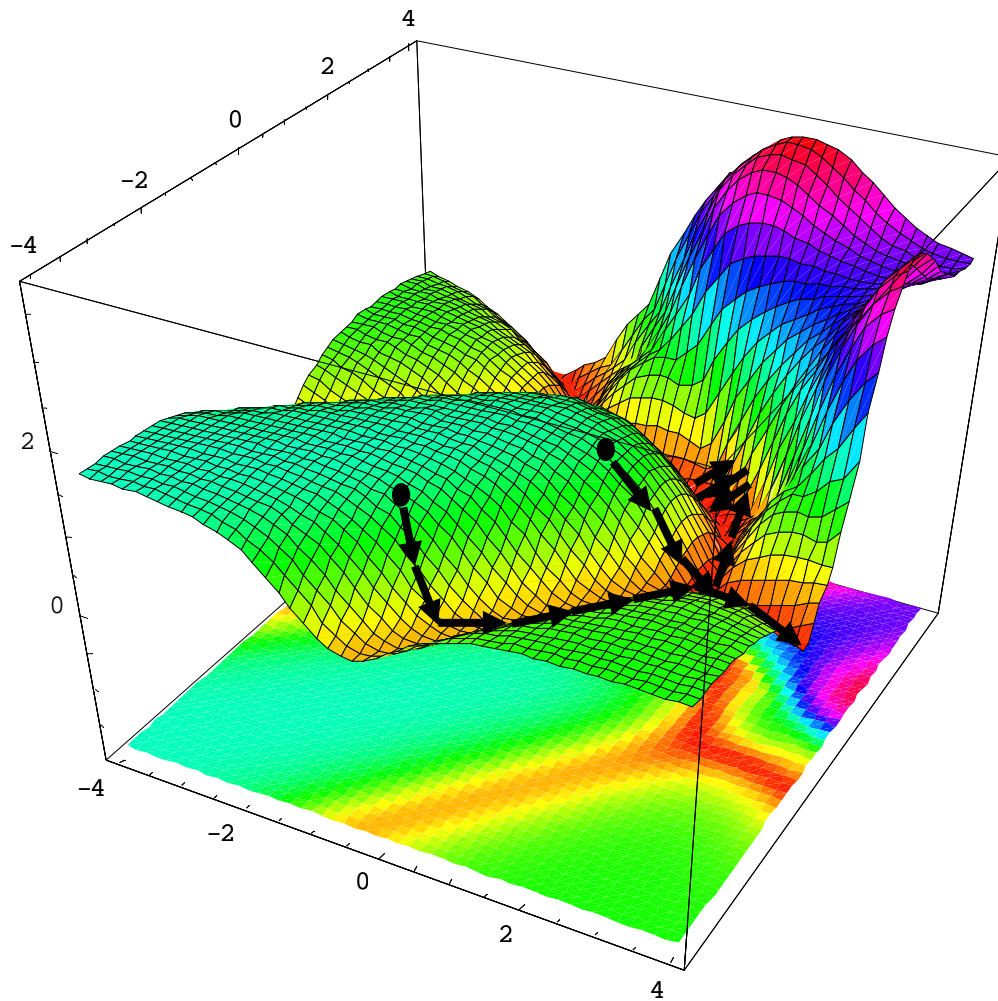
Neural Network Training = Error Minimization

- Minimize Error through changing ONE weight w_j



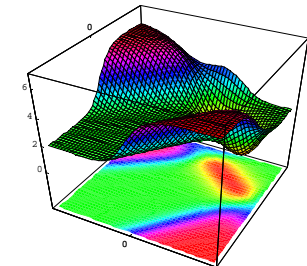
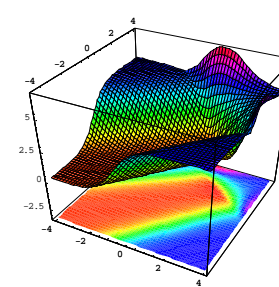
Error Backpropagation = 3D+ Gradient Decent

- Local search on multi-dimensional error surface



- task of finding the deepest valley in mountains
 - local search
 - stepsize fixed
 - follow steepest decent

→ local optimum = any valley
 → global optimum = deepest valley with lowest error
 → varies with error surface



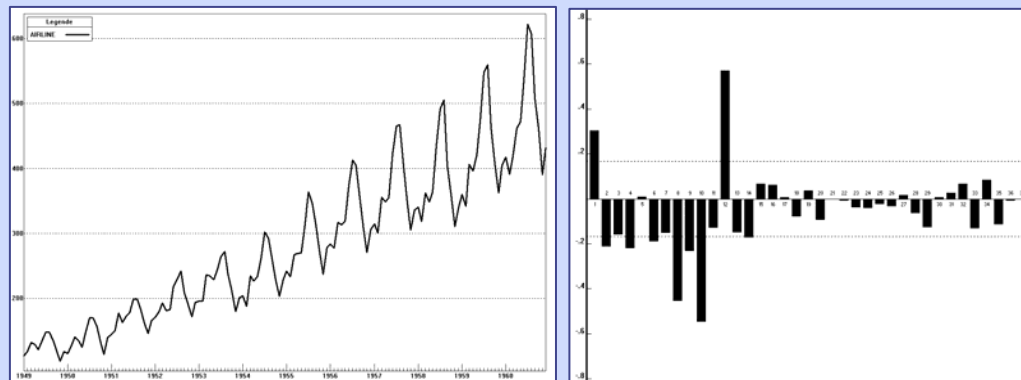
Demo: Neural Network Forecasting revisited!

Simulation of NN for Business Forecasting



Airline Passenger Data Experiment

- 3 layered NN: (12-8-1) 12 Input units - 8 hidden units – 1 output unit
- 12 input lags $t, t-1, \dots, t-11$ (past 12 observations) → time series prediction
- $t+1$ forecast → single step ahead forecast



→ **Benchmark Time Series**
[Brown / Box&Jenkins]

- **132 observations**
- **13 periods of monthly data**

Agenda

Forecasting with Artificial Neural Networks

1. Forecasting?
2. Neural Networks?
3. Forecasting with Neural Networks ...
 1. NN models for Time Series & Dynamic Causal Prediction
 2. NN experiments
 3. Process of NN modelling
4. How to write a good Neural Network forecasting paper!

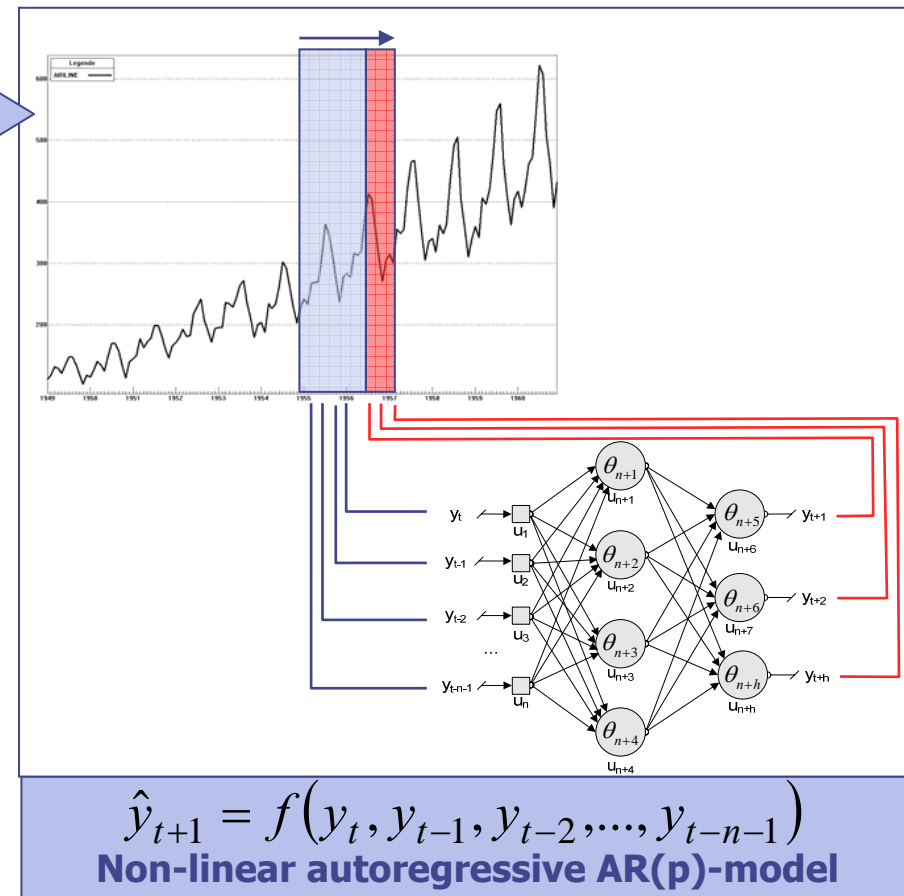
Time Series Prediction with Artificial Neural Networks

- ANN are universal approximators [Hornik/Stichcomb/White92 etc.]
 - ↪ Forecasts as application of (nonlinear) function-approximation
 - ↪ various architectures for prediction (time-series, causal, combined...)

$$\hat{y}_{t+h} = f(x_t) + \varepsilon_{t+h}$$

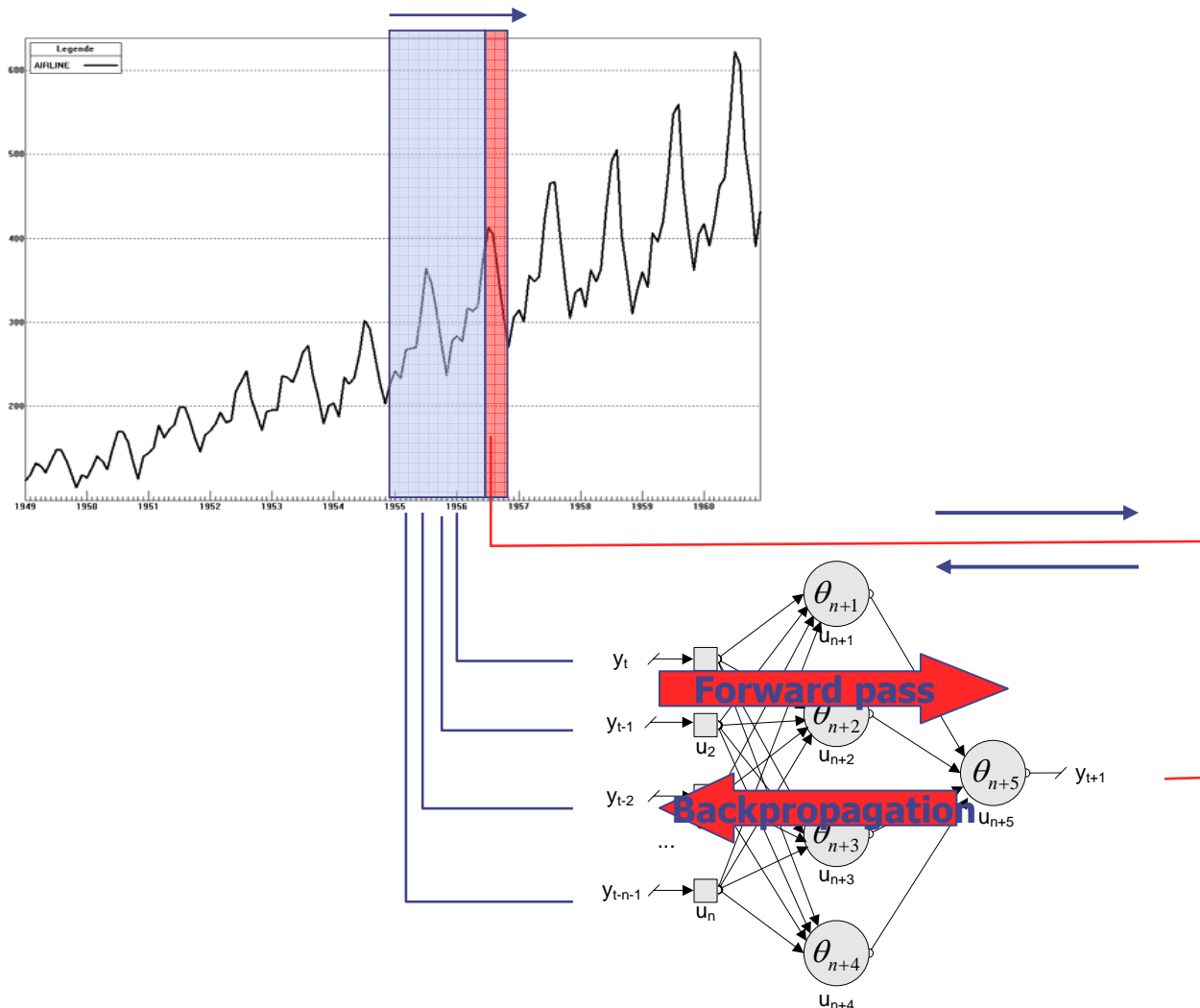
y_{t+h} = forecast for $t+h$
 $f(-)$ = linear / non-linear function
 x_t = vector of observations in t
 ε_{t+h} = independent error term in $t+h$

- ↪ Single neuron / node
 ≈ nonlinear AR(p)
- ↪ Feedforward NN (MLP etc.)
 ≈ hierarchy of nonlinear AR(p)
- ↪ Recurrent NN (Elman, Jordan)
 ≈ nonlinear ARMA(p,q)
- ↪ ...



Neural Network Training on Time Series

- Sliding Window Approach of presenting Data



Input

Present new data pattern to Neural Network

Calculate

Neural Network Output from Input values

Compare

Neural Network Forecast against $\langle \rangle$ actual value

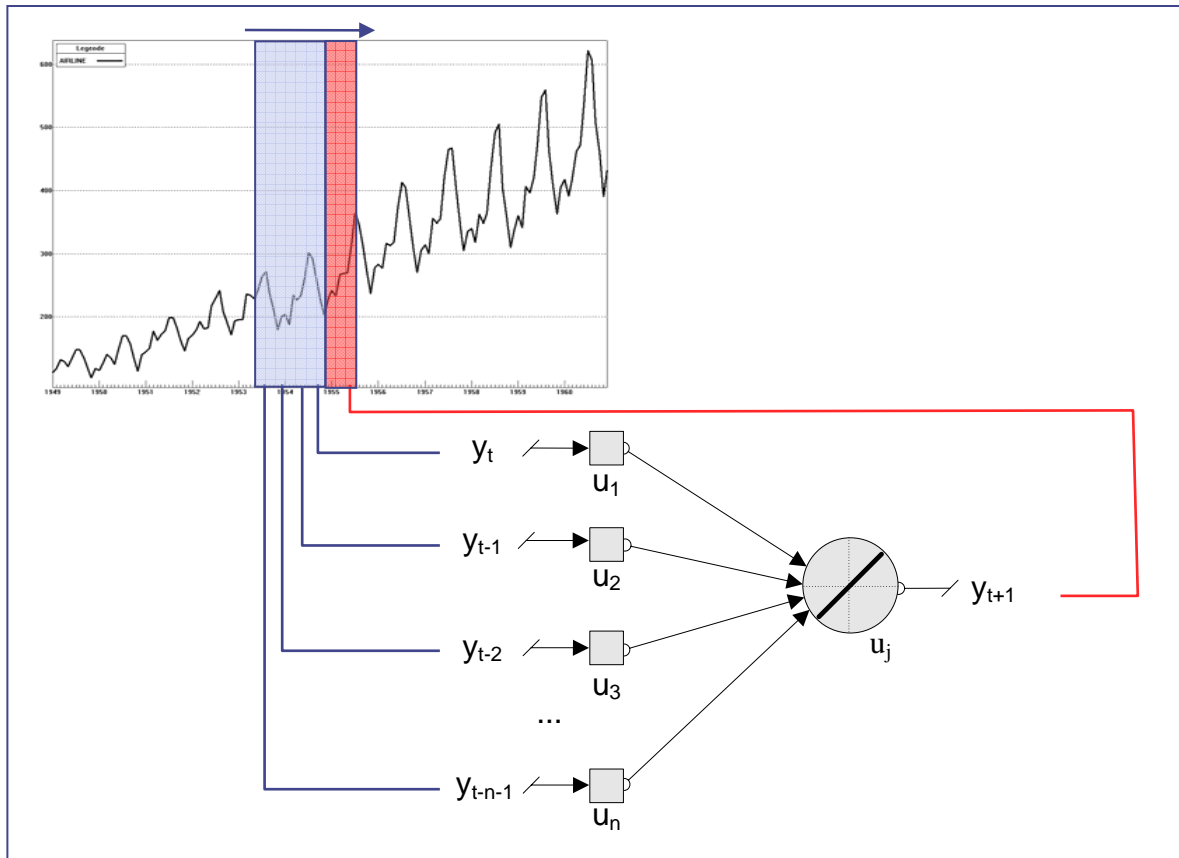
Backpropagation

Change weights to reduce output forecast error

New Data Input

Slide window forward to show next pattern

Neural Network Architectures for Linear Autoregression



→ Interpretation

- weights represent autoregressive terms
- Same problems / shortcomings as standard AR-models!

→ Extensions

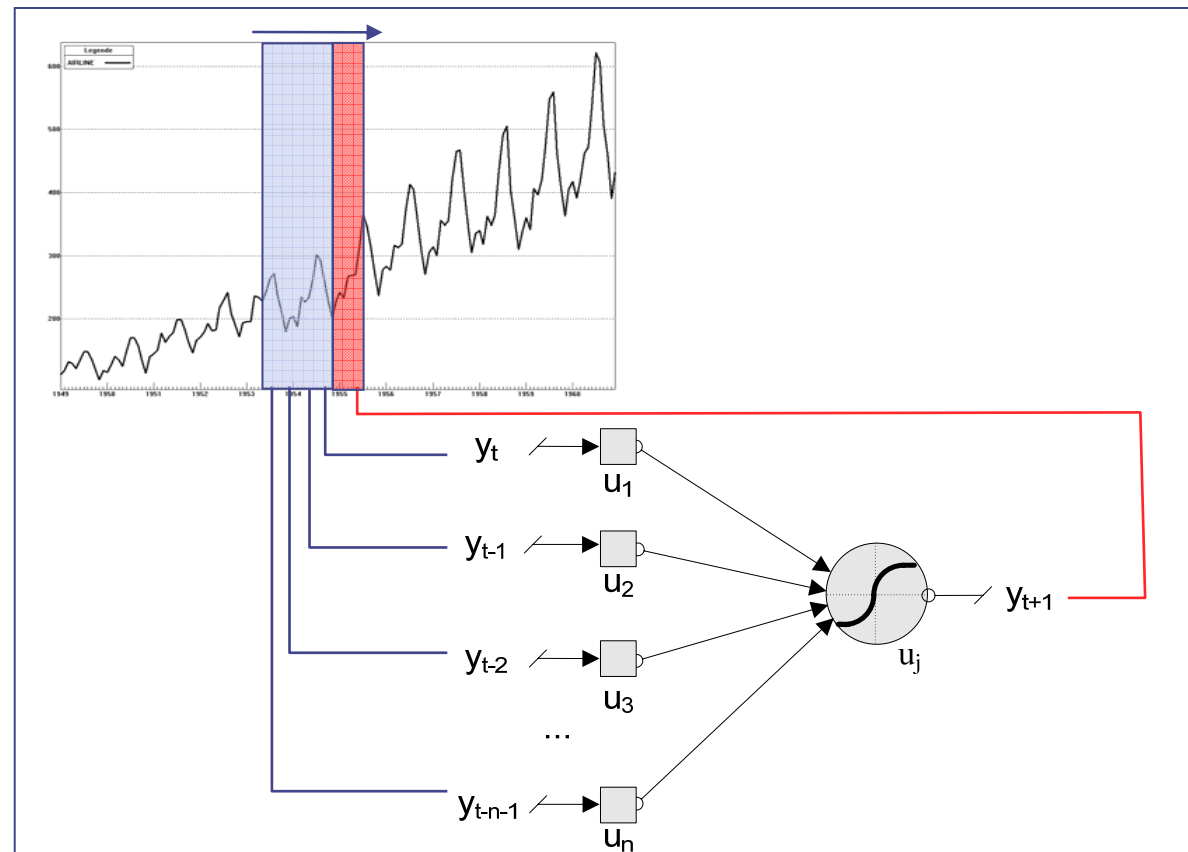
- multiple output nodes = simultaneous autoregression models
- Non-linearity through different activation function in output node

$$\hat{y}_{t+1} = f(y_t, y_{t-1}, y_{t-2}, \dots, y_{t-n-1})$$

$$\hat{y}_{t+1} = y_t w_{tj} + y_{t-1} w_{t-1j} + y_{t-2} w_{t-2j} + \dots + y_{t-n-1} w_{t-n-1j} - \theta_j$$

linear autoregressive AR(p)-model

Neural Network Architecture for Nonlinear Autoregression



$$\hat{y}_{t+1} = f(y_t, y_{t-1}, y_{t-2}, \dots, y_{t-n+1})$$

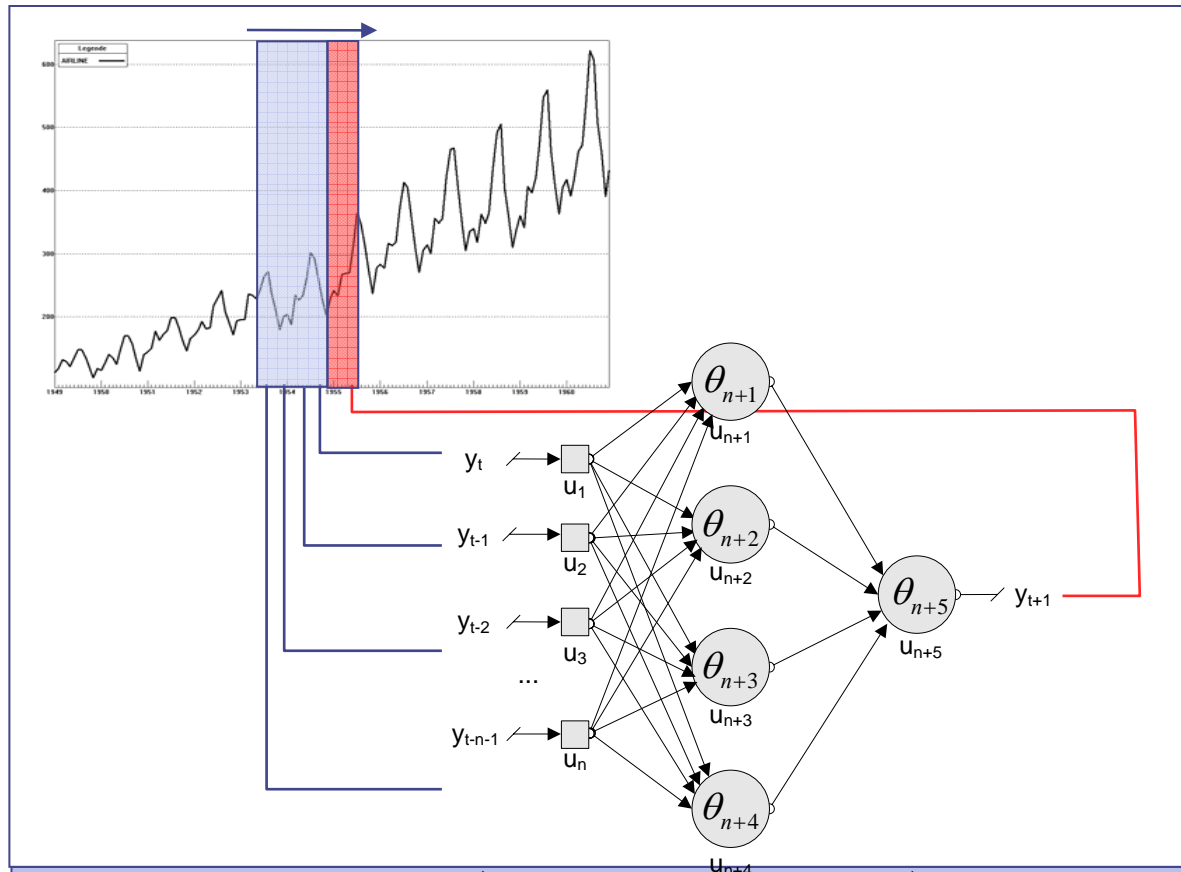
$$\hat{y}_{t+1} = \tanh\left(\sum_{i=t-n+1}^{t-n+1} y_i w_{ij} - \theta_j\right)$$

Nonlinear autoregressive AR(p)-model

→ Extensions

- additional layers with nonlinear nodes
- linear activation function in output layer

Neural Network Architectures for Nonlinear Autoregression



$$\hat{y}_{t+1} = \tanh \left(\sum_k w_{kj} \tanh \left(\sum_i w_{ki} \tanh \left(\sum_j w_{ji} y_{t-j} - \theta_j \right) - \theta_i \right) - \theta_k \right)$$

Nonlinear autoregressive AR(p)-model

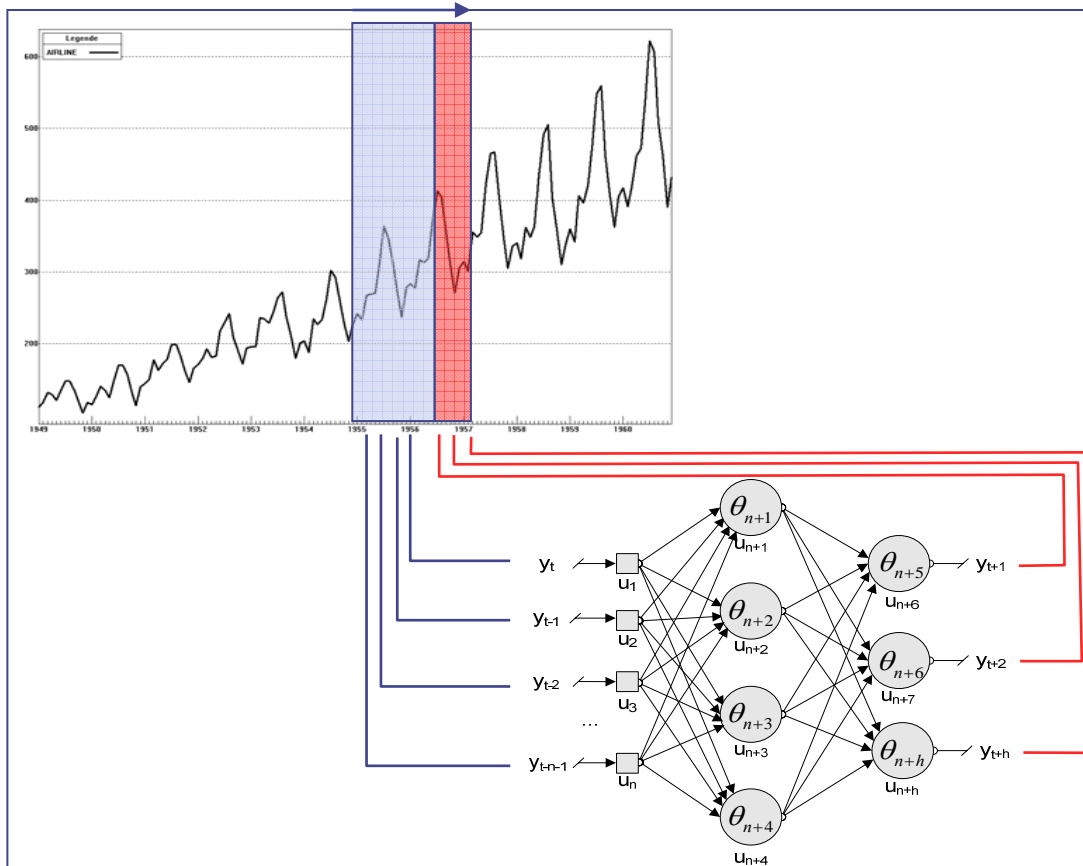
→ Interpretation

- Autoregressive modeling AR(p)-approach **WITHOUT** the moving average terms of errors
≠ nonlinear ARIMA
- Similar problems / shortcomings as standard AR-models!

→ Extensions

- multiple output nodes = simultaneous autoregression models

Neural Network Architectures for Multiple Step Ahead Nonlinear Autoregression



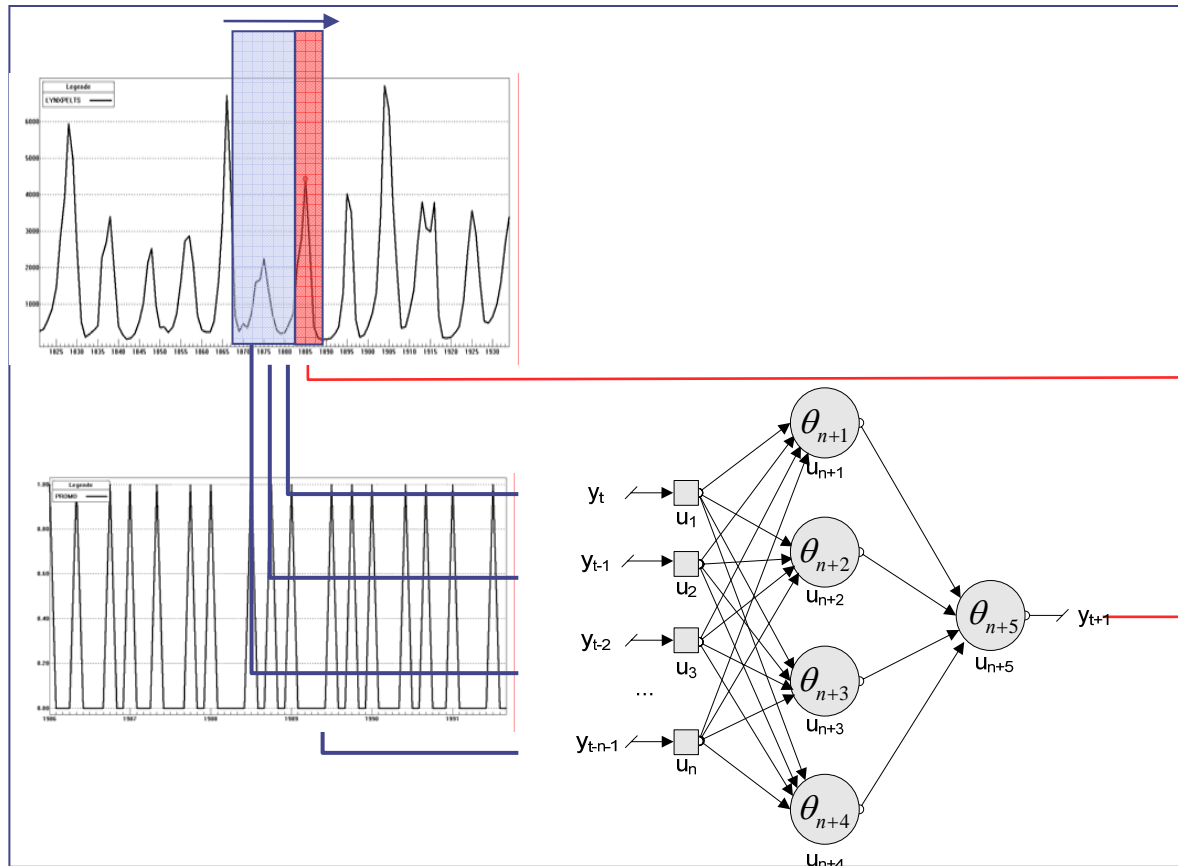
→ Interpretation

- As single Autoregressive modeling AR(p)

$$\hat{y}_{t+1}, \hat{y}_{t+2}, \dots, \hat{y}_{t+n} = f(y_t, y_{t-1}, y_{t-2}, \dots, y_{t-n-1})$$

Nonlinear autoregressive AR(p)-model

Neural Network Architectures for Forecasting - Nonlinear Autoregression Intervention Model



$$\hat{y}_{t+1}, \hat{y}_{t+2}, \dots, \hat{y}_{t+n} = f(y_t, y_{t-1}, y_{t-2}, \dots, y_{t-n-1})$$

Nonlinear autoregressive ARX(p)-model

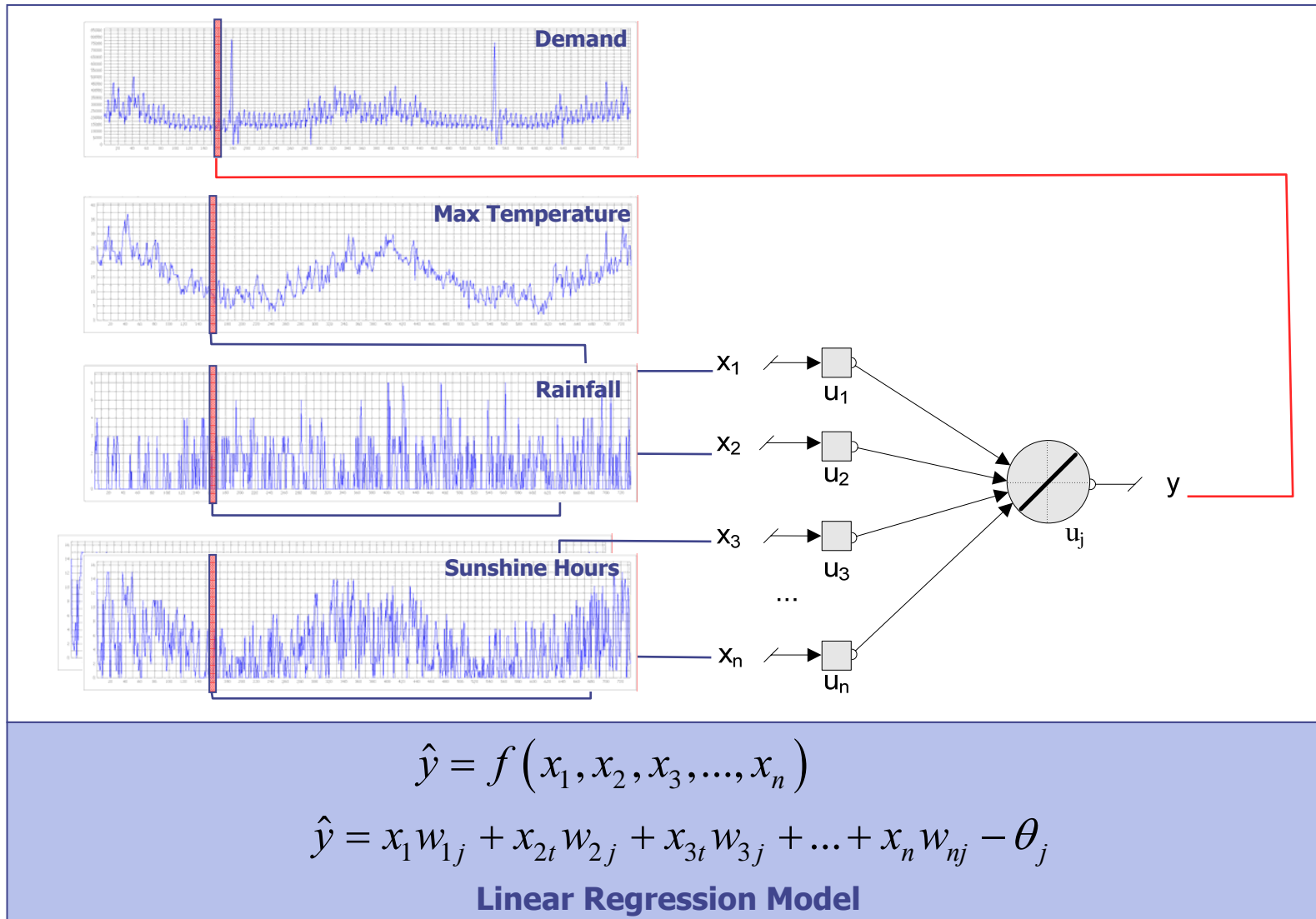
→ Interpretation

- As single Autoregressive modeling AR(p)
- Additional Event term to explain external events

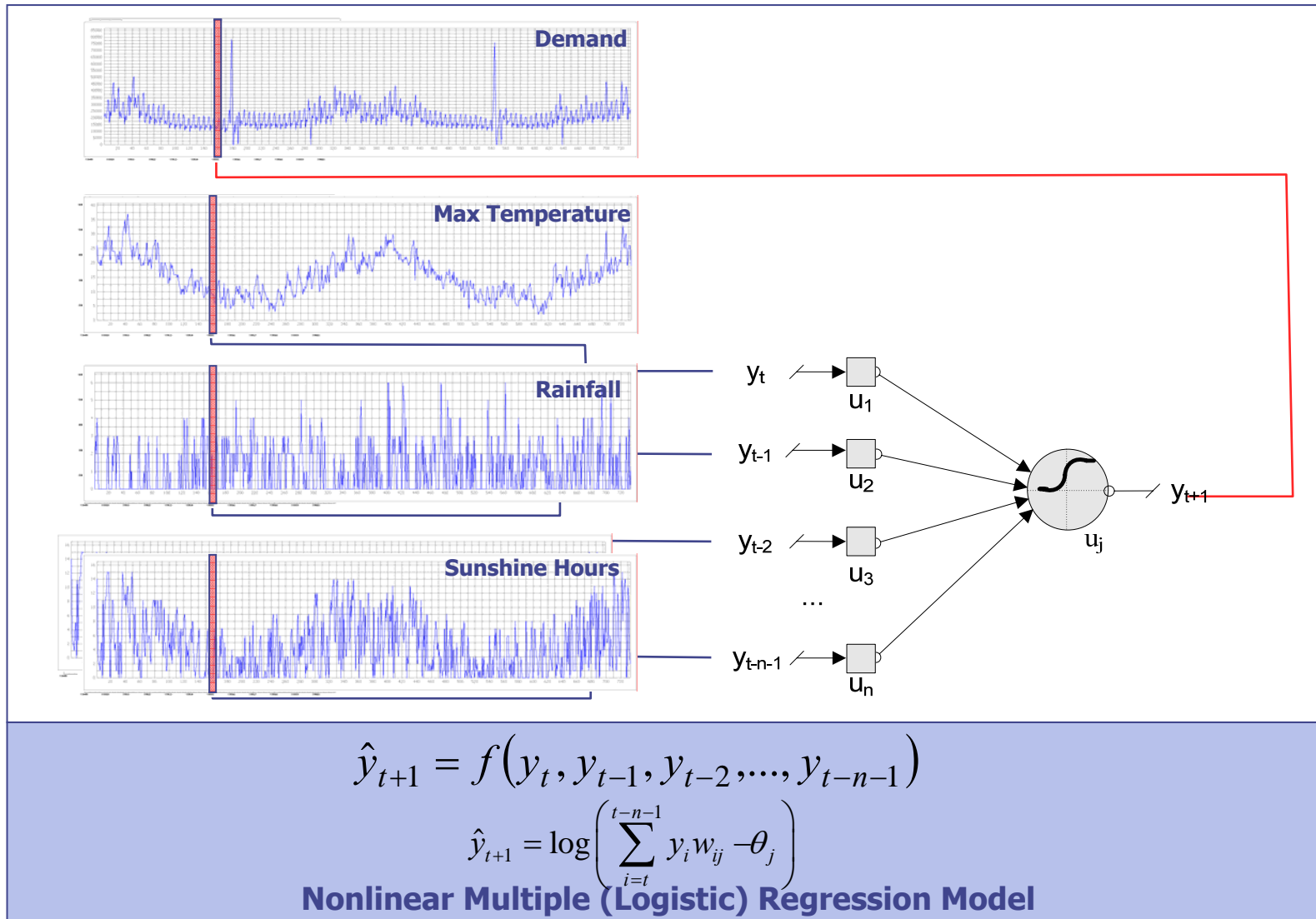
→ Extensions

- multiple output nodes = simultaneous multiple regression

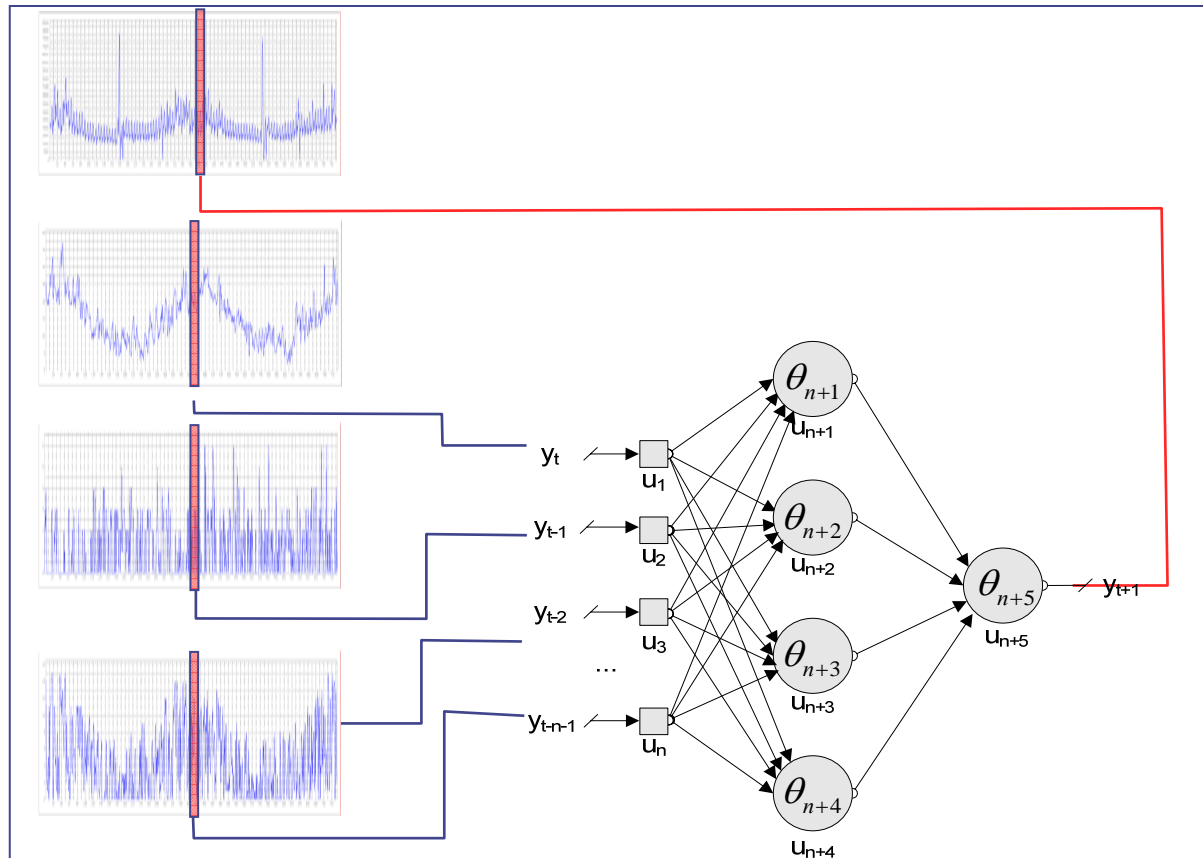
Neural Network Architecture for Linear Regression



Neural Network Architectures for Non-Linear Regression (\approx Logistic Regression)



Neural Network Architectures for Non-linear Regression



$$\hat{y} = f(x_1, x_2, x_3, \dots, x_n)$$

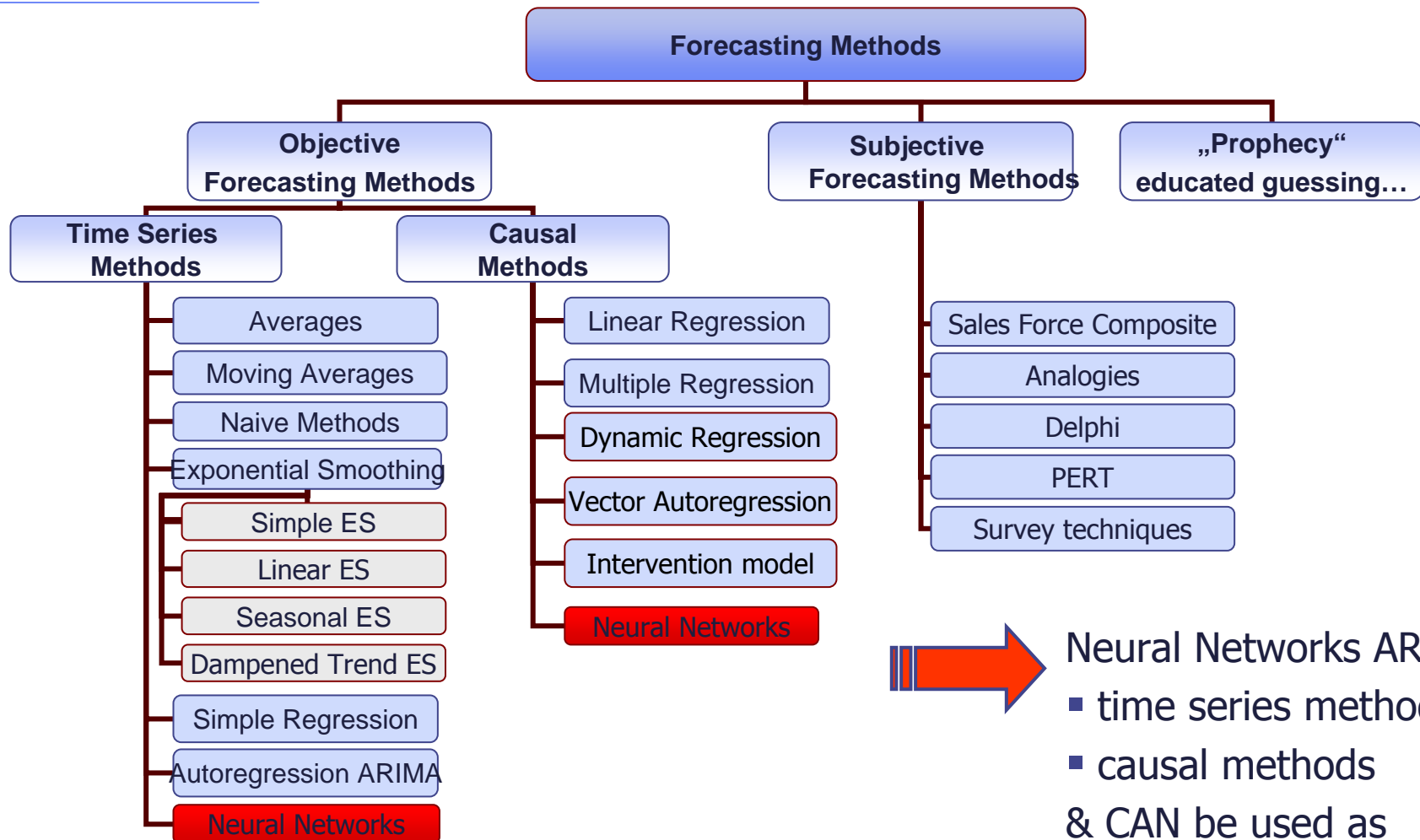
$$\hat{y} = x_1 w_{1j} + x_{2t} w_{2j} + x_{3t} w_{3j} + \dots + x_n w_{nj} - \theta_j$$

Nonlinear Regression Model

→ Interpretation

- Similar to linear Multiple Regression Modeling
- Without nonlinearity in output: weighted expert regime on non-linear regression
- With nonlinearity in output layer: ???

Classification of Forecasting Methods



Neural Networks ARE

- time series methods
- causal methods

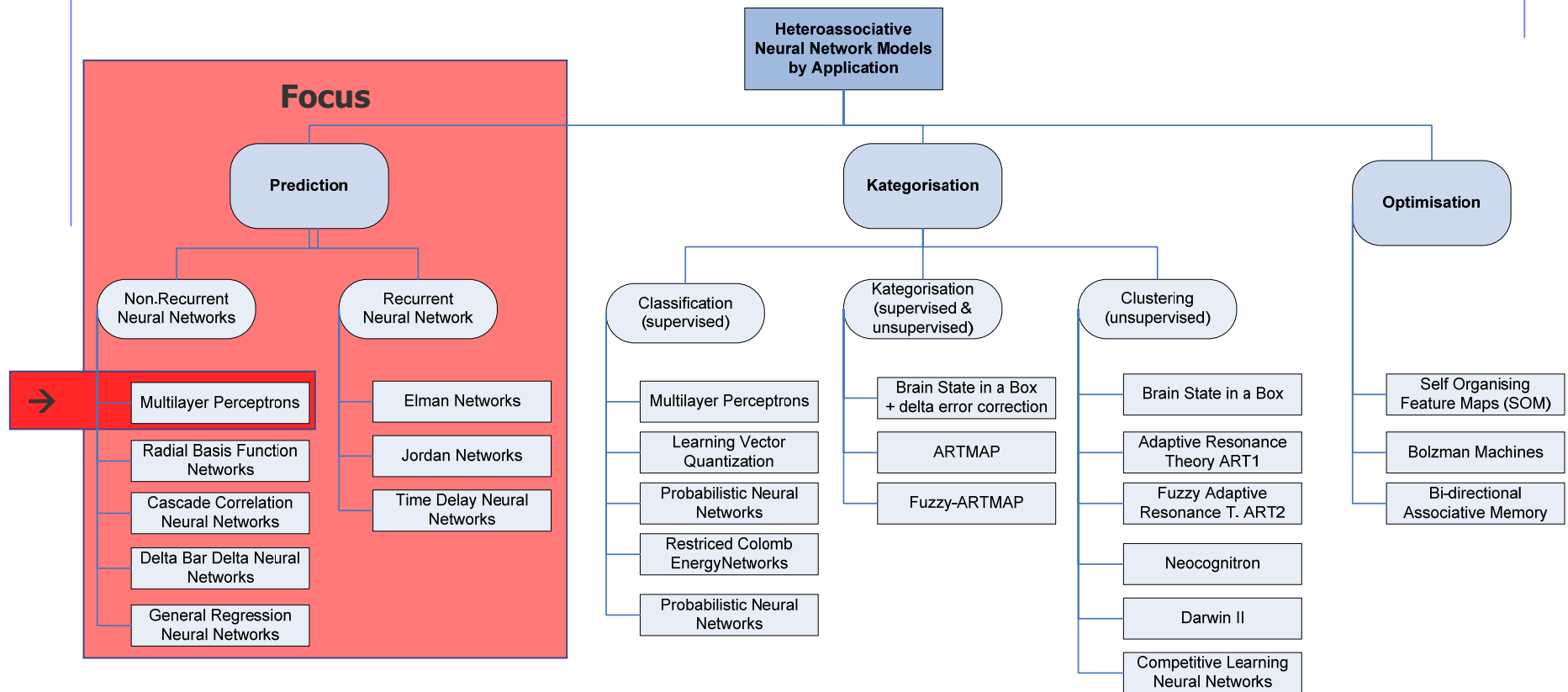
& CAN be used as

- Averages & ES
- Regression ...

Demand Planning Practice
Objektive Methoden + Subjektive correction

Different model classes of Neural Networks

- Since 1960s a variety of NN were developed for different tasks
 → Classification ≠ Optimization ≠ Forecasting → Application Specific Models



- Different CLASSES of Neural Networks for Forecasting alone!
 → Focus only on original Multilayer Perceptrons!

Problem!

- MLP most common NN architecture used
- MLPs with sliding window can ONLY capture nonlinear seasonal autoregressive processes $nSAR(p,P)$

- BUT:
 - Can model $MA(q)$ -process through extended $AR(p)$ window!
 - Can model $SARMAX$ -processes through recurrent NN

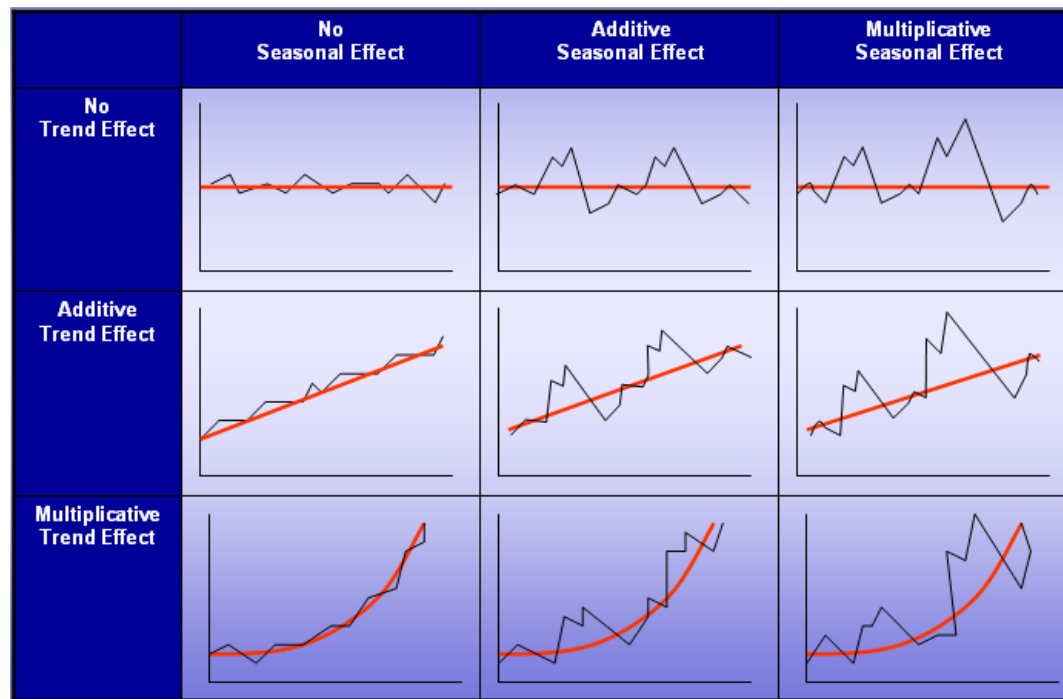
Agenda

Forecasting with Artificial Neural Networks

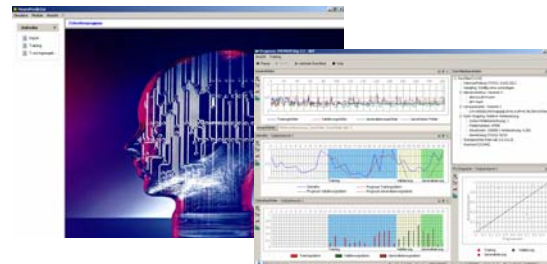
1. Forecasting?
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Time Series Prediction with Artificial Neural Networks

- Which time series patterns can ANNs learn & extrapolate?
[Pegels69/Gardner85]



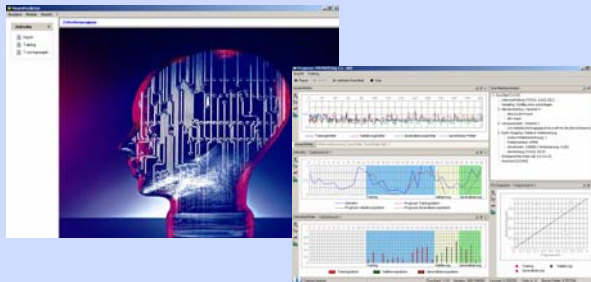
- ... ???



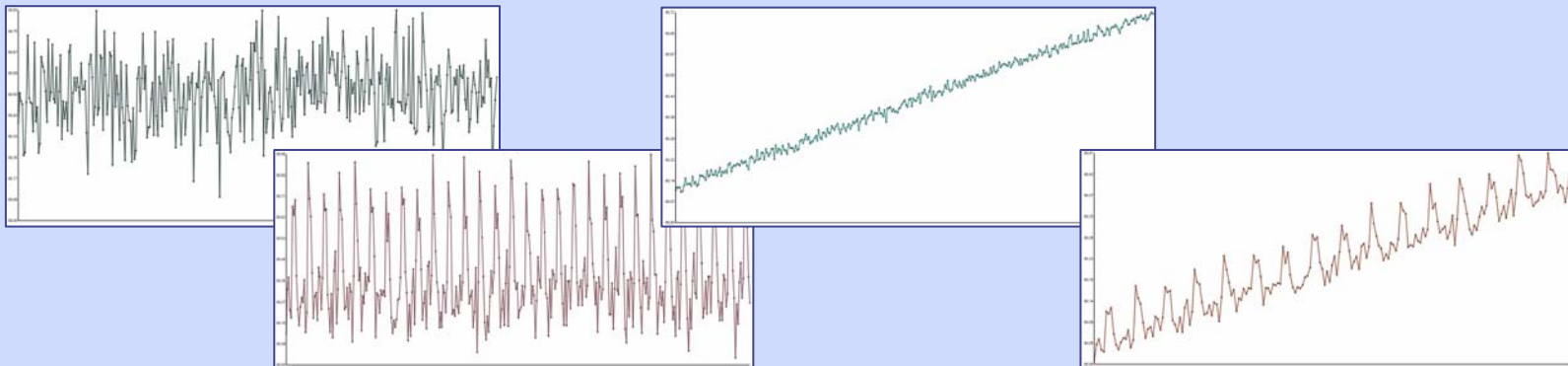
→ Simulation of
Neural Network prediction of
Artificial Time Series

Time Series Demonstration – Artificial Time Series

- Simulation of NN in Business Forecasting with NeuroPredictor

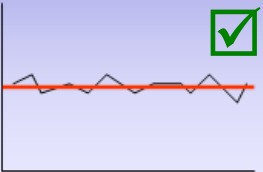
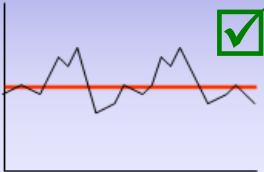
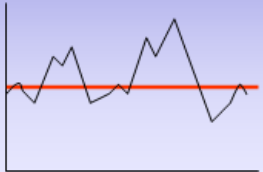

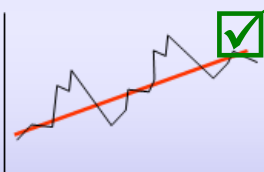
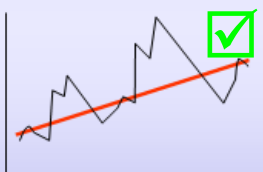
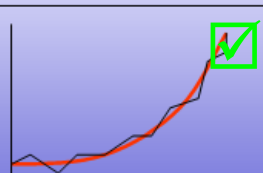
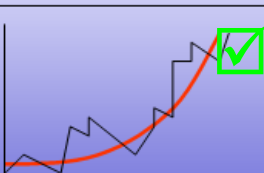
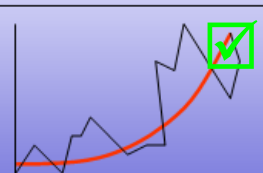


- Experiment: Prediction of Artificial Time Series (Gaussian noise)
 - Stationary Time Series
 - Seasonal Time Series
 - linear Trend Time Series
 - Trend with additive Seasonality Time Series



Time Series Prediction with Artificial Neural Networks

- Which time series patterns can ANNs learn & extrapolate?
[Pegels69/Gardner85]

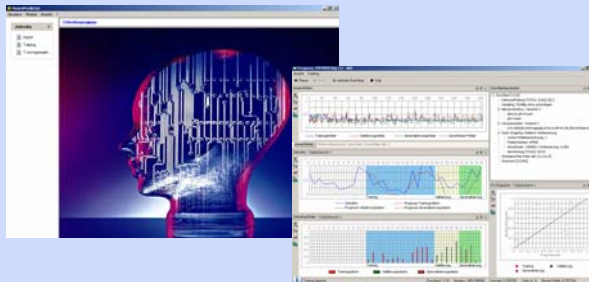
| | No Seasonal Effect | Additive Seasonal Effect | Multiplicative Seasonal Effect |
|-----------------------------|--|---|--|
| No Trend Effect |  |  |  |
| Additive Trend Effect |  |  |  |
| Multiplicative Trend Effect |  |  |  |

→ **Neural Networks can forecast ALL major time series patterns**

- NO time series dependent preprocessing / integration necessary
- NO time series dependent MODEL SELECTION required!!!
- **SINGLE MODEL APPROACH FEASIBLE!**

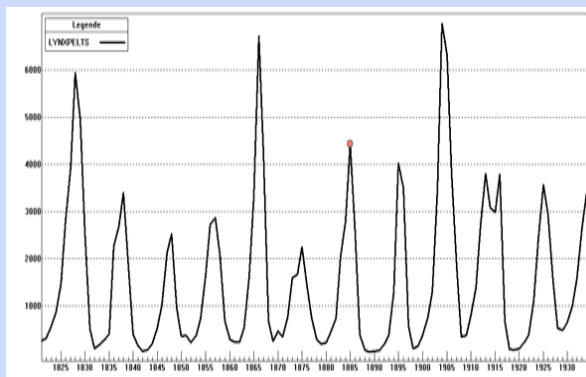
Time Series Demonstration A - Lynx Trappings

■ Simulation of NN in Business Forecasting



■ Experiment: Lynx Trappings at the McKenzie River

- 3 layered NN: (12-8-1) 12 Input units - 8 hidden units – 1 output unit
- Different lag structures: $t, t-1, \dots, t-11$ (past 12 observations)
- $t+1$ forecast \rightarrow single step ahead forecast

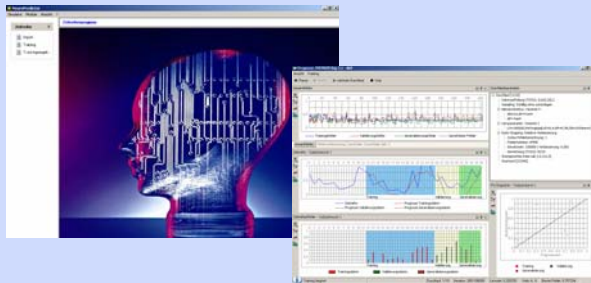


\rightarrow Benchmark Time Series
[Andrews / Hertzberg]

- **114 observations**
- **Periodicity? 8 years?**

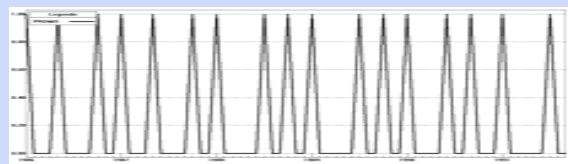
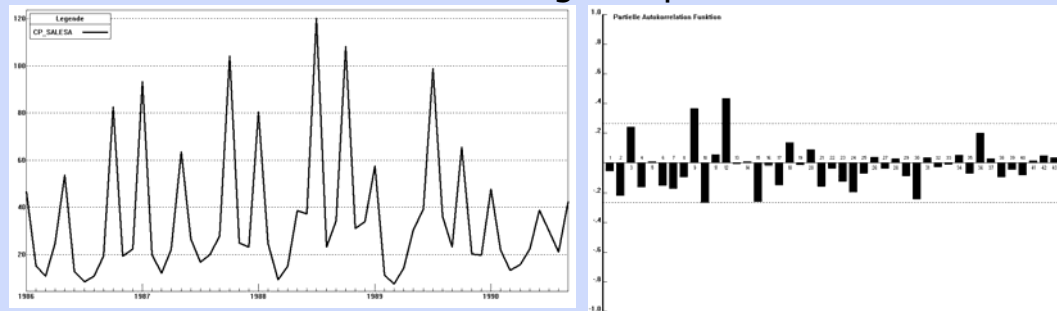
Time Series Demonstration B – Event Model

■ Simulation of NN in Business Forecasting



■ Experiment: Mouthwash Sales

- 3 layered NN: (12-8-1) 12 Input units - 8 hidden units – 1 output unit
- 12 input lags $t, t-1, \dots, t-11$ (past 12 observations) → time series prediction
- $t+1$ forecast → single step ahead forecast

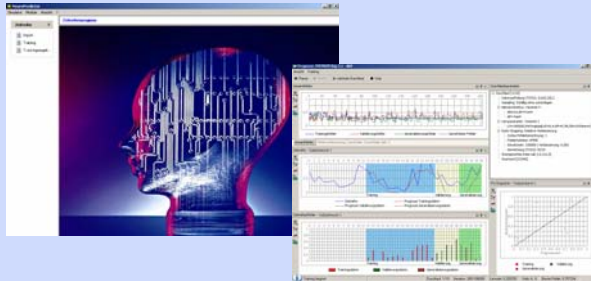


→ **Spurious Autocorrelations from Marketing Events**

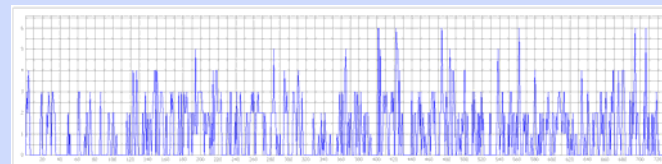
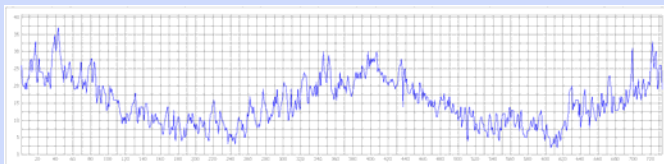
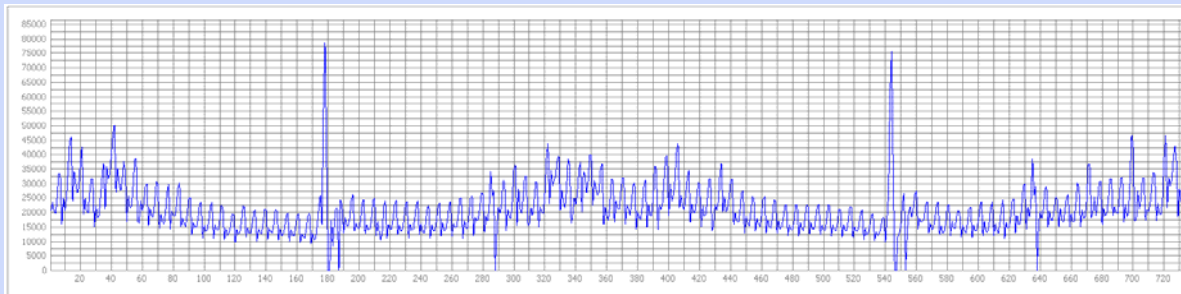
- **Advertisement with small Lift**
- **Price-reductions with high Lift**

Time Series Demonstration C – Supermarket Sales

- Simulation of NN in Business Forecasting



- Experiment: Supermarket sales of fresh products with weather
 - 4 layered NN: (7-4-4-1) 7 Input units - 8 hidden units – 1 output unit $t+4$
 - Different lag structures: $t, t-1, \dots, t-7$ (past 12 observations)
 - $t+4$ forecast \rightarrow single step ahead forecast



Agenda

Forecasting with Artificial Neural Networks


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 4. Evaluation
4. How to write a good Neural Network forecasting paper!

Decisions in Neural Network Modelling



NN Modelling Process

- Data Pre-processing
 - Transformation
 - Scaling
 - Normalizing to $[0;1]$ or $[-1;1]$
- Modelling of NN architecture
 - Number of INPUT nodes
 - Number of HIDDEN nodes
 - Number of HIDDEN LAYERS
 - Number of OUTPUT nodes
 - Information processing in Nodes (Act. Functions)
 - Interconnection of Nodes
- Training
 - Initializing of weights (how often?)
 - Training method (backprop, higher order ...)
 - Training parameters
 - Evaluation of best model (early stopping)
- Application of Neural Network Model
- Evaluation
 - Evaluation criteria & selected dataset



manual
Decisions require
Expert-Knowledge

Modeling Degrees of Freedom

- Variety of Parameters must be pre-determined for ANN Forecasting:

| | | | | | | |
|---------------------------------|--|---|--|--|---|-------------------------------|
| D= Dataset | [D ^{SE} Selection | D ^{SA} Sampling] | | | | |
| P= Preprocessing | [C Correction | N Normalization | S Scaling] | | | |
| A= Architecture | [N ^I no. of input nodes | N ^S no. of hidden nodes | N ^L no. of hidden layers | N ^O no. of output nodes | K connectivity / weight matrix | T Activation Strategy] |
| U= signal processing | [F ^I Input function | FA Activation Function | FO Output Function] | | | |
| L= learning algorithm | [G choice of Algorithm | PT,L Learning parameters phase & layer | I ^P initializations procedure | I ^N number of initializations | B stopping method & parameters] | |
| O objective Function | | | | | | |

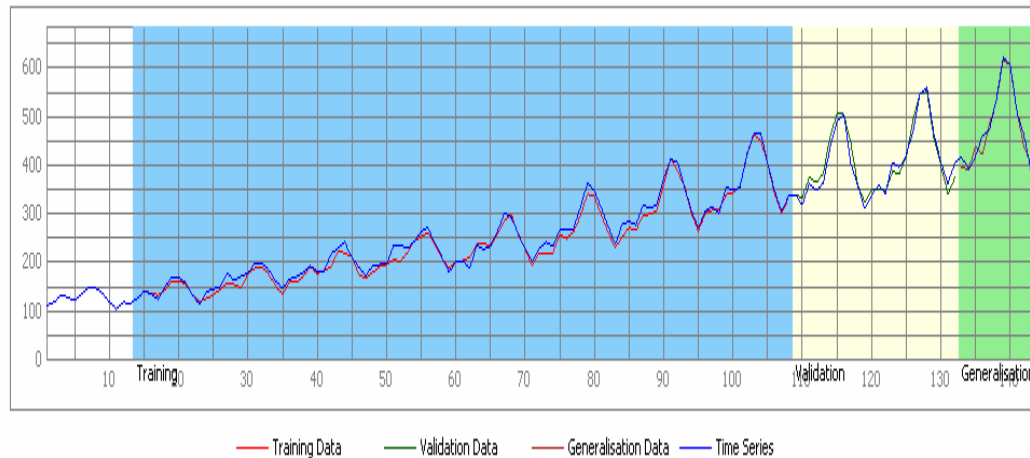
→ interactions & interdependencies between parameter choices!

Heuristics to Reduce Design Complexity

- Number of Hidden nodes in MLPs (in no. of input nodes n)
 - $2n+1$ [Lippmann87; Hecht-Nielsen90; Zhang/Pauwo/Hu98]
 - $2n$ [Wong91]; n [Tang/Fishwick93]; $n/2$ [Kang91]
 - $0.75n$ [Bailey90]; $1.5n$ to $3n$ [Kasstra/Boyd96] ...
 - Activation Function and preprocessing
 - logistic in hidden & output [Tang/Fischwick93; Lattermacher/Fuller95; Sharda/Patil92]
 - hyperbolic tangent in hidden & output [Zhang/Hutchinson93; DeGroot/Wurtz91]
 - linear output nodes [Lapedes/Faber87; Weigend89-91; Wong90]
 - ... with interdependencies!
-
- no research on relative performance of all alternatives
 - no empirical results to support preference of single heuristic
 - ADDITIONAL SELECTION PROBLEM of choosing a HEURISTIC
 - INCREASED COMPLEXITY through interactions of heuristics
 - AVOID selection problem through EXHAUSTIVE ENUMERATION

Tip & Tricks in Data Sampling

- Do's and Don'ts
 - Random order sampling? **Yes!**
 - Sampling with replacement? **depends / try!**
 - Data splitting: **ESSENTIAL!!!!**
 - Training & Validation for identification, parameterisation & selection
 - Testing for ex ante evaluation (ideally multiple ways / origins!)



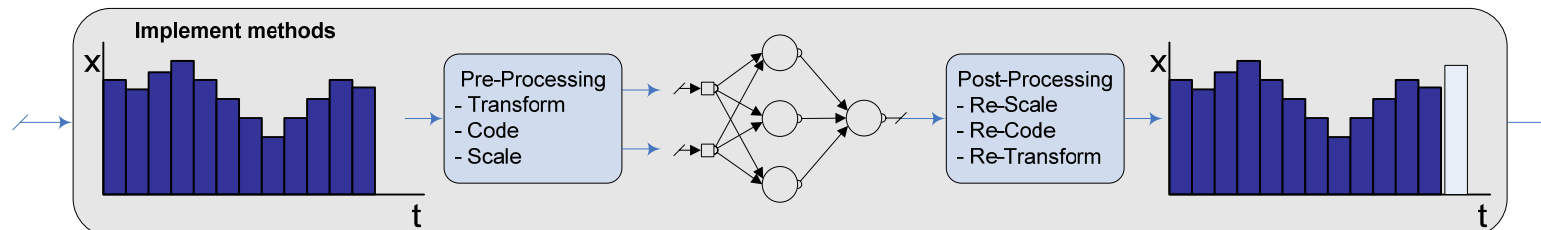
→ **Simulation Experiments**

Data Preprocessing

- Data Transformation
 - Verification, correction & editing (data entry errors etc.)
 - Coding of Variables
 - Scaling of Variables
 - Selection of independent Variables (PCA)
 - Outlier removal
 - Missing Value imputation

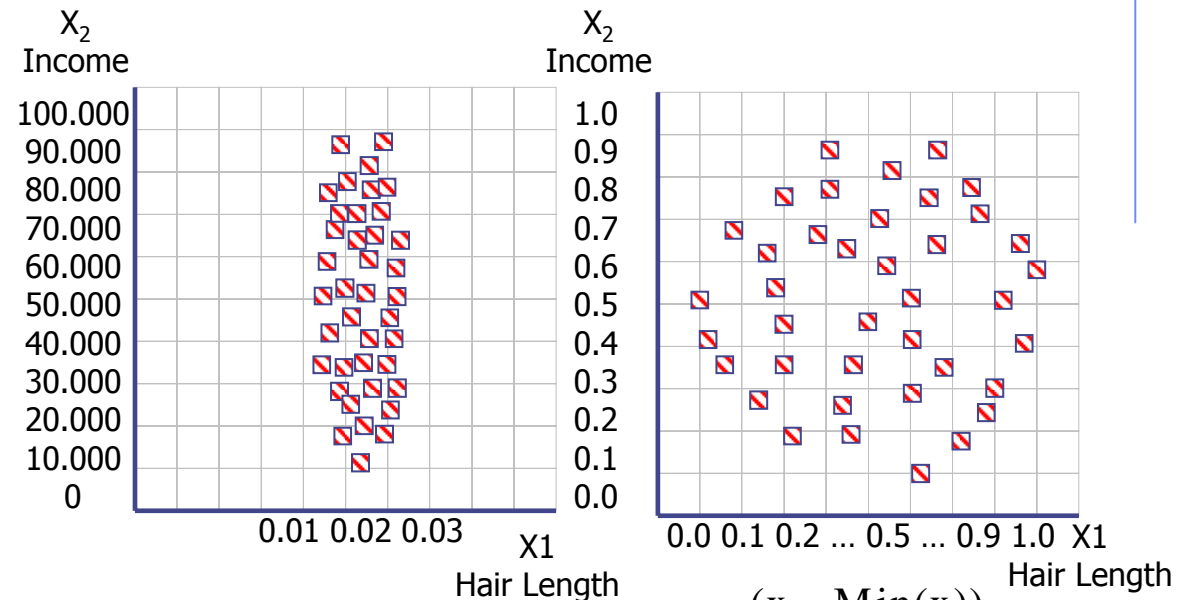
- Data Coding
 - Binary coding of external events → binary coding
 - n and n-1 coding have no significant impact, n-coding appears to be more robust (despite issues of multicollinearity)

→ Modification of Data to enhance accuracy & speed



Data Preprocessing – Variable Scaling

- Scaling of variables



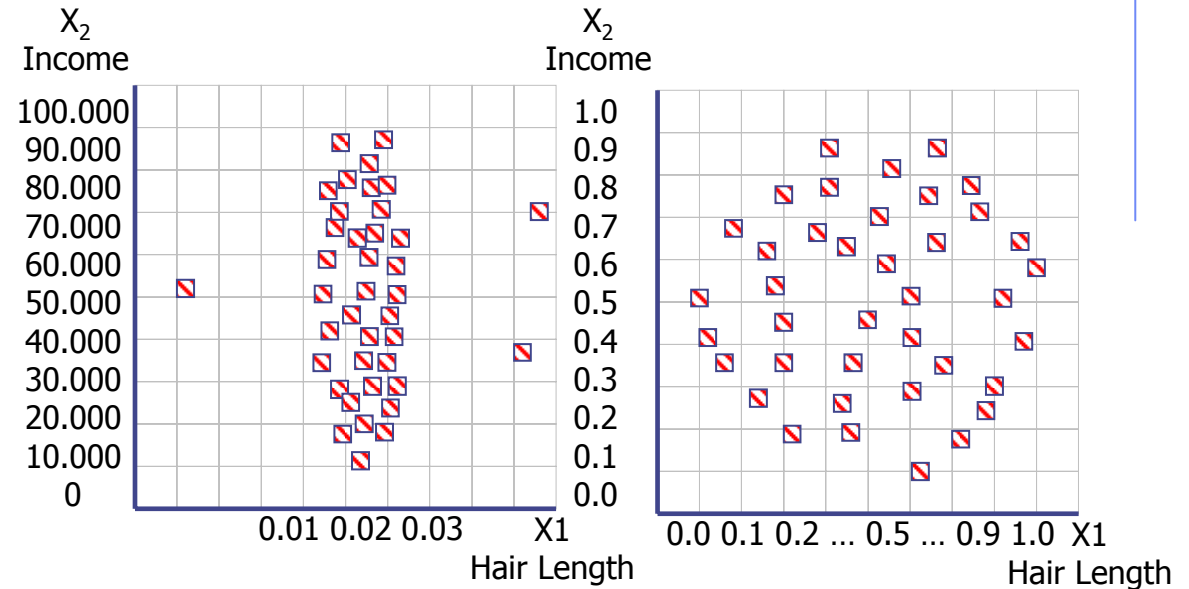
- Linear interval scaling $y = I_{\text{Lower}} + (I_{\text{Upper}} - I_{\text{Lower}}) \frac{(x - \text{Min}(x))}{\text{Max}(x) - \text{Min}(x)}$
- Intervall features, e.g. „turnover“ [28.12 ; 70; 32; 25.05 ; 10.17 ...]
Linear Intervall scaling to target intervall, e.g. [-1;1]

eg. $x = 72$ $\text{Max}(x) = 119.95$ $\text{Min}(x) = 0$ Target [-1;1]

$$y = -1 + (1 - (-1)) \frac{(72 - 0)}{119.95 - 0} = -1 + \frac{144}{119.95} = 0.2005$$

Data Preprocessing – Variable Scaling

- Scaling of variables



- Standardisation / Normalisation

$$y = \frac{x - \eta}{\sigma}$$

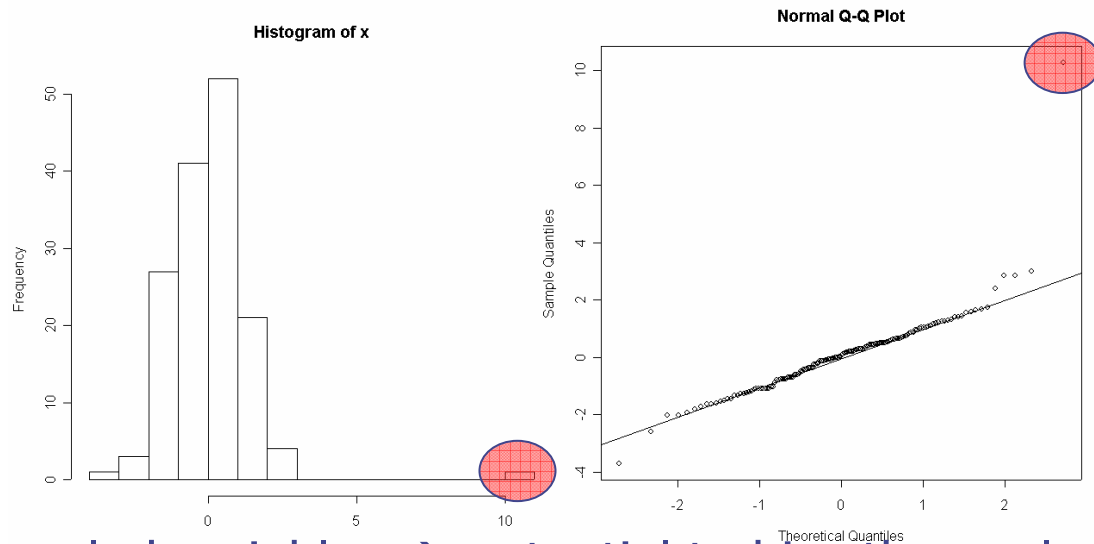
- Attention: Interaction of interval with activation Function

- Logistic [0;1]
 - TanH [-1;1]

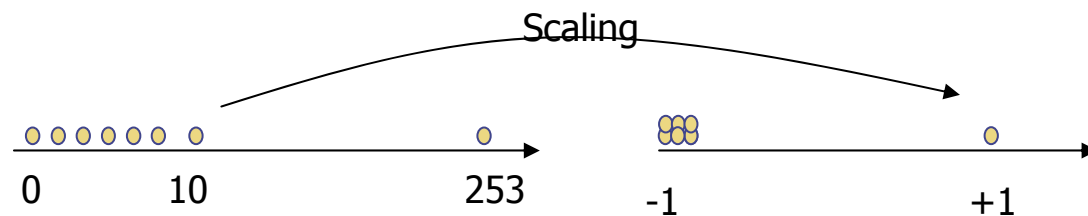
Data Preprocessing – Outliers

Outliers

- extreme values
- Coding errors
- Data errors



- Outlier impact on scaled variables → potential to bias the analysis
 - Impact on linear interval scaling (no normalisation / standardisation)

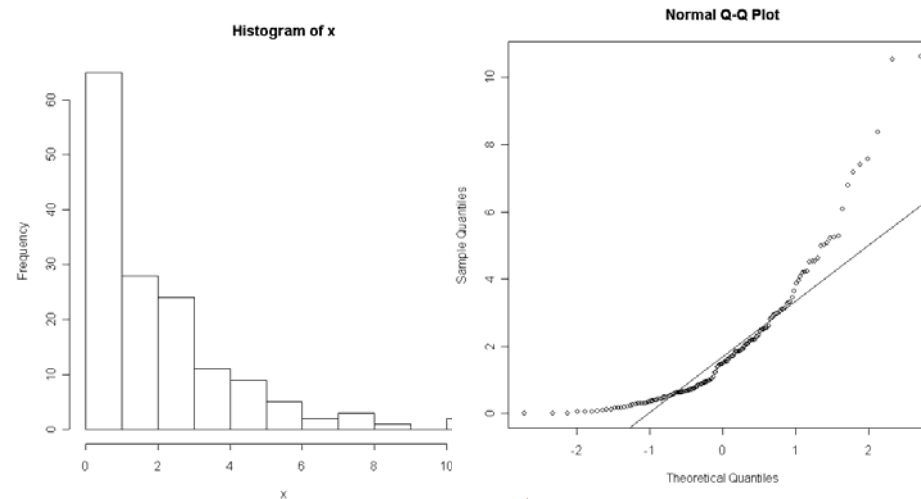


Actions

- Eliminate outliers (delete records)
- replace / impute values as missing values
- Binning of variable = rescaling
- Normalisation of variables = scaling

Data Preprocessing – Skewed Distributions

- Asymmetry of observations



- ...

→ Transform data

- Transformation of data (functional transformation of values)
- Linearization or Normalisation

→ Rescale (DOWNSCALE) data to allow better analysis by

- Binning of data (grouping of data into groups) → ordinal scale!

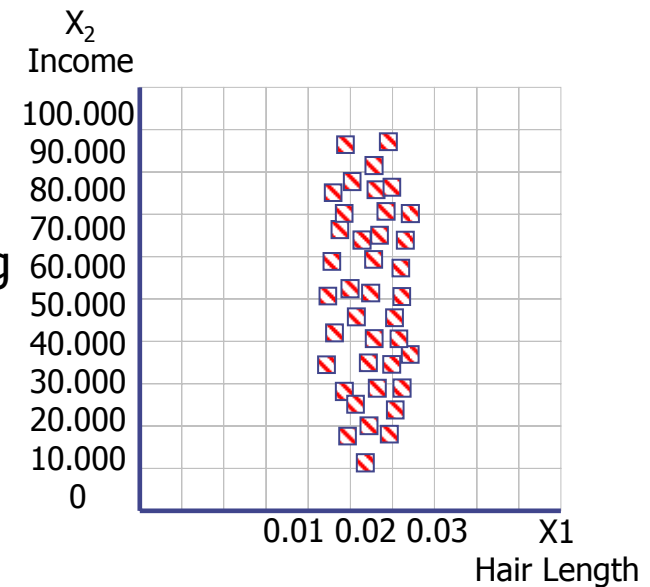
Data Preprocessing – Data Encoding

- Downscaling & Coding of variables
 - metric variables → create bins/buckets of ordinal variables (=BINNING)
 - Create buckets of equally spaced intervalls
 - Create bins if Quantile with equal frequencies
 - ordinal variable of n values
→ rescale to n or $n-1$ nominal binary variables
 - nominal Variable of n values, e.g. {Business, Sports & Fun, Woman}
→ Rescale to n or $n-1$ binary variables
 - 0 = Business Press
 - 1 = Sports & Fun
 - 2 = Woman
 - Recode as 1 of N Coding → 3 new bit-variables
 - 1 0 0 → Business Press
 - 0 1 0 → Sports & Fun
 - 0 0 1 → Woman
 - Recode 1 of N-1 Coding → 2 new bit-variables
 - 1 0 → Business Press
 - 0 1 → Sports & Fun
 - 0 0 → Woman

Data Preprocessing – Impute Missing Values

■ Missing Values

- missing feature value for instance
- some methods interpret "" as 0!
- Others create special class for missing
- ...



■ Solutions

- Missing value of interval scale → mean, median, etc.
- Missing value of nominal scale → most prominent value in feature set

Tip & Tricks in Data Pre-Processing

- Do's and Don'ts
 - De-Seasonalisation? **NO!** (maybe ... you can try!)
 - De-Trending / Integration? **NO** / depends / preprocessing!

 - Normalisation? **Not necessarily** → correct outliers!
 - Scaling Intervals $[0;1]$ or $[-1;1]$? **Both OK!**
 - Apply headroom in Scaling? **YES!**
 - Interaction between scaling & preprocessing? **limited**
 - ...



→ **Simulation Experiments**

Outlier correction in Neural Network Forecasts?

- Outlier correction? YES!

 - Neural networks are often characterized as
 - Fault tolerant and robust
 - Showing graceful degradation regarding errors
- Fault tolerance = outlier resistance in time series prediction?



→ **Simulation Experiments**

- Number of OUTPUT nodes
 - Given by problem domain!
- Number of HIDDEN LAYERS
 - 1 or 2 ... depends on Information Processing in nodes
 - Also depends on nonlinearity & continuity of time series
- Number of HIDDEN nodes
 - Trial & error ... sorry!

- Information processing in Nodes (Act. Functions)
 - Sig-Id
 - Sig-Sig (Bounded & additional nonlinear layer)
 - TanH-Id
 - TanH-TanH (Bounded & additional nonlinear layer)

- Interconnection of Nodes
 - ???

Tip & Tricks in Architecture Modelling

- Do's and Don'ts
 - Number of input nodes? **DEPENDS!** → use linear ACF/PACF to start!
 - Number of hidden nodes? **DEPENDS!** → evaluate each time (few)
 - Number of output nodes? **DEPENDS** on application!

 - fully or sparsely connected networks? ???
 - shortcut connections? ???

 - activation functions → logistic or hyperbolic tangent? **TanH !!!**
 - activation function in the output layer? **TanH or Identity!**
 - ...



→ **Simulation Experiments**

Agenda

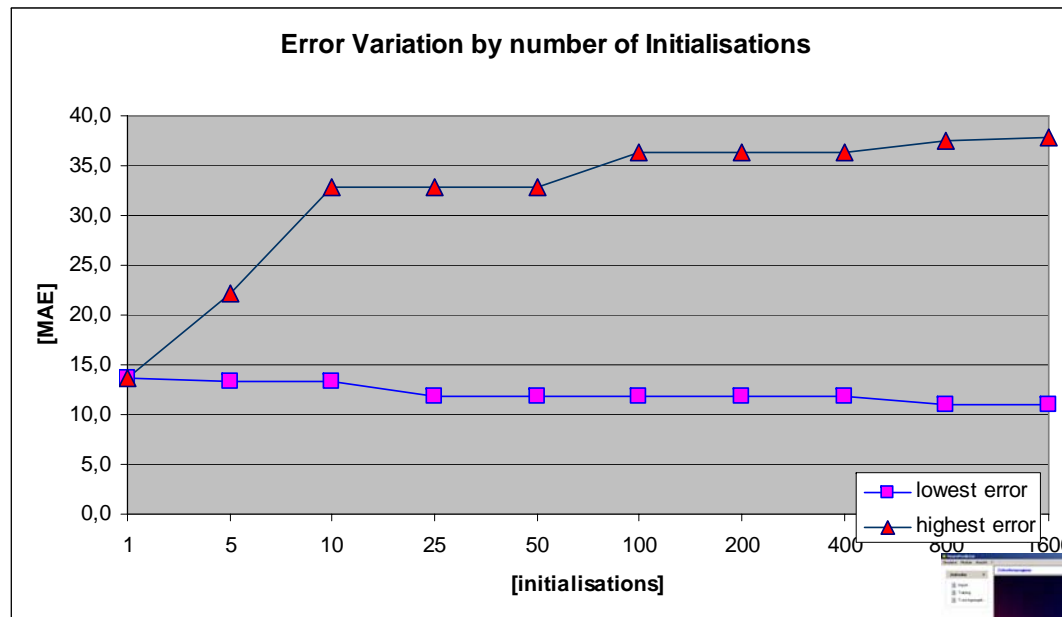
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Tip & Tricks in Network Training

- Do's and Don'ts

- Initialisations? A MUST! Minimum 5-10 times!!!



→ **Simulation Experiments**

Tip & Tricks in Network Training & Selection

- Do's and Don'ts
 - Initialisations? **A MUST!** Minimum 5-10 times!!!
 - Selection of Training Algorithm? Backprop OK, DBD OK ...
... not higher order methods!
 - Parameterisation of Training Algorithm? **DEPENDS** on dataset!
 - Use of early stopping? **YES** – carefull with stopping criteria!
 - ...

 - Suitable Backpropagation training parameters (to start with)
 - Learning rate 0.5 (always <1!)
 - Momentum 0.4
 - Decrease learning rate by 99%

 - Early stopping on composite error of Training & Validation



→ **Simulation Experiments**

Agenda

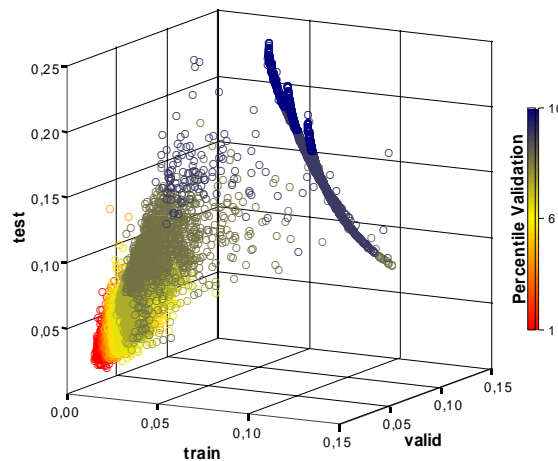
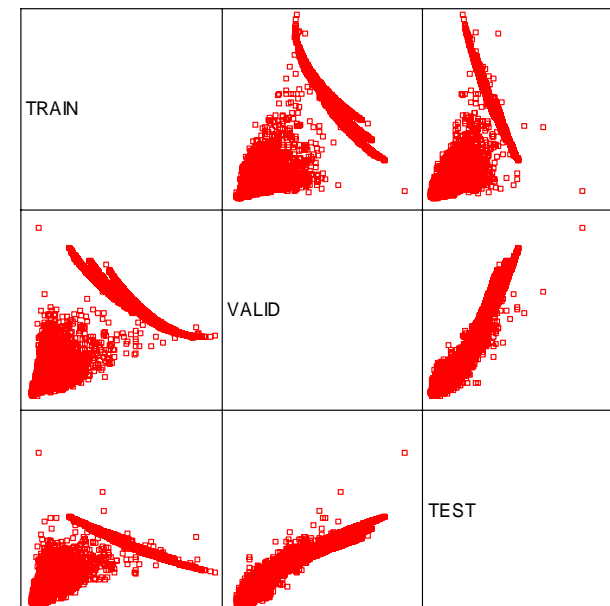
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Experimental Results

- Experiments ranked by validation error

| Rank by valid-error | Data Set Errors | | | ANN ID |
|---------------------|-----------------|------------|----------|------------|
| | Training | Validation | Test | |
| overall lowest | 0,009207 | 0,011455 | 0,017760 | |
| overall highest | 0,155513 | 0,146016 | 0,398628 | |
| 1 st | 0,010850 | 0,011455 | 0,043413 | 39 (3579) |
| 2 nd | 0,009732 | 0,012093 | 0,023367 | 10 (5873) |
| ... | ... | ... | ... | ... |
| 25 th | 0,009632 | 0,013650 | 0,025886 | 8 (919) |
| ... | ... | ... | ... | ... |
| 14400 th | 0,014504 | 0,146016 | 0,398628 | 33 (12226) |



→ significant positive correlations

- training & validation set
 - validation & test set
 - training & test set
- inconsistent errors by selection criteria
- low validation error → high test error
 - higher validation error → lower test error

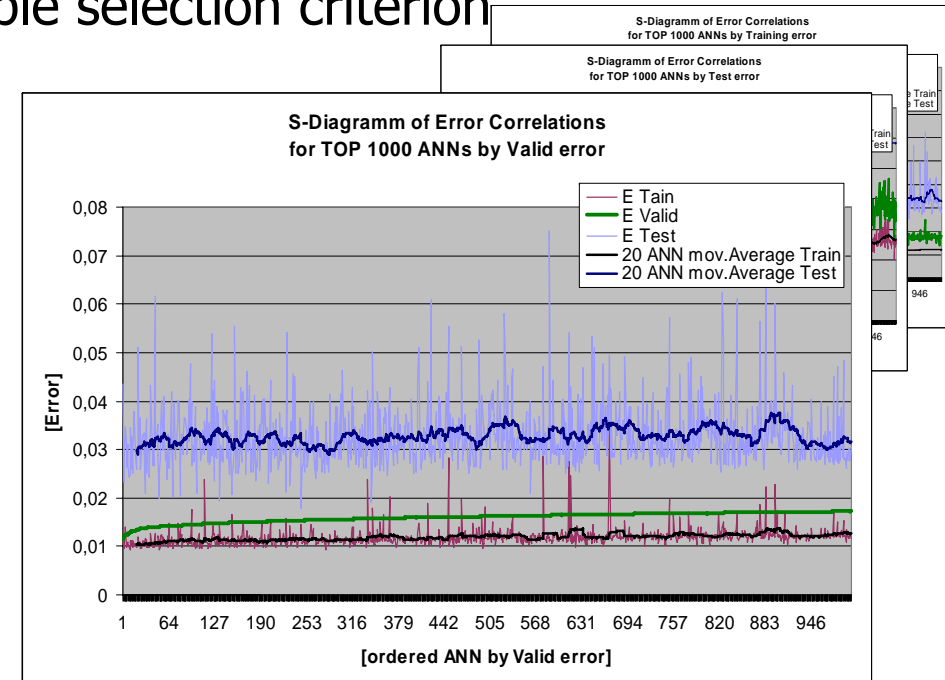
Problem: Validation Error Correlations

■ Correlations between dataset errors

| Data included | Correlation between datasets | | |
|---------------|------------------------------|-----------------|--------------|
| | Train - Validate | Validate - Test | Train - Test |
| 14400 ANNs | 0,7786** | 0,9750** | 0,7686** |
| top 1000 ANNs | 0,2652** | 0,0917** | 0,4204** |
| top 100 ANNs | 0,2067** | 0,1276** | 0,4004** |

→ validation error is questionable selection criterion

- decreasing correlation
- high variance on test error
- same results ordered by training & test error



- ***Desirable properties of an Error Measure:***
 - summarizes the cost consequences of the errors
 - Robust to outliers
 - Unaffected by units of measurement
 - Stable if only a few data points are used

Fildes, IJF, 92, Armstrong and Collopy, IJF, 92;
Hendry and Clements, Armstrong and Fildes, JOF, 93,94

Model Evaluation through Error Measures

- forecasting k periods ahead we can assess the forecast quality using a holdout sample

- Individual forecast error

- e_{t+k} = Actual - Forecast

$$e_t = y_t - F_t$$

- Mean error (ME)

- Add individual forecast errors
- As positive errors cancel out negative errors, the ME should be approximately zero for an unbiased series of forecast

$$ME_t = \frac{1}{n} \sum_{k=1}^n Y_{t+k} - F_{t+k}$$

- Mean squared error (MSE)

- Square the individual forecast errors
- Sum the squared errors and divide by n

$$MSE_t = \frac{1}{n} \sum_{k=1}^n (Y_{t+k} - F_{t+k})^2$$

Model Evaluation through Error Measures

→ avoid cancellation of positive v negative errors: absolute errors

- Mean absolute error (MAE)

- Take absolute values of forecast errors
- Sum absolute values and divide by n

$$MAE = \frac{1}{n} \sum_{k=1}^n |Y_{t+k} - F_{t+k}|$$

- Mean absolute percent error (MAPE)

- Take absolute values of percent errors
- Sum percent errors and divide by n

$$MAPE = \frac{1}{n} \sum_{k=1}^n \left| \frac{Y_{t+k} - F_{t+k}}{Y_{t+k}} \right|$$

→ This summarises the forecast error over different lead-times

→ May need to keep k fixed depending on the decision to be made based on the forecast:

$$MAE(k) = \frac{1}{(n-k+1)} \sum_{t=T}^{T+n-k} |Y_{t+k} - F_t(k)| \quad MAPE(k) = \frac{1}{(n-k+1)} \sum_{t=T}^{T+n-k} \left| \frac{Y_{t+k} - F_t(k)}{Y_{t+k}} \right|$$

Selecting Forecasting Error Measures

- *MAPE* & *MSE* are subject to upward bias by single bad forecast
- Alternative measures may be based on median instead of mean
- Median Absolute Percentage Error
 - median = middle value of a set of errors *sorted in ascending order*
 - If the *sorted* data set has an even number of elements, the median is the average of the two middle values

$$MdAPE_f = \text{Med} \left(\left| \frac{e_{f,t}}{y_t} \right| \times 100 \right)$$

- Median Squared Error

$$MdSE_f = \text{Med}(e_{f,t}^2)$$

Evaluation of Forecasting Methods

- The *Base Line* model in a forecasting competition is the Naïve 1a **No Change** model → use as a benchmark

$$\hat{y}_{t+f|t} = y_t$$

- Theil's U statistic allows us to determine whether our forecasts outperform this base line, with increased accuracy through our method (outperforms naïve) if $U < 1$

$$U = \sqrt{\frac{\sum \left(\frac{(\hat{y}_{t+f|t} - y_{t+f})}{y_t} \right)^2}{\sum \left(\frac{(y_t - y_{t+f})}{y_t} \right)^2}}$$

Tip & Tricks in Network Selection

- Do's and Don'ts
 - Selection of Model with lowest Validation error? **NOT VALID!**
 - Model & forecasting competition? **Always multiple origin etc.!**
 - ...



→ **Simulation Experiments**

Agenda

Forecasting with Artificial Neural Networks

1. Forecasting?
2. Neural Networks?
3. Forecasting with Neural Networks ...
 1. NN models for Time Series & Dynamic Causal Prediction
 2. NN experiments
 3. Process of NN modelling
4. How to write a good Neural Network forecasting paper!

How to evaluate NN performance

Valid Experiments

- Evaluate using ex ante accuracy (HOLD-OUT data)
 - Use training & validation set for training & model selection
 - NEVER!!! Use test data except for final evaluation of accuracy
- Evaluate across multiple time series
- Evaluate against benchmark methods (NAÏVE + domain!)
- Evaluate using multiple & robust error measures (not MSE!)
- Evaluate using multiple out-of-samples (time series origins)
- Evaluate as Empirical Forecasting Competition!

Reliable Results

- Document all parameter choices
- Document all relevant modelling decisions in process
- Rigorous documentation to allow re-simulation through others!

Evaluation through Forecasting Competition

- Forecasting Competition
 - Split up time series data → 2 sets PLUS multiple ORIGINS!
 - Select forecasting model
 - select best parameters for IN-SAMPLE DATA
 - Forecast next values for DIFFERENT HORIZONS $t+1$, $t+3$, $t+18$?
 - Evaluate error on hold out OUT-OF-SAMPLE DATA
 - choose model with lowest AVERAGE error OUT-OF-SAMPLE DATA

- Results → M3-competition
 - simple methods outperform complex one
 - exponential smoothing OK
 - neural networks not necessary
 - forecasting VALUE depends on VALUE of INVENTORY DECISION



Evaluation of Forecasting Methods

- HOLD-OUT DATA → out of sample errors count!

... 2003 "today" ... today presumed Future ... Future ...

| Method | Jan | Feb | Mar | Apr | Mai | Jun | Jul | Aug | Sum | Sum |
|----------------------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| Baseline Sales | 90 | 100 | 110 | ? | ? | ? | ? | ? | | |
| Method A | 90 | 90 | 90 | 90 | 90 | 90 | 90 | 90 | | |
| Method B | 110 | 100 | 120 | 100 | 110 | 100 | 110 | 100 | | |
| absolute error AE(A) | 0 | 10 | 20 | ? | ? | ? | ? | ? | 30 | ? |
| absolute error AE(B) | 20 | 0 | 10 | ? | ? | ? | ? | ? | 10 | ? |

↑ ↑ ↑ ...
t+1 t+2 t+3

↑ ↑ ↑ ...
t+1 t+2 t+3

SIMULATED = EX POST Forecasts

Evaluation of Forecasting Methods

- Different Forecasting horizons, emulate rolling forecast ...

... 2003 "today" | presumed Future ...

| Method | Jan | Feb | Mar | Apr | Mai | Jun | Jul | Aug | Sum | Sum |
|----------------------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| Baseline Sales | 90 | 100 | 110 | 100 | 90 | 100 | 110 | 100 | | |
| Method A | 90 | 90 | 90 | 90 | 90 | 90 | 90 | 90 | | |
| Method B | 110 | 100 | 120 | 100 | 110 | 100 | 110 | 100 | | |
| absolute error AE(A) | 0 | 10 | 20 | 10 | 0 | 10 | 20 | 10 | 30 | 50 |
| absolute error AE(B) | 20 | 0 | 10 | 0 | 20 | 0 | 0 | 0 | 30 | 20 |

$t+1$ $t+2$ $t+3$...
 $t+1$ $t+2$...

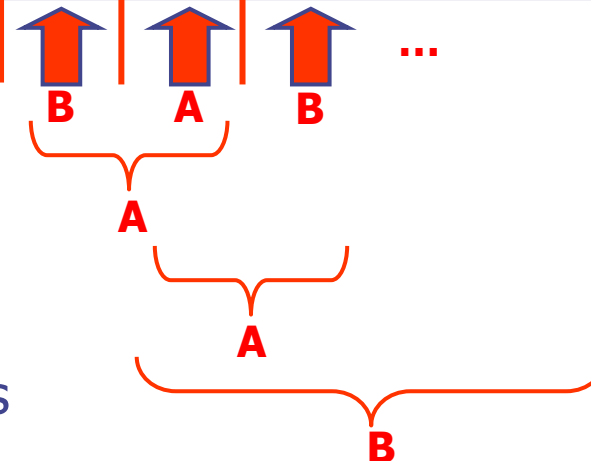
- Evaluate only RELEVANT horizons
 - omit $t+2$ if irrelevant for planning!

Evaluation of Forecasting Methods

- Single vs. Multiple origin evaluation

... 2003 "today" | presumed Future ...

| Method | Jan | Feb | Mar | Apr | Mai | Jun | Jul | Aug | Sum | Sum |
|----------------------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| Baseline Sales | 90 | 100 | 110 | 100 | 90 | 100 | 110 | 100 | | |
| Method A | 90 | 90 | 90 | 90 | 90 | 90 | 90 | 90 | | |
| Method B | 110 | 100 | 120 | 100 | 110 | 100 | 110 | 100 | | |
| absolute error AE(A) | 0 | 10 | 20 | 10 | 0 | 10 | 20 | 10 | 30 | 50 |
| absolute error AE(B) | 20 | 0 | 10 | 0 | 20 | 0 | 0 | 0 | 30 | 20 |



- Problem of sampling Variability!
 - Evaluate on multiple origins
 - Calculate $t+1$ error
 - Calculate average of $t+1$ error
- GENERALIZE about forecast errors

Software Simulators for Neural Networks

Commercial Software by Price

- High End
 - Neural Works Professional
 - SPSS Clementine
 - SAS Enterprise Miner
- Midprice
 - Alyuda NeuroSolutions
 - NeuroShell Predictor
 - NeuroSolutions
 - NeuralPower
 - PredictorPro
- Research
 - Mathlab Library
 - R-package
 - NeuroLab
- ...

Public Domain Software







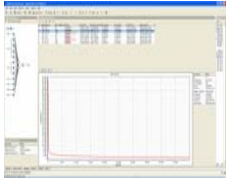

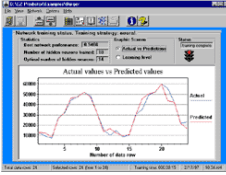

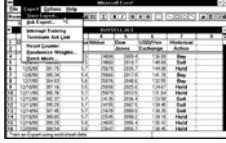
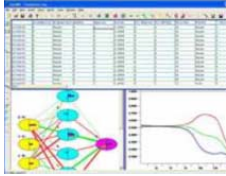

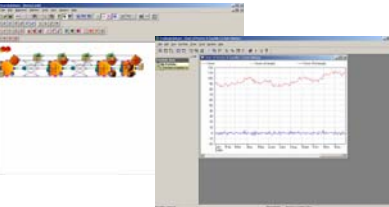
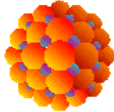

- Research oriented
 - SNNS
 - JNNS JavaSNNS
 - JOONE
 - ...

→ **FREE** CD-ROM for evaluation


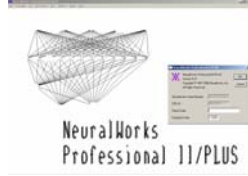


- Data from Experiments
 - M3-competition
 - airline-data
 - lynx-data
 - beer-data
- Software Simulators

→ Consider Tashman/Hoover Tables on forecasting Software for more details

Neural Networks Software - Times Series friendly!

| | | |
|--|---|---|
| <p>Alyuda Inc.</p>  |      |  |
| <p>Ward Systems</p>  <p>"Let your systems learn the wisdom of age and experience"</p> | <p>AITrilogy: NeuroShell Predictor, NeuroShell Classifier, GeneHunter NeuroShell 2, NeuroShell Trader, Pro,DayTrader</p> |  |
| <p>Attrasoft Inc.</p> | <p>Predictor Predictor PRO</p> |  |
| <p>Promised Land PROMISED LAND TECHNOLOGIES, INC.</p> | <p>Braincell</p> |  |
| <p>Neural Planner Inc.</p> | <p>Easy NN Easy NN Plus</p> |  |
| <p>NeuroDimension</p>  | <p>NeuroSolutions Cosconsultant Neurosolutions for Excel NeuroSolutions for Matlab Trading Solutions</p> |    |

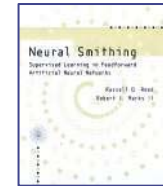
Neural networks Software – General Applications

| | | |
|---|-----------------------------------|---|
| Neuralware Inc  | Neural Works Professional II Plus |  |
| SPSS  | SPSS Clementine DataMining Suite | |
| SAS  | SAS Enterprise Miner | |
| ... | ... | |

Further Information

■ Literature & websites

- NN Forecasting website www.neural-forecasting.com or www.bis-lab.com
- Google web-resources, SAS NN newsgroup FAQ
<ftp://ftp.sas.com/pub/neural/FAQ.html>
- BUY A BOOK!!! Only one? Get: Reeds & Marks 'Neural Smithing'



■ Journals

- Forecasting ... rather than technical Neural Networks literature!
 - JBF – Journal of Business Forecasting
 - IJF – International Journal of Forecasting
 - JoF – Journal of Forecasting



■ Contact to Practitioners & Researchers

- Associations
 - IEEE NNS – IEEE Neural Network Society
 - INNS & ENNS – International & European Neural Network Society
- Conferences
 - Neural Nets: IJCNN, ICANN & ICONIP by associations (search google ...)
 - Forecasting: IBF & ISF conferences!
- Newsgroups news.comp.ai.nn
- Call Experts you know ... me ;-)



Agenda

Business Forecasting with Artificial Neural Networks

1. Process of NN Modelling
2. Tips & Tricks for Improving Neural Networks based forecasts
 - a. Copper Price Forecasting
 - b. Questions & Answers and Discussion
 - a. Advantages & Disadvantages of Neural Networks
 - b. Discussion

Advantages ... versus Disadvantages!

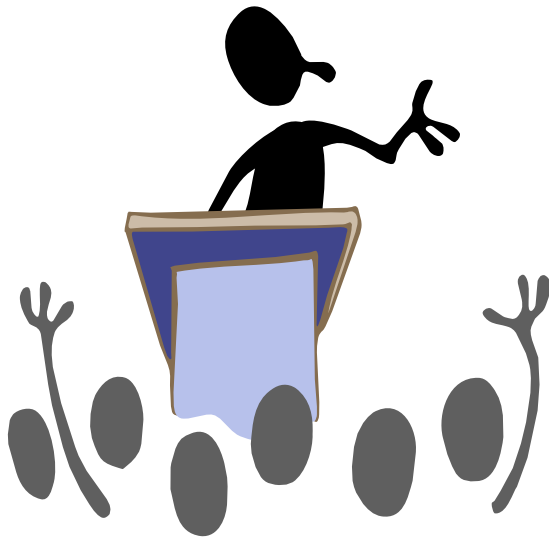
Advantages

- ANN can forecast any time series pattern ($t+1!$)
 - without preprocessing
 - no model selection needed!
- ANN offer many degrees of freedom in modeling
 - Freedom in forecasting with one single model
 - Complete Model Repository
 - linear models
 - nonlinear models
 - Autoregression models
 - single & multiple regres.
 - Multiple step ahead
 - ...

Disadvantages

- ANN can forecast any time series pattern ($t+1!$)
 - without preprocessing
 - no model selection needed!
- ANN offer many degrees of freedom in modeling
 - Experience essential!
 - Research not consistent
- explanation & interpretation of ANN weights IMPOSSIBLE (nonlinear combination!)
 - impact of events not directly deductible

Questions, Answers & Comments?



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SLIDES & PAPERS available:
www.bis-lab.de

www.lums.lancs.ac.uk

Summary Day I

- ANN can forecast any time series pattern ($t+1!$)
 - without preprocessing
 - no model selection needed!
- ANN offer many degrees of freedom in modeling
 - Experience essential!
 - Research not consistent

What we can offer you:

- NN research projects with complimentary support!
- Support through MBA master thesis in mutual projects

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